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SOUND PROPAGATION THROUGH A TURBULENT ATMOSPHERE: EXPERIMENTAL TECHNIQUES AND DATA ANALYSIS

Final Report

Henry E. Bass, Lee N. Bolen, and John Noble



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PARGUM Report #87-02





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SOUND PROPAGATION THROUGH A TURBULENT ATMOSPHERE: EXPERIMENTAL TECHNIQUES AND DATA ANALYSIS

Final Report

Henry E. Bass, Lee N. Bolen, and John Noble
PARGUM Report #87-02

Abstract

This is the first of a series of reports on a three year study of sound propagation through a turbulent atmosphere. This report documents the experimental configuration and describes data analysis. The data analysis includes plots of the real and imaginary parts of the acoustic pressure as a function of time (scatter plots), probability of observing a particular amplitude, and the more familiar structure functions.

A preliminary analysis of data suggest reasonable agreement in structure functions at frequencies of 500 Hz and above. At lower frequencies, phase and log amplitude structure functions are both larger than predicted from theory. A tentative explanation for this difference is under development and will be presented in the third of the three volume series. The second volume will be devoted to refractive effects.

Sound Propagation Through a Turbulent Atmosphere: Experimental Techniques and Data Analysis

I. Introduction

The propagation of sound waves close to the ground is a complex problem involving many interesting mechanisms. In addition to geometrical spreading and molecular absorption, which are reasonably well understood, the three main mechanisms which influence the acoustic field are reflection with phase change due to the finite impedance of the ground, refraction by wind and temperature gradients, and scattering by atmospheric turbulence. Outdoor sound propagation in a turbulent medium is not a well understood process and has only recently begun to receive serious attention. This report will present experimental data taken under several different meteorological conditions including various degrees of turbulence and different geometrical configurations. This report also contains the results of a preliminary analysis of the data.

The first section will describe the experimental configuration of the experiments which were undertaken over a period of two years. A complete set of geometrical configurations will be presented along with the analysis procedure for processing the acoustical data. A unique technique for examining the fluctuations in acoustic amplitude is described in this section. This analysis was completed for each microphone in the array over a range of frequencies starting at 62.5 Hz and going up to 8000 Hz. The next section describes the meteorological information that is available for the experiments. Temperature and wind velocity vary strongly with height within the first few meters above the ground. Because of this, the wind speed, wind direction, and temperature measurements are given as a function of height. Sound speed profiles have been computed for each of the runs where weather information is available. The third section deals with extracting sound pressure levels from the analyses described in Section II.

The fourth item discussed will be the form of the complex amplitude of the sound wave as it propagates through a turbulent medium. As an acoustic wave propagates a distance r through the atmosphere from a point source S to a receiver R, atmospheric turbulence causes fluctuations in

the acoustical refractive index, the effect of which is to produce fluctuations in the phase and amplitude of the sound field at the receiver. In order to observe these fluctuations, a set of plots, referred to as scatter plots, are made which show the fluctuation of the complex amplitude over time. These plots will provide clues about the interaction between the acoustic wave and the turbulence. From these scatter plots, an empirical argument emerges which provides a statistical distribution having the same characteristics as the data. A comparison between the statistical distribution and the data is also presented.

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Finally, the phase and log-amplitude structure functions are calculated for the data runs.

The calculations are compared with the structure functions determined by Daigle.

II. Experimental Configuration

Measurements were made over a relatively flat open farm land over a period between mid-June 1984 and mid-July 1985. The sound source was driven by a tape which had, pre-recorded, a signal consisting of a mixture of seven pure tones centered at one octave spacing beginning with 62.5 Hz. A run consisted of an eight minute record of signals received simultaneously at five microphones mounted one meter above the ground surface and one microphone mounted near the source. The received signals were recorded on a seven channel TEAC R-81 tape recorder. Typically, at least one run was made in the morning and one run in the afternoon. This allowed for propagation through different turbulence conditions. During a typical run, the first five channels were used to record the signals from the array microphones, the sixth was used to record the reference microphone and channel seven was used for a voice log.

The measurements were made using four different types of geometries. The most common geometry had the source on the ground with a transverse array of five microphones one meter above the ground about 100 meters from the source and one microphone five meters from the source also one meter above the surface. Another common geometry had the source on top of a 100 foot tower with a transverse array of five microphones on the ground with one microphone about five meters from the source at the same height as the source. One experiment, December 13

- Run 3.1, was performed with the source on top of the tower and a vertical array of microphones ranging from 0 meters to 2.57 meters above the ground. Another run, December 13 - Run 2.1, was conducted with the source on top of the tower with a longitudinal array of microphones on the ground. A complete list of geometries for all of the runs is found in Appendix A.

The transverse array was chosen so that the phase and log-amplitude structure functions could be calculated for various transverse separation distances. This gives a measure of the fluctuations in the sound field after propagating some distance along almost parallel paths.

One quantity of interest is the fluctuation in the amplitude. In order to observe these fluctuations, we devised the analysis procedure shown in Figure 2.1. The analysis begins by retrieving the data from tape and passing it through a 1/3 octave filter set at one of the broadcast frequencies. The output from the filter was sent to a multichannel analyzer (MCA) which stored the amplitude of each acoustic half cycle in a channel number proportional to the amplitude. The number of counts in each channel is proportional to the probability that an acoustic half cycle will have a particular amplitude. The MCA accumulated data over the time of the run. After the accumulation was completed, the MCA showed amplitude distribution. After examining these for various frequencies, we found that the amplitude distributions were of two basic shapes; a Gaussian or Rayleigh as shown in Figure 2.2 and Figure 2.3. From these distributions, the relative sound pressure levels were calculated by taking from the distribution plots the difference between the mode of the array microphone and the mode of the reference microphone. The procedure for calculating the relative sound pressure levels is outlined in detail in Chapter IV. Later, the amplitude distribution plots will be used to fit a statistical distribution.

The next analyses yield the phase and log-amplitude structure functions and scatter plots. The configuration of the analysis equipment is given in Figure 2.4. The output from each channel of the recorder (other than seven) was passed through a 1/3 octave filter set at one of the broadcast frequencies to a multichannel ADF12F A/D converter connected to a Masscomp 5535 mini-main frame computer. The data was stored in a 16 bit binary file format for further analysis. The digitization rate was twelve times the signal frequency.

AMPLITUDE DISTRIBUTION APPRARATUS SETUP

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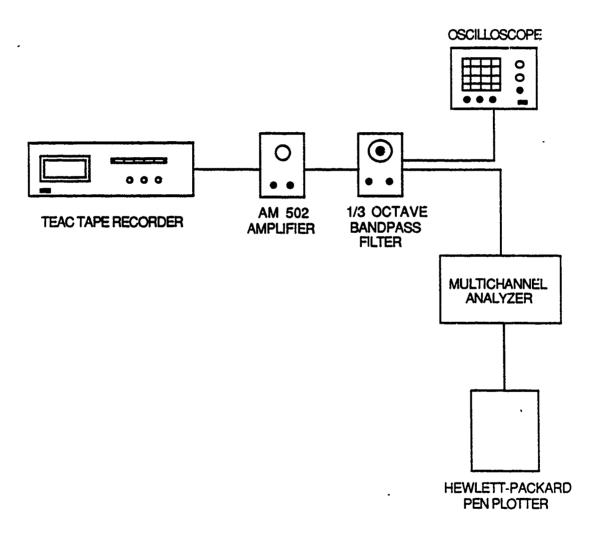
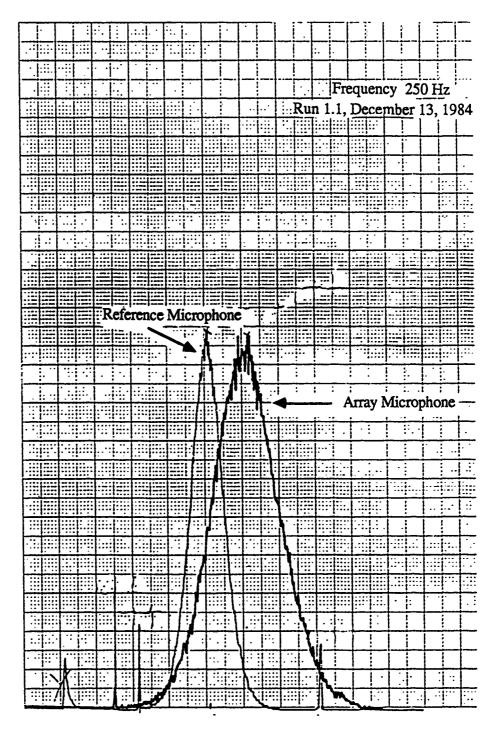


Figure 2.1

Relative Probability



Amplitude

Figure 2.2 Amplitude Probability from MCA

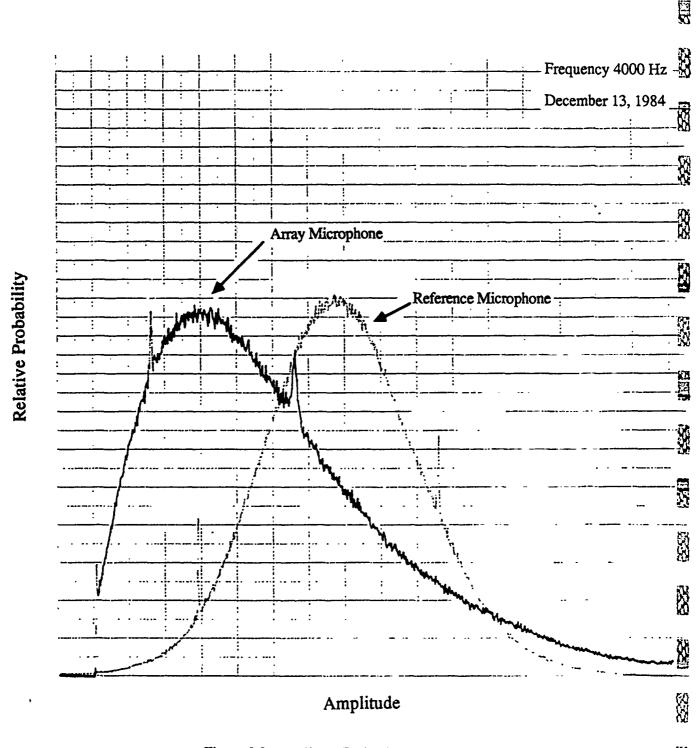
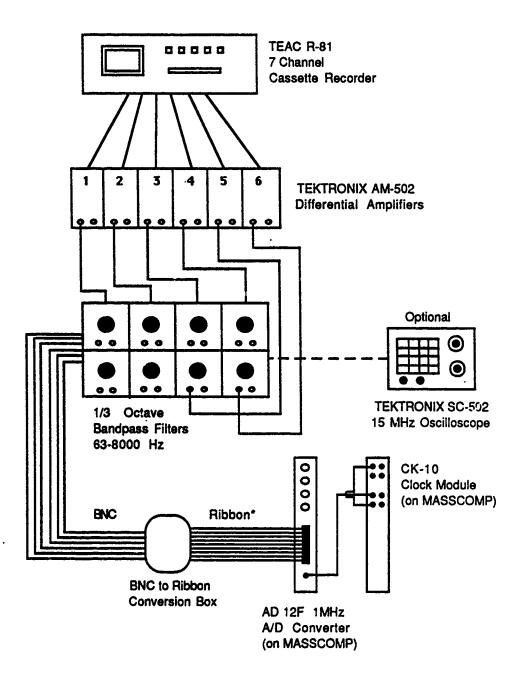


Figure 2.3 Amplitude Probability from MCA

TURBULENCE DATA ANALYSIS APPARATUS SETUP



SPETRA-STRIP (Gray with red edge, 28 AWG, 34 Conductor Cable)

Figure 2.4

The program phaze in Appendix B is used to calculate the phase and amplitude difference between any two channels for each acoustic half cycle. It accomplishes this by reading in 1024 points from each channel at one time and subtracting the dc bias from each channel. Next, the program searches through the data and locates the sign changes on each channel. The time of zero crossing is then estimated. A similar procedure based on change of slope gives the corresponding amplitude located between the crossings. After the time for each zero crossing has been calculated, the difference between this time and the corresponding time on another channel is calculated which is related to the phase difference between the two channels. The ratio of amplitudes for the two channels being compared is also computed for each half cycle. This process continues until all possible comparisons between channels have completed. The output from this program is used by the scatter plot and structure function routines described later.

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III. Weather Profiles

Meteorological effects can have a significant effect on the received sound field. Large eddies are formed in the atmosphere by instabilities in the thermal and viscous boundary layers at the surface of the ground. Futher instabilities cause these eddies to break down progressively into smaller and smaller sizes until the energy is finally dissipated by viscosity in eddies approximately 1 mm in size. A statistical distribution of eddies, which we call turbulence, is therefore present in the atmosphere at all times. The intensity of the turbulence, however, is strongly dependent on meteorological conditions.

While the effects of wind and temperature gradients appear similar in the graphs in Appendix C, the following differences should be noted. Because temperature is a scalar quantity, the refraction of sound produced by lapse or inversion conditions is the same in all horizontal directions. Wind, however, produces refraction which is nonuniform in direction according to the vector component of wind relative to the direction of propagation. Thus, the refraction produced

by wind is zero when the sound propagates directly crosswind, and increases progressively as the direction of propagation deviates from this condition.

Temperature and wind velocity vary strongly with height within the first few meters above the ground. These vertical gradients produce steep sound speed profiles close to the ground. In addition to the vertical gradients, the temperature and wind velocity fluctuate about their mean. The resulting random fluctuations of the refractive index scatter sound, which leads to random fluctuations in the phase and amplitude of the sound wave. Even when the turbulence is sufficiently weak that it has negligible effect on the sound field in free space it is still sufficient to affect the sound field above the boundary, especially in regions of destructive interference where the sound level is critically dependent on phase relationships.

For most of the experiment measurements of the wind velocity and temperature were made at four heights simultaneously. These points were located at 3, 10, 30, and 110 feet. An example of the output from the sensors is given in Table 3.1.

Time	Height	Wir	nd Speed	d (m/s)	Win	d Direc	tion	Tem	perature	(C)
	feet	Avg	Max	Min	Avg	Max	Min	Avg	Max	Min
11:25	110	8.0	11.0	6.1	34.8	404.3	386.4	2.7	3.1	2.3
	30	6.2	7.8	4.7	52.3	423.3	402.2	2.9	3.3	2.3
	10	5.8	7.3	4.1	226.5	248.1	196.9	3.1	3.6	2.0
	3	4.4	6.2	2.4	86.0	457.1	438.7	4.2	4.6	3.6
11:30	110	7.5	9.8	5.5	35.9	404.3	388.0	2.7	3.3	2.1
	30	6.1	7.7	4.9	54.4	420.7	404.3	2.9	3.3	2.5
	10	5.6	6.8	4.0	213.8	227.0	178.9	3.1	3.5	2.7
	3	4.3	5.8	3.2	87.1	462.4	435.5	4.2	4.6	3.7
11:35	110	7.9	9.4	6.1	37.0	409.1	384.8	2.7	3.3	2.2
	30	6.1	7.8	4.4	54.4	426.0	404.9	2.8	3.5	2.1
	10	5.7	7.8	3.7	183.7	203.2	176.8	3.1	3.5	2.3
	3	4.5	7.3	2.9	90.3	459.2	439.7	4.3	4.9	3.6

Table 3.1

This type data is available for seven of the experiments. The four points at each height represent an average.

The sound speed, sv, was calculated from

$$sv = 331.45 * \sqrt{(1 + T/273.15)} + w * cos(\phi - 90)$$
 (1)

where T is the temperature in Celcius, w is the wind speed, and ϕ is the angle that the wind is blowing relative to teh direction of propagation. A computer program performed a least square curve fit of the sound speed data to an equation of the form

$$sv = sv0 + m * ln(z)$$
 (2)

where sv0 is the sound speed at one meter, m is the slope of the curve, and z is the height above the ground. Typical values generated by this curve fit are given in Table 3.2.

Date	Run	Slope	c0
December 13, 1984	1.1	0.627	338.347
	1.2	0.663	338.609
	2.1	0.664	338.185
	4.1	0.948	338.770
January 11, 1985	2.1	-0.4876	325.320
	2.2	-0.4183	325.394

Table 3.2

A positive slope indicates that the atmosphere is downward refracting and a negative slope is upward refracting.

Also, in Appendix C there are weather data taken near the ground with a vertical array of thermocouples and temperature transducers. For the Sandusky site and June 23, 1985 Bondville site, both types of measurements were made. The measurements made with the thermocouple are indicated with the word trun and the other is run. Some measurements made at the Flatville site used only the thermocouple array.

IV. Relative Sound Pressure Level

The relative sound pressure level was calculated for each run. In all the measurements, a microphone placed close to the source served as a reference.

The relative sound pressure levels were computed from the distributions recorded by the MCA. The MCA output had the form of Figure 4.1. There are two distributions contained in the figure. The distribution marked B is the distribution of amplitude at an array microphone and D is the amplitude distribution at the reference microphone. The peaks marked A, C, and E are calibration points used to determine the dB levels of peaks B and D from a calibration tone put on each channel prior to every run. The difference in dB between the mode of the amplitude distribution recorded for the array and reference microphone is the relative sound pressure level. The difference is calculated as

$$R_{dB} = R_{odB} - 20 \log \left[\frac{xr_6 \cdot xc_i}{xc_6 \cdot xr_i} \right] - 20 \log \left[\frac{gc_6 \cdot gr_i}{gr_6 \cdot gc_i} \right]$$
(4.1)

where R_{OdB} is the difference in dB between the reference calibration point and the array microphone's calculation point, xr₆ is the MCA channel number for the reference, xr_i is the MCA channel number of the mode for the ith array microphone, xc₆ is the MCA channel number for the calibration point for the ith array microphone, gc₆ is the gain of the amplifier for the reference channel, gc_i is the gain for the ith array microphone channel, gr₆ is the gain for reference, and gr_i is the gain for the ith array microphone.

The following example will show how the equation is used. Referring to Figure 4.2, peak A is xc_i, peak B is xr_i, peak D is xc₆, and peak E is xr₆. Reading from the graph

$$xc_i = 2.0$$

 $xr_i = 6.1$

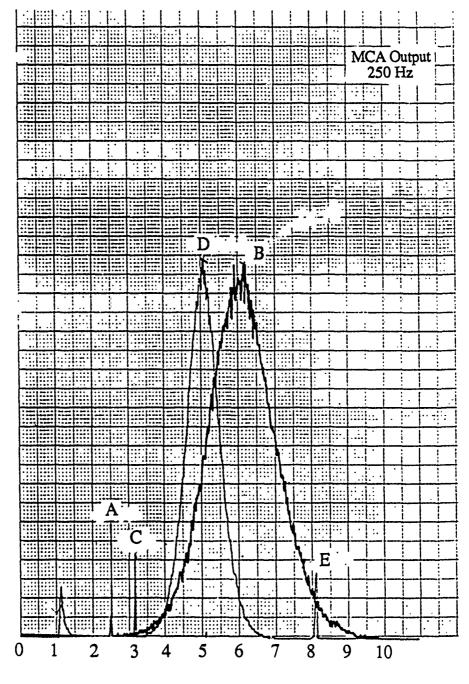
 $xc_6 = 3.2$

and

$$xr_6 = 5.05$$
.

From the data logs, $gc_6 = gr_6$ and $gc_i = gr_i$, also $R_{odB} = 44-84 = -40$ dB. Substituting these





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Amplitude

Figure 4.1

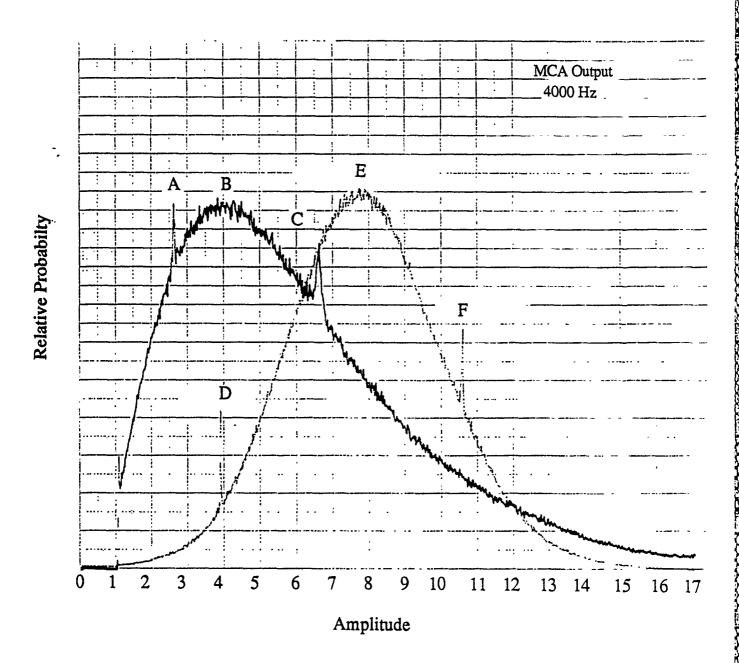


Figure 4.2

values into Eq. (4.1), R_{dB} is -42.28 dB. For most runs, the calibration gain is the same as for the run gain; however, there are a few runs where the gains are not the same. Plots of relative sound pressure level for every run are included as Appendix D.

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V. Distribution Functions

Large eddies are formed in the atmosphere by instabilities in the thermal and viscous boundary layers near the ground. Further instability causes these eddies to break down into progressively smaller sizes until the energy is finally dissipated by viscosity in very small eddies. A statistical distribution of eddies of various sizes is therefore present in the atmosphere at all times

The fluctuations in the sound pressure level of a pure tone measured outdoors, however, are frequently much larger than would predict on the basis of sound propagation in an unbounded medium. The influence of turbulence on the sound field can be large when a boundary is present because the field above the boundary is critically dependent upon the phase relationships between the direct and reflected waves near a boundary, then fluctuations in phase and amplitude are not independent.

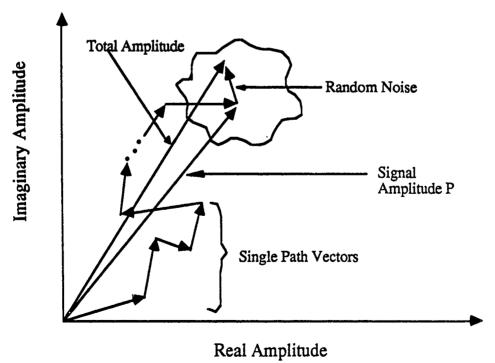


Figure 5.1

A polar representation of the signal is shown in Figure 5.1.

Note that the signal is composed of many single path vectors. These single path vectors are a mathematical representation of the various fluctuations in the phase and amplitude of the acoustical field as it propagates through the atmosphere. The total amplitude is a complex analysis representation of the complex signal amplitude P plus a complex random noise contribution. The random noise term takes into account the random nature of the fluctuations in the index of refraction of the turbules and size distribution of the turbules in the atmosphere over time. Any fluctuations in the total amplitude will depend upon the fluctuations in the single path phases and/or amplitudes, and the noise.²

In order to view the change in phase and amplitude over time, a series of scatter plots were made. A scatter plot is a representation of the changes in the complex amplitude over a fixed amount of time. Samples of these plots are provided in Figure 5.2 and Figure 5.3. The samples are from the January 11, 1985, run 2.1 data set.

These representative scatter plots appear as pictured in Figure 5.4.

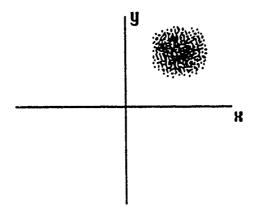
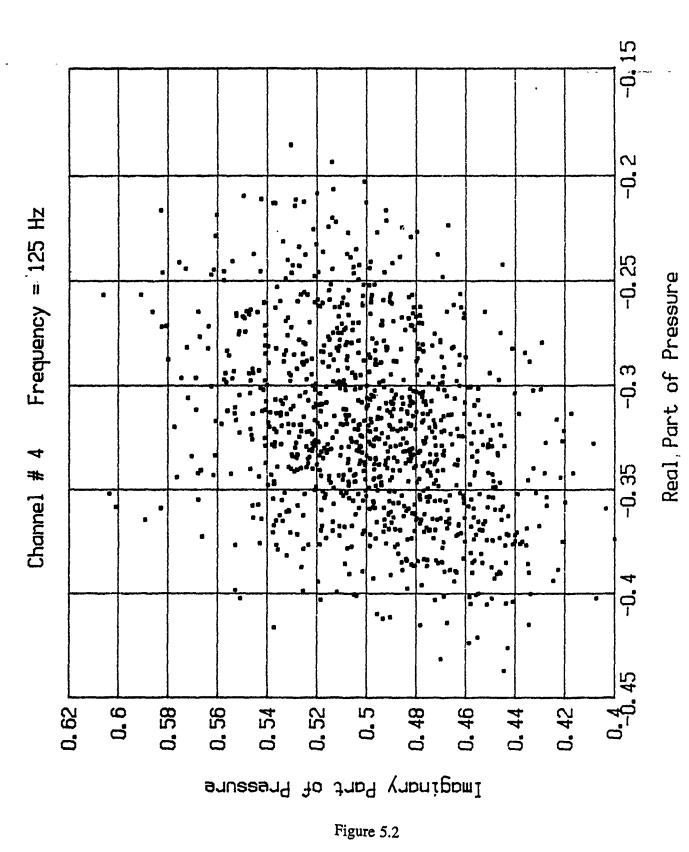


Figure 5.4

Assume that the real and imaginary parts have a Gaussian distribution about averages x and y.

These assumptions give a Bivariant Normal Probability Function of the form



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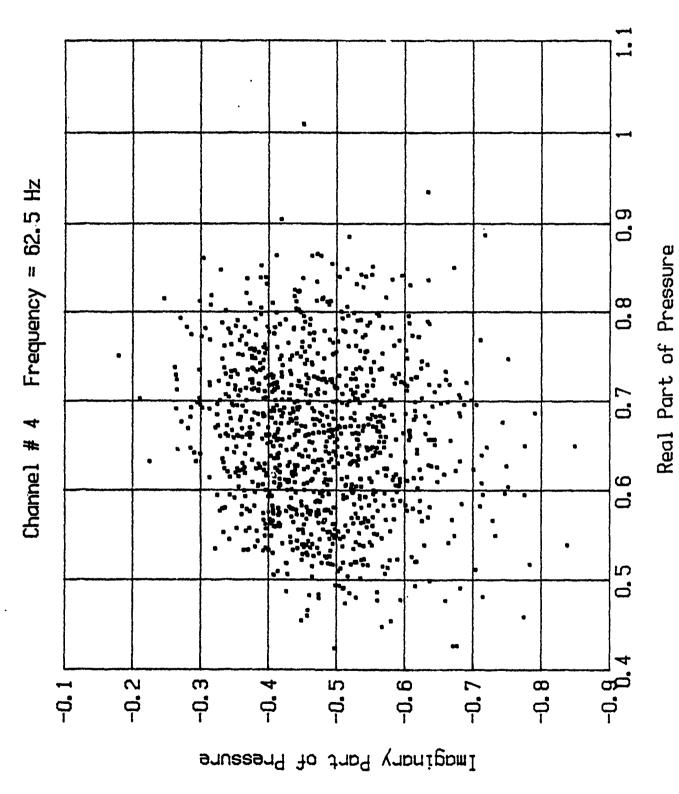


Figure 5.3

$$P(x,y) = \frac{1}{2\pi\sigma} e^{-\left[\left(x-x\right)^{2} + \left(y-y\right)^{2}\right]/2\sigma^{2}}$$

Converting to polar coordinates,

$$P(p) = p/\sigma^{2} e^{-p^{2} + p^{2}/2\sigma^{2}} I_{o} pp_{o}/\sigma^{2}$$
(5.1)

where

 p_0 = the distance to the center of the distribution, $\left(\bar{x}_0^2 + \bar{y}_0^2\right)^{1/2}$

 σ = the standard deviation of the distribution

p = the distance to a point in the distribution, $(x^2 + y^2)^{1/2}$.

If $p_0/\sigma >> 1$, Eq. 5.1 reduces to

$$P(p) = \frac{1}{\sqrt{2\pi} \sigma} \sqrt{\frac{p}{p_o}} e^{-(p-p_o)^2/2\sigma^2}$$

which has the form of a skewed Gaussian. If $p_0/\sigma << 1$, Eq. 5.1 reduces to

$$P(p) = \frac{p}{\sigma} e^{-p^2/2\sigma^2}$$

which has the form of a Rayleigh distribution.

The mode of a distribution is the point where the maximum probability occurs. This is found by taking the derivative of the distribution function and equating it to zero. If this is carried out on Eq. (5.1), the result is

$$x^{2} - x_{o}x \frac{I_{1}(x_{o}x)}{I_{o}(x_{o}x)} - 1 = 0$$

where $x = p/\sigma$ and $x_0 - p_0/\sigma$.

Case 1: $x_0 >> 1$ which is supposed to be Gaussian yields

$$\frac{I_1(x_0x)}{I_0(x_0x)} \rightarrow 1$$
 as x_0x becomes large

$$x^2 - x_0 x - 1 \approx 0$$

 $x \approx x_0$ which means that

the mode of the distribution is po.

This result corresponds to that for a Gaussian distribution.

Case 2: $x_0 \ll 1$ which is supposed to be Rayleigh yields

$$\frac{I_1(x_0x)}{I_0(x_0x)} \rightarrow 0$$
 as x_0x becomes small

$$x^2 - 1 = 0$$

x = 1 which means that the mode of the distribution is $\overline{\sigma}$. This corresponds to the behavior of a Rayleigh distribution.

Equation 5.1 was fit to the amplitude probability data from the MCA giving values for σ and P_0 . Comparisons between measured and computed distributions are given at Appendix E. The program used to perform a least squares curfit to the data is in Appendix B.

VI. Structure Functions

For straight-line propagation (absence of refraction) a distance r through atmospheric turbulence, the log-amplitude and phase structure of functions in a plane perpendicular to the direction of propagation are defined as 1

$$D_{x}(r,\rho) = \left\langle \left[x \left(\overrightarrow{r} + \overrightarrow{\rho} \right) - x \left(\overrightarrow{r} \right) \right]^{2} \right\rangle$$
(6.1)

anc

$$D_{s}(r,\rho) = \left\langle \left[\phi \left(\overrightarrow{r} + \overrightarrow{\rho} \right) - \phi \left(\overrightarrow{r} \right) \right]^{2} \right\rangle$$
(6.2)

respectively, where ρ is the separation between receivers, x is the log amplitude, and ϕ is the phase. The mean square log-amplitude and phase fluctuations, $\langle x^2 \rangle = \langle (\ln A/A_0)^2 \rangle$ and $\langle s^2 \rangle = \langle (\ln A/A_0)^2 \rangle$

 $\langle (\phi - \phi_0)^2 \rangle$, where A_0 and ϕ_0 are the amplitude and phase in the absence of turbulence, respectively.

If L is a measure of the scale of the turbulence, then in the case $(\lambda r)^{1/2} >> L$, the theory predicts that u is the rms fluctuations in the acoustic index of refraction

$$D_{x}(r,\rho) = 2\left[\left\langle x^{2}\right\rangle - B_{x}(\rho)\right] \tag{6.3}$$

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$$D_{s}(r,\rho) = 2\left[\left\langle s^{2}\right\rangle - B_{s}(\rho)\right] \tag{6.4}$$

where

$$\langle x^2 \rangle = \langle s^2 \rangle = \left(\frac{\sqrt{\pi}}{2}\right) \langle u^2 \rangle k^2 rL$$
 (6.5)

u is the rms fluctuation in the acoustic index of refraction, k is the propagation constant, and $B_X(\rho)$ and $B_S(\rho)$ are, respectively, the covariances of the log-amplitude and phase fluctuations.⁵

$$\frac{B_x(\rho)}{\langle x^2 \rangle} = \frac{B_s(\rho)}{\langle s^2 \rangle} = \frac{\Phi(\rho/L)}{\rho/L}$$
(6.6)

where

$$\Phi(\rho/L) = \int_{0}^{\rho/L} e^{-u} du.$$

In practice Eq. (6.5) agrees with experimental results for $\langle s^2 \rangle$. However, measurements show that $\langle x^2 \rangle \ll \langle s^2 \rangle$ and, in addition, the log-amplitude fluctuations quickly saturate. Substituting Eq. (6.6) and (6.5) for x into Eq. 6.3 yields

$$D_{x}(r,\rho) = \sqrt{\pi} \left\langle u^{2} \right\rangle k^{2} r L \left[1 - \frac{\Phi(\rho/L)}{\rho/L} \right]. \tag{6.7}$$

The extraction of the mean square amplitude and phase fluctuations requires processing of the recorded acoustical signals. The analysis requires the assumption that the phase and amplitude sequences represent samples of random processes where ensemble averages equal time averages (Taylor's Frozen Turbulence Hypothesis). Let i, j refer to two microphones in a plane

perpendicular to the direction of propagation. Then the log-amplitude for the ith microphone at the nth time sample is

$$x_{in} = \ln \left(\frac{A_{in}}{A_{io}} \right) \tag{6.8}$$

where Ain denotes the amplitude and

$$A_{io} = \frac{1}{N} \sum_{n=1}^{N} A_{in}$$
 (6.9)

is the average amplitude over N samples. The amplitude structure function, Eq. (6.1), is then computed from

$$D_{x} = \frac{1}{N} \sum_{n=1}^{N} (x_{in} - x_{jn})^{2}.$$
(6.10)

Similarly the phase structure function, Eq. (6.2) is obtained from

$$D_{s} = \frac{1}{N} \sum_{i=1}^{N} (\phi_{in} - \phi_{jn})^{2} - \left[\frac{1}{N} \sum_{n=1}^{N} (\phi_{in} - \phi_{jn}) \right]^{2}.$$
 (6.11)

Equation (6.11) is written in its more general form where the last term accounts for the fact that in experimental practice the mean phase difference of the measured signals may not be zero.

There are three programs which are used for this task. They are called phaz, phase, and turbl. The purpose of the program phaz was discussed in section 2. The program phase takes the output from phaz and calculates the phase structure function using Eq. (6.11). The program turbl is used to perform the calculations needed to arrive at the log-amplitude structure function.

The output from phase and turbl was plotted against transverse separation of the microphones. These plots can be found in Appendix F. The solid line is the theoretical curve based on Eq. (6.7) using the values from Table 6.1 for $\langle u^2 \rangle$ and L measured according to the method outlined by Johnson, Raspet, and Bobak.⁴

	1/1	1/85		<u>12/13/84</u>					
	Run 2.1	Run 2.2	Run 1.1	Run 1.2	Run 2.1	Run 4.1			
$\langle u^2 \rangle$	1.6 x 10 ⁻⁶	2.56 x 10 ⁻⁶	8.8 x 10-6	11.7 x 10 ⁻⁶	8.41 x 10 ⁻⁶	15.4 x10 ⁻⁶			
L	15 m	0.82 m	15.0 m	15.0 m	15.0 m	2.17 m			

Table 6.1

References

- 1. G.A. Daigle, J. E. Piercy, and T.F.W. Embleton, "Effects of Atmospheric Turbulence on the Interface of Sound Waves Near a Hard Boundary," J. Acoust. Soc. Am. <u>64</u>, 622-630 (1978).
- 2. Peter N. Mikhalevsky, "Characteristics of CW Signals Propagated Under the Ice in the Arctic," J. Acoust. Soc. Am. 70, 1717-1722 (1981).
- 3. S. F. Clifford and R.J. Lataitis, "Turbulence Effects on Acoustic Propagation Over a Smooth Surface," J. Acoust. Soc. Am. 73, 1545-1550 (1983).
- 4. M.A. Johnson, R. Raspet, and M.T. Bobak, "A Turbulence Model for Sound Propagation from an Elevated Source Above Level Ground," J. Acoust. Soc. Am. <u>81</u>, 638-646 (1987).
- 5. V.N. Karavinikov, "Fluctuations of Amplitude and Phase in a Spherical Wave," Akast. Zh. 3, 175-186 (1957).

APPENDICES

A. Geometries

This appendix contains the geometrical configuration for all of the experimental runs performed.

B. Programs

1000

This appendix contains the computer programs used to analyze or compute the results obtained.

C. Weather

Contains the plots of the different meteorological parameters measured during the experiment.

D. Relative Sound Pressure Levels

Contains the plots of the relative sound pressure level for each microphone and each experiment.

E. Distribution

Contains the MCA data that has been compared with the bivariant normal probability function.

F. Structure Function

Has the comparisons between the structure functions calculated from the data and Daigle's theoretical structure function.

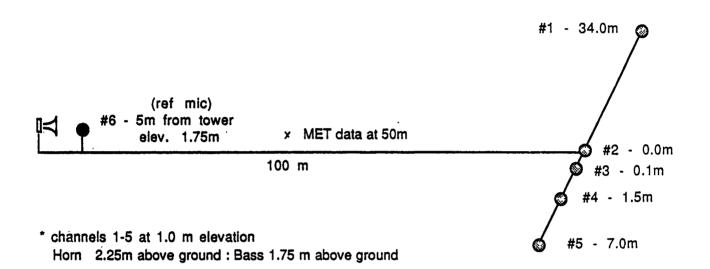
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APPENDIX A

区区

Geometrical configuration for all of the experimental runs performed.

GEOMETRY JUNE 19-20, 1984

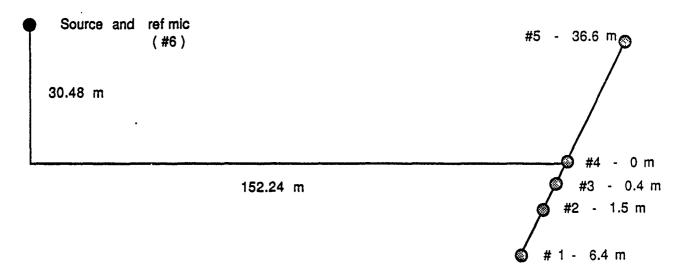


TRANSVERSE DISTANCES

1/2	34.0m
1/3	34.1
1/4	35.5
1/5	41.0
2/3	0.1
2/4	1.5
2/5	7.0
3/4	1.4
3/5	6.9
4/5	5.5

Bondville, III. Dec. 13, 1984 Runs 1.1 & 1.2

GEOMETRY

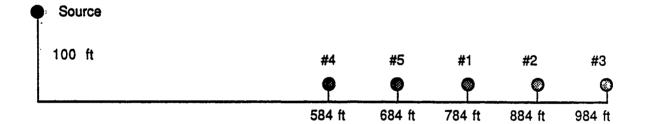


223

ransverse	Distances
1/2	5.0 m
1/3	6.1 m
1/4	6.4 m
1/5	43.0 m
2/3	1.1 m
2/4	1.4 m
2/5	38.0 m
3/4	0.3 m
3/5	36.9 m
4/5	36.6 m

Bondville, III. Dec, 13 1984 Run 2.1

Geometry



BONDVILLE, ILL. DEC. 13, 1984 RUN 3.1

区区

GEOMETRY

152.24 m

speaker and ref. mic (#6)

30.48 m vertical

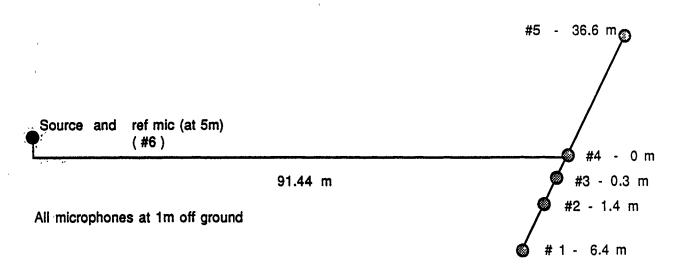
#5 - 2.57 m

#4 - 1.0 m

#1 - 0.0 m

Bondville III. Dec 13, 1984 Run 4.1

GEOMETRY



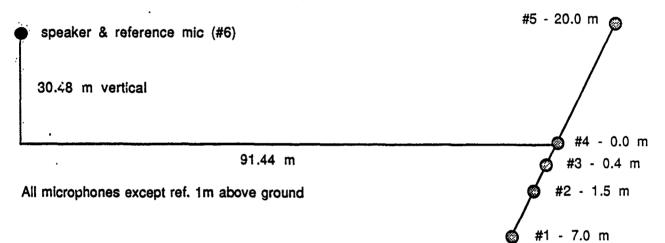
ransverse	Distances
1/2	5.0 m
1/3	6.1 m
1/4	6.4 m
1/5	43.0 m
2/3	1.1 m
2/4	1.4 m
2/5	38.0 m
3/4	0.3 m
3/5	36.9 m
4/5	36.6 m

BONDVILLE, ILL. JAN. 11, 1985 RUN 2.1

GEOMETRY

888

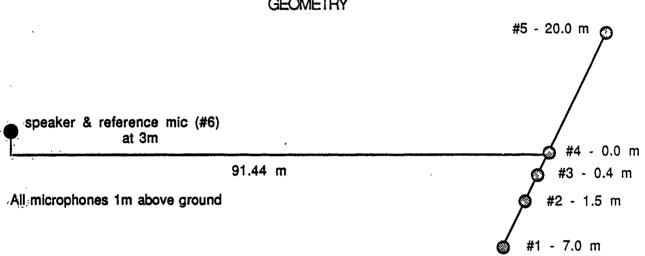
X.



Transverse		Distances	Ch. #	Mic. #
1/2	-	5.5 m	1	2
1/3	-	6.6	2	3
1/4		7.0	3	4
1/5	-	27.0	4	7
2/3	-	1.1	5	5
2/4	-	1.5	6	ref
2/5	-	21.5	7	voice
3/4	-	0.4		
3/5	-	20.4		
4/5	-	20.0		

BONDVILLE, ILL. JAN. 11, 1985 **RUN 2.2**

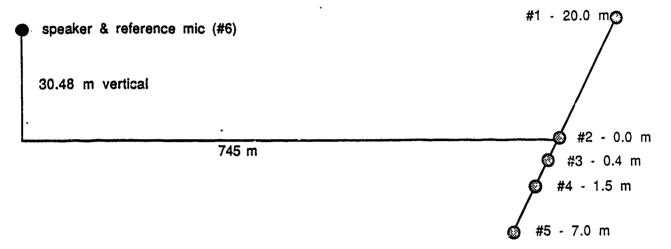
GEOMETRY



Transverse		Distances	Ch. # Mic. #
1/2	-	5.5 m	· 1 2
1/3	-	6.6	2 3
1/4	_	7.0	3 4
1/5	-	27.0	4 7
2/3	_	1.1	5 5
2/4	_	1.5	6 ref
2/5	_	21.5	7 voice
3/4	-	0.4	
3/5	_	20.4	
4/5	_	20.0	

BONDVILLE, ILL. JULY 23, 1985 RUN #1

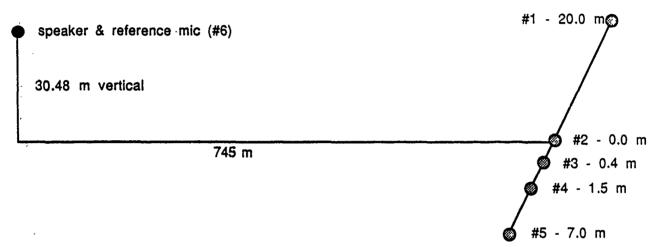
GEOMETRY



Transverse	Distances	Ch. #	Mic. #
1/2	20.0 m	1	7
1/3	20.4	2	5
1/4	21.5	3	4
1/5	27.0	4	3
2/3	0.4	5	2
2/4	1.5	6	?
2/5	7.0	7	voice
3/4	1.1		
3/5	6.6		
4/5	5.5		

BONDVILLE, ILL. JULY 23, 1985 RUN #2

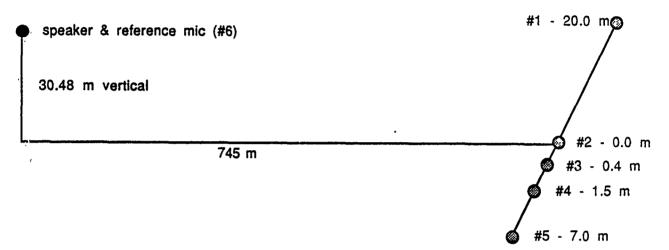
GEOMETRY



Transverse	Distances		Ch. #	Mic. #
1/2	20.0 m	,	1	7
1/3	20.4		2	5
1/4	21.5		3	4
1/5	27.0		4	3
2/3	0.4		5	2
2/4	1.5		6	?
2/5	7.0		7	voice
3/4	1.1			
3/5	6.6			
4/5	5.5			

BONDVILLE, ILL. JULY 23, 1985 RUN # 3

GEOMETRY

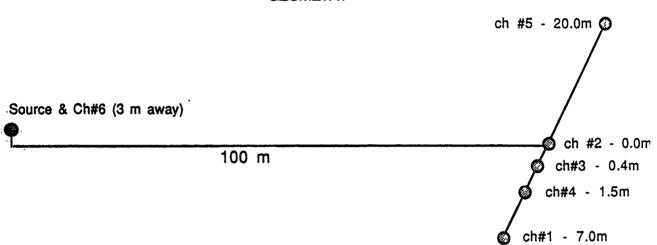


Transverse	Distances	Ch. #	Mic. #
1/2	20.0 m	1	7
1/3	20.4	2	5
1/4	21.5	3	4
1/5	27.0	4	3
2/3	0.4	5	2
2/4	1.5	6	?
2/5	7.0	7	voice
3/4	1.1		
3/5	6.6		
4/5	5.5		

22.3

BONDVILLE, ILL. JULY 25, 1985 RUN #1 RUN #2

GEOMETRY

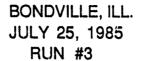


Horn 2 m above ground: Bass 1.36 m above ground Source 2 m above ground All microphones 1 m above ground

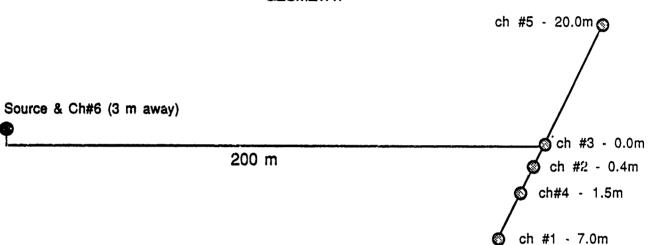
TRANSVERSE DISTANCE

AKG MICROPHONES

ch#/ch#	distance	mic#	ch#
1/2	7.0m	7	1
1/3	6.6	blank	2
1/4	5.5	4	3
1/5	27.0	AKG standard	4
2/3	0.4	2	5
2/4	1.5	Richard's	6
2/5	20.0		
3/4	1.1		
3/5	20.4		
4/5	21.5		







Horn 2 m above ground: Bass 1.36 m above ground
Source 2 m above ground
All microphones 1 m above ground
** notice ch#2 and ch#3 switched ***

TRANSVERSE DISTANCES		AKG MICROPHONES	
ch#/ch#	distance	mic#	ch#
1/2	6.6m	7	1
1/3	7.0	blank	2
1/4	5.5	4	3
1/5	27.0	AKG	4
2/3	0.4	2	5
2/4	1.1	Richard's	6
2/5	20.4		
3/4	1.5		
3/5	20.0		
4/5	21.5		

APPENDIX B

Computer programs used to analyze or compute the results obtained.

```
this program will read the weather data and convert to sup
c
C
   then perform the statistics
c -
C
        character*32 nfile
        real m(3),b(3),mavg
        dimension w(4,10), d(4,10), t(4,10), sv(4,10), ad(4), x(4)
        dimension xs(4),x2s(4),ys(4),y2s(4),xys(4),n(4),h(4),r2(3)
        print*,"Input data file"
        read*,nfile
        open(1,file=nfile,status="old")
        rewind 1
        h(1)=110
        h(2)=38
        h(3)=10
        h(4)=3
        x(1)=3.5571
        x(2)=2.3086
        x(3)=1.1147
        x(4) = -0.09431
        do 188 i=1,3
           n d=0
            ad(i)=0.0
            do 200 j=1,4
               read(1,*) w(i,j),d(i,j),t(i,j)
               ad(i)=d(i,j)+ad(i)
               if (d(i,j).ne.0.0) then
                  nd≈nd+1
               endif
200
           continue
            ad(i)=ad(i)/float(nd)
            do 400 j=1,4
               sv(i,j) = 331.5 * sqrt(i + t(i,j) / 273.15)
                          + ω(i,j) * cos(fad(i) - 90) / 52.295/79)
               if (t(i,j).eq.0.0.and.w(i,j).eq.0.0) then
               sv(i,j)=0.0
               endi f
               write(6,500) h(j), sv(i,j)
499
               continue
100
        continue
500
         format(5x,2f8.2)
   this section starts the statistical portion of the
C
              first we calculate the sums for each subset.
C
   program.
C -
c
         do 700 i=1.3
            x \le (i) = 0.0
            \times 2s(i) = 0.0
            ys(i)=0.0
            y2s(i)=0.0
            xys(i)=0.0
            n(i)=4
```

```
do 800 j=1.4
              if (sv(i,j).eq.0.0) go to 750
              xs(i)=xs(i)+x(j)
              x2s(i)=x2s(i)+x(j)*x(j)
              ys(i)=ys(i)+sv(i,j)
              y2s(i)=y2s(i)+sv(i,j)*sv(i,j)
              xys(i)=xys(i)+su(i,j)*x(j)
758
                  if (sv(i,j).eq.8.8) then
                 n(i)=n(i) - 1
              endif
800
              continue
           m(i)=(float(n(i))*xys(i)-xs(i)*ys(i))/
                        \langle float(n(i)) *x2s(i)-xs(i) *xs(i) \rangle
           b(i)=(ys(i)-m(i)*xs(i))/float(n(i))
           r2(i)=(float(n(i))*b(i)*ys(i)+float(n(i))*m(i)*xys(i)
                  -ys(i)*ys(i))/(float(n(i))*y2s(i)-ys(i)*ys(i))
700
        continue
        if (n(1).eq.n(2).and.n(1).eq.n(3)) go to 1100
        write(6,"('unequal data sets, check input')")
        go to 2008
1190
        continue
   this section calculates the combined statistics
        mavq=0.0
        bavg=0.0
        r2avg=0.0
        nm=0
        do 1300 i=1,3
           mavg=mavg+m(i)
           bavg=bavg+b(i)
           r2avg=r2avg+r2(i)
           nm=nm+1
1300
        continue
        mavg=mavg/float(nm)
        tory daing (floot (nm)
        r2avg=r2avg/f1oat(nm)
        write(6,1500) maug,baug,r2aug
        format(1x, "mavg=", f8.4," bavg=", f8.4," r2avg=", f8.5)
1500
2000
        stop
        end
```

```
C
     ************
     <del>****************************</del>
C
                                                *****
                         phaz.f
C
                 Finds the amplitude and phase
C
     *******
                    difference between two
     *****
C
                                                *****
                     different channels.
C
     ******************
C
     C
c
     program phaz
      integer hiwin, i, iblk, ch1, ch2, dgfreq, ipts, j
      integer K, lowin, n1, n2, xcycl1, xcycl2, nK
      integer npass, numch
      integer*2
                data(1024,2)
            areal, area2, bias1, bias2, freq
     real
             datai(1024), data2(1024), hper, lastp1, lastp2
     real
             noise1, noise2, period, phasinc, phastot, pi, sumtim
     real
             tol, tsampl, timkp1, timkp2
     real
             time(1024,2), phase(2048), ampl(1024,2)
     real
     parameter (pi=3.1910/2007, ___
open(20,file='/data/adc.dat',access='direct',status='old',recl=2,x
      parameter (pi=3.141592654, to l=0.15)
      open(1,file='/data/holder',status='old')
      open(2,file='/data/ampl.dat')
      open(4,file='/usr/data/phase.dat')
      open(3,file='/usr/data/freq.dat')
      rewind 1
      read(1,*), numch
      read(1,*),dgfreq
      read(1,*), ipts
      read(1,*),ch1
      read(1,*),ch2
      tsamp1 = 1 / float(dgfreq)
      freq = float(dgfreq / 12)
      hper = 1 / (2 * freq)
      npass = ipts / (numch * 1024)
      xcycli = 0
      xcyc12 = 0
      lastp1 = 0.
      lastp2 = 0.
      areai = 0.
      area2 = 0.
      phastct = 0.
      iblk = 0
      nk = 0
      ******************
 C
      ** Read In 1024 Points From Each Channel **
```

 $\overline{\mathcal{S}}$

```
C
     ** Skip First Hundred Points
     ********
c
     lowin = chi + nk * numch + 100 ★ numch
10
     hiwin = ch1 + (nk + 1023) * numch + 100 * numch
     j = 1
     do 2 i=lowin, hiwin, numch
       read(20, rec=i), data(j, 1)
       read(20,rec=i+ch2-ch1),data(j,2)
       j = j + 1
 2
     continue
     nk = nk + 1024
     *********
C
     ***** Determine DC Blas (Just Average Over
C
     ***** Complete Cycles, 1020 instead of 1024)
C
                                             ****
     *******************
c
     bias1 = 0.0
     bias2 = 0.0
     do 15 i=1,1020
       biasi = biasi + float(data(i,1))
       bias2 = bias2 + float(data(i,2))
15
     continue
     biasi = biasi / 1020.
     bias2 = bias2 / 1020.
     *******
C
     ** Remove DC Blas **
C
     ************
     do 20 i = 1, 1024
       data1(i) = data(i,1) - bias1
        data2(i) = data(i,2) - bias2
20
     continue
C
     n1=xcycli+1
     n2=xcyc12+1
c
     *************************
     ***** Determine Local Zeroes For Channels 1 & 2 *****
     ********************
     call cycle(1,data1,n1,lastp1,timkp1,area1,time,ampl,
                   tsamp1)
     ni=ni-1
     call cycle(2,data2,n2,lastp2,timkp2,area2,time,amp1,
                   tsampl)
     n2 = n2 - 1
c.
     *************
C
            Zero Crossings are now in
            Time Array. Compute Period *****
C
     ****
     **************
     sumtim=0.0
     do 65 i=1,n1
        sumtim=sumtim+time(i,1)
65
     continue
```

ጀኒያዊያል የጀኒኒያዊ የጀኒኒያዊ የጀኒኒያዊ እና እና ተመሰር ላይ ተመሰው የሚያለው የተመሰው የሚያለው የሚያለው የሚያለው የሚያለው የሚያለው የሚያለው የሚያለው የሚያለው የሚያለ የመስያያለው የጀኒኒያዊ የጀኒኒያዊ የመጀኒኒያዊ የመጀ

```
period=2.*sumtim/n1
     frea=1.0/period
     ***********
C
            Check Signal to Noise Ratio for this Block
c
     <del>**************************</del>
c
     noise1=float(nzer1)/float(n1)*100.
     noise2=float(nzer2)/float(n2)*100.
     if (noise1.1t.5.) then
          if (noise2.1t.5.) then
            **************************
                   Compute Phase
                                  ****
c
            *********
C
                phasing=(time(1,1)-time(1,2))/period*360.
                phase(1)=phastot+phasinc
                k=min0(n1,n2)
                do 70 i=2,k
                  phasinc=(time(i,1)-time(i,2))/period#360.
                  phase(i)=phase(i-1)+phasinc
79
                continue
                do 75 i=1, k
                   if (iblk.eq.0.and.i.eq.1) go to 75
                  write(2,*)ampl(i,1),ampl(i,2)
                  write(4,*)phase(i)
75
                continue
                phastot=phase(K)
                print*,'Ch 2. Too Noisy. Skip Data. Hold Phase.'
           endif
        else
           print*,'Chi. Too Noisy. Skip Data. Hold Phase.'
     endi f
     ib1k=ib1k+1
     if (iblk.ge.npass) go to 95
     xcycli = 0
     xcyc12 = 0
      if (n2.qt.n1) then
          C
               More Cycles on Ch 2
                                  ****
C
        ***********
C
        xcyc12=n2-n1
        do 85 i=1,xcyc12
           time(i,2)=time(n1+i,2)
           ampl(i,2)=ampl(n1+i,2)
85
        continue
      endif
      if (n1.gt.n2) then
        *<del>*</del>****************************
C
               More Cycles on Ch 1
                                  ****
c
        C
        xcycli=n1-n2
```

ስያለዊ ስያለያ ስር ፈላጊ ተመፈር እና የሚያስፈር እ

```
do 90 i=1,xcycl1
          time(i,1)=time(n2+i,1)
          ampl(i,1)=ampl(n2+i,1)
90
       continue
     endif
     go to 10
     write(3,*) freq
95
     stop
     end
C
C
     ***********
C
     ** Finds the Zero Crossing Between **
C
            (0,y1) And (dx,y2)
C
     C
     real function zerox(y1,y2,dx)
            y1, y2, slope, dx
     slope = (y2 - y1) / dx
     zerox = -yi / slope
     .return
     end
C
c
     subroutine cycle(nch,data,ncyc,lastpt,timeKp,area,
                   time, ampl, tsampl)
     *********
C
        Processes Cycles in Each Block of 1024 Points
C
        Records Time and Amplitude of each 1/2 cycle
c
     *************************
C
c
     integer
              i, neye, nch
              amp1(1024,2), time(1024,2), data(1024)
     real
              aftime, zerox, thispt, lastpt, prod, timekp, tsampl
     real
              pi, area
     parameter (pi=3.141592654)
C
     do 10 i=1,1024
        thispt=float(data(i))
        prod = thispt*lastpt
        if (prod.ge.0) then
          **********
C
                Same Side of Zero
C
          **********
C
          timekp = timekp + tsamp1
          area = area + tsampl*(thispt+lastpt)/2
          if (thispt.ea.0) then
             ********
C
             **** Hit Zero Exactly
C
             *********
             time(ncyc,nch) = timeKp
```

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```
ampl(ncyc,nch) = (pi*area)/(2*timekp)
           ncyc = ncyc + 1
           timekp = 0
           area = 0
         endif
      else
c
         *****************
         ***** Crossed Zero -- End of 1/2 Cycle
c
         aftime = zerox(lastpt,thispt,tsampl)
         timekp = timekp + aftime
         area = area + lastpt*aftime/2
         time(ncyc,nch) = timeKp
         amp!(ncyc,nch) = (pi*area)/(2*timeKp)
         ncyc = ncyc + 1
c
         c
         ***** Get Prepared For Next 1/2 Cycle
         ******************
         timekp = tsamp1 - aftime
         area = thispt*timekp/2
      endi f
C
       ***************
      **** Remember This Data Point
C
C
      *****************
      lastpt = thispt
10
    continue
    return
```

end

 \mathbb{R}

```
***************
C
  <del>****************************</del>
C
                      phase.f
  ********
C
              Finds the average phase and
  *******
٠C
 *****
              the phase structure function
                                         *****
                for a pair of channels.
  *********
  ***********
C
c
  program phase
  dimension tot(1000),tot2(1000),ds(1000)
  integer*4 num(1000)
  format(15x,e13.6,12x,e13.6)
  format(1x,/,25x,'Corrected Results ')
  format(10x, 'Overall Avg Phase =',e13.6,3x,'Avg Structure =',e13.6)
  format(25x, 'Raw Data')
  format(23x,'Very Raw Data')
  format(10x.'Phase Structure Function', 6x, 'Average Phase', /,
         18x, '(rad**2)', 18x, '(rad)')
   format(10x, Total Phase Structure = ',e13.6)
16 format(10x, 'Frequency = ', f11.6)
   open(4,file='/usr/data/phase.dat',status='old')
   open(1,file='/usr/data/freq.dat',status='old')
   open(2,file='/usr/data/ph')
   open(3,file='/usr/data/cph')
   open(5,file='/usr/data/raw')
   rewind 1
   rewind 4
   pi=3.141592654
   conv=pi/180.
   read(1,*),freq
   ns=1
   write(2,7)
   write(2,8)
   write(5.1)
   write(5,8)
   ********
   ***** Read Phase and Compute 5 Second Averages
   ********
   kt=20*ifix(freq)
   do 99 i=1,6
     read(4,*),phase
 99 continue
 10 j = j + 1
   num(j)=0
   tot(j)=0.0
   tot2(j)=0.0
   do 20 i=1.kt
```

```
read(4,*,end≈25),phase
     t=phase*conv
     if (i.eq.1.and.j.eq.1) then
           t0=t
        else
           call correction(t,t0)
     endif
     tot(j)=tot(j)+t
     tot2(j)=tot2(j)+t*t
20 continue
   tot2(j)=tot2(j)/float(kt)
   tot(j)=tot(j)/float(kt)
   ds(j)=tot2(j)-tot(j)**2
  write(5,2)ds(j),tot(j)
  num(j)=j
   go to 10
  **********************
          Identify Long Term Drifts, First Find Average Phase,
          Ignore Records Less Than 5 Sec. in Duration
                                                               ****
  ******************************
25 j=j-1
26 call average(ds,avg,j)
  call standard(ds,avg,stan,j)
  var=stan * stan
  print*, var
   if (var.1t.0.1.or.j.1t.6) go to 28
   call search(tot,tot2,ds,num,j,stan,avg)
  call structure(tot,tot2,ds,j)
   go to 26
28 do 29 i=1,j
     write(2,2)ds(i),tot(i)
29 continue
   avg2=0.0
   avgx=0.0
   sum=0.0
   sig2=0.0
   avgy=0
   do 30 i=1,j
     augy=augy+tot(i)
     sum=sum+tot(i)*float(num(i))
     sig2=sig2+float(num(i)*num(i))
     avgx=avgx+float(num(i))
     avg2=avg2+(tot2(i)-(tot(i)**2))
30 continue
   avgx=avgx/float(j)
   avg2=avg2/float(j)
   augy=augy/float(j)
   sum≃sum/float(j)
   sig2=sig2/float(j)-avgx*avgx
   slope=(sum-avgx*avgy)/sig2
```

```
b=avgy-slope*avgx
  write(2,4)avgy,avg2
  ***********
. C
          Now Correct for Drift
  do 40 i=1.j
     corr=slope*float(rum(i))+b
     tot2(i)=tot2(i)-2.*corr*tot(i)+corr*corr
     tot(i)=tot(i)-corr
40 continue
  *************
c
          Save Corrected Results
                                 ****
  *****************
  write(3.3)
  write(3,8)
  avg1=0.0
  avg2=0.0
  avg3=0.0
  do 45 i=1, j
     ds(i)=tot2(i)-tot(i)**2
     avg3=avg3+ds(i)
     write(3,2)ds(i),tot(i)
     avg1=avg1+tot(i)
     avg2=avg2+tot2(i)
45 continue
   avgi=avgi/float(j)
   ds(j+1)=avg2/float(j)-avg1*avg1
   avg3=avg3/float(j)
  write(3,4)avg1,avg3
  write(3,9)ds(j+1)
  write(3,16)freq
   stop
   end
C
   subroutine search(mark,mark2,ds,num,j,stan,avg)
   real*4 mark(1000),mark2(1000),ds(1000)
   integer*4 num(1000)
   pi=3.141592654
   accept=avg + stan
   diff=0.
   i=1
10 if (i.le.j) then
      if (accept.lt.ds(i)) then
           do 20 k=i,j-1
              mark(k)=mark(k+1)
              mark2(k)=mark2(k+1)
              num(k)≔num(k+1)
              ds(k) = ds(k+1)
20
           continue
```

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```
j=j-1
            diff=mark(i) - mark(1)
            i=i-1
            mark(i)=mark(i) - diff
            mark2(i)=ds(i) + mark(i) * mark(i)
      endif
      i=i+1
      go to 10
   endif
   return
   end
c
c
   subroutine correction(phase,phi0)
   pi = 3.141592653589
10 flag=1.
   dphi=phase - phi0
   if (abs(dphi).gt.pi/2.) then
      if (dphi.eq.0.) then
            sign=1.
         else
            sign=dphi/abs(dphi)
      phase=phase - sign * pi / 2.
      flag=0.
   endif
   if (flag.eq.0) go to 10
   phi0=phase
   return
   end
C
C
   subroutine average(x,avg,num)
   dimension x(1000)
   sum=0.
   do 10 i=1, num
      sum=sum + x(i)
10 continue
   avg= sum / float(num)
   return
   end
C
c
   subroutine standard(x,avg,stan,num)
   dimension x(1000)
   diff=0.
   do 10 i=1, num
      diff=diff + (x(i) - avg) * (x(i) - avg)
10 continue
```

```
diff = diff / float(num) 
stan=sqrt(diff)
return
end
c
c
subroutine structure(mark,mark2,ds,j)
real*4 mark(1000),mark2(1000),ds(1000)
do 10 i= 1,j
    ds(i)=mark2(i) - mark(i) * mark(i)
10 continue
return
end
```

```
C
     C
     C
                           turb!
c
                Finds the ampl tude structure
                   for a pair of channels.
c
     ***********************************
c
C
     按据按据按据按按证据
C
c
     program turbl
     open(1,file='/data/ampl.dat',status='old')
     open(2,file='/usr/data/aph')
101
     format(15x, '2048 Point Average = ',e13.6)
102
     format(10x,'Amplitude Structure Function = ',e13.6)
     sumi=0.0
     sum2=0.0
     n=0
5
     read(1,*,end=20),ampli,ampl2
     if (abs(ampl1).lt.5.0.or.abs(ampl1).gt.5000.) go to 5
     if (abs(amp12).1t.5.0.or.abs(amp12).gt.5000.) go to 5
     sum1=sum1+abs(amp11)
     sum2=sum2+abs(amp12)
     go to 5
20
     if (n.ne.0) then
        avg1=sum1/float(n)
         avg2=sum2/float(n)
         print*,"There are no acceptable amplitude values"
        go to 50
     endi f
     rewind 1
     0.0=xb
     nn=0
25
     sum1=0.0
     n=0
     do 30 i=1,2048
        read(1,*,end=40),ampli,ampl2
        if (abs(ampl1).!t.5.0.or.abs(ampl1).gt.5000.) go to 30
        if (abs(amp12).1t.5.0.or.abs(amp12).gt.5000.) go to 30
        n=n+1
        ampli=abs(ampli/avgi)
        amp12=abs(amp12/avg2)
        ampli=alog(ampli)
        amp12=alog(amp12)
        sumi=sumi+(ampli-ampl2)*(ampli-ampl2)
30
     continue
     if (n.ne.0) then
        dx=dx+sum1/float(n)
```

区区

A P

```
C
     ***********************
c
     ****
                        Theory . f
c
     ****
            Generates data for the theoretical
                                               ****
     ****
            plot of the structure function.
C
     C
C
     program theory
     real mu2, L, nu, lambda, k
     character*64 xname, yname
     print*, "Name of x file"
     read*,xname
     print*, "Name of y file"
     read*,yname
     open(1,file = xname)
     open(2,file = yname)
     print*,"Propagation Distance in Meters"
     read*,r
     print*, "Mu**2"
     read*,mu2
     print*, "Outer Scale of Turblence in Meters"
     print*, "Temperature at run in Celsius"
     read*,T
     print*, "Frequency in Hz"
     read*,nu
     print*, "Input maximum separation"
     read*, sep
     ihigh = ifix(sep * 10.)
     i!ow = 1
     pi = 3.141592654
     c0 = 331.6
     c = c0 * sqrt(1 + T / 273)
     lambda = c / nu
     K = 2 * pi / lambda
     k2 = k * k
     do 10 i = ilow, ihigh
        rho = float(i) / (10 * L)
        call integrate(rho,L,phi)
C
                                                          C
c
                                                          C
     sf = sqrt(pi) * ( u ) * k * r * L * ( 1 - ----
c
                                                          C
                                                 rho
C
    where:
C
      sf
             Structure Function
C
       2
C
      <u >
c
             Fluctuating Index of Refraction
             The Wave Number
C
       r
             Straight-Line Propagation Distance
C
```

ዸጞፚኯፚ፠ዄጞፚፙፚፙጜኯኯኯፚቑፚቑፚቑፚቑፚዹዹኯጜዹዹጚኯዹዹፚቑፚቑፚቑፚቑፚቑቔቑዾኯዾቑኯዺዹዹዹዹዹዹዹዹዹዹዹዹኯኯኯኯዹዹዹኯኯ ዸጞፚኯፚ፠ዄቔፚፙፚፙጜኯኯኯኯኯዹዹዹዹዹ

```
Outer Scale of Turbulence
C
              Integral from 0 to the / L of exp(-x*x) dx
       phi
C
              Spatial Separation Perpendicular to the
C
       rho
              Direction of Propagation
C
         sf = sqrt(pi) * mu2 * k2 * r * L * (1 - phi / rho)
         if (sf.le.0) go to 10
         write(1,*) rho * L
         write(2,*) sf
      continue
10
      stop
      end
      Performs a Numerical Integration Using Trapazoid Rule c
    With Endpoint Correction
C
c.
C
      subroutine integrate(rho, L, phi)
      real L
      itter=20
      upper=rho
      lower=0
      dx=(upper - lower) / float(itter)
      x=lower
      call equation(x,y0)
      y=7 * y0
      call derivative(x,yp)
      y=y + dx * yp
      x=upper
      call equation(x,y0)
      y=y + 7 * y0
      call derivative(x,yp)
      y=y - dx * yp
      i=1
      x=lower + dx
10
      if (x.1t.upper - dx / 2.) then
          if (2*ifix(i / 2).eq.i) then
               call equation(x,y0)
                y=y + 14 * y0
             else
                call equation(x,y0)
                y=y + 16 * y0
         endif
         x \approx x + dx
          i=i+1
         go to 10
      endif
      phi= dx * y / 15.
```

```
return
      end
C
      Performs a Numerical Derivative Using Difference
                                                             C
C
      Tables. This is Used in the Numerical Integration
                                                             C
c
      Routine For Endpoint Correction
                                                             C
      subroutine derivative(x,yp)
      dimension delta(20), diff(20)
      dx = x / 100
      xx=x
      do 110 i=1,20
         call equation(xx,delta(i))
         xx=xx + dx
110
      continue
      do 130 j=1,18
      do 120 i=1,20-j
         delta(i)=delta(i+1) - delta(i)
120
      continue
      diff(j)=delta(1)
130
      continue
      yp=0
      do 140 i=1,18
         if (dx.ne.0) then
                yp=yp + (-1.)**(i+1) * diff(i) / (dx * float(i))
             else
                yp=0
          endif
140
      continue
       return
       end
C
c
       subroutine equation(x,y)
       y=exp(-x * x)
       return
       end
```

```
program distrib
      character*64 fnam, xnam, ynam
print*,"Root name for data"
      read*,fnam
      xnam = "x"//fnam
      ynam = "y"//fnam
      open(1,file=xnam,status="new")
      open(2,file=ynam,status="new")
      print*,"Insert p0"
      read*,p0
      print*,"Insert sigma"
      read*,sigma
      print*, "Upper limit for p"
      read*,pu
      print*, "Lower limit for p"
      read*,pl
      print*, "Increment for p"
      read*,pinc
      x0 = p0 / sigma
      xu = pu / sigma
      x1 = p1 / sigma
      xinc = pinc / sigma
      x = x1 - xinc
10
      x = x + xinc
      t = (x * x0) / 3.75
      if (t.ge.1) then
          call bivge1(x,x0,t,sigma,P)
          call bivlt1(x,x0,t,sigma,P)
      write(1,*) \times * sigma
      write(2.*) F
      if (x.1t.xu) go to 10
      stop
      end
C
      subroutine bivge1(x,x0,t,sigma,P)
      real I0
      IO=0.39894228+0.01328592/t+(0.002255319/(t*t))-(0.001575a5/t**3)
             +(0.00916281/t**4)-(0.02057706/t**5)+(0.02635537/t**6)
             -(0.01647633/t**7)+(0.00392377/t**8)
      10 = 10 / sqrt(x * x0)
      P = ((x * 10) / sigma) * exp(-((x - x0) * (x - x0)) / 2.)
      return
      end
C
      subroutine biv1t1(x,x0,t,sigma,P)
      real I0
```

I0=1+3.5156229*t*t+3.0899424*t**4+1.2067492*t**6
+ +0.2659732*t**8+0.0360768*t**10+0.0045813*t**12
P = ((x * I0) / sigma) * exp(-(x * x + x0 * x0) / 2.)
return
end

区区

```
*********************
 THIS PROGRAM IS DESIGNED TO FIT THE DATA USING
 LEAST SQUARES TO A NORMALIZED BIVARIANT DISTRIBUTION.
**************************
 program distfit
 parameter (maxd = 100, maxp = 5, npts = 500)
 character*1 yesno
 character*64 device
 real xdata(maxd), ydata(maxd), par(maxp)
 real xtheory(npts), ytheory(npts)
***<del>****************************</del>
  ---- READ ALL THE DATA INTO ARRAYS AND KEEP COUNT -----
open (10.file='xdatafile')
  open (11,file='ydatafile')
  rewind 10
  rewind 11
*********
  ---- EITHER ASK FOR GUESSES OR STORE THEM -----
print *, "best guess for p0 and sigma"
  read *, par(1), par(2)
  npar = 2
***********
  ---- READ THE DATA POINTS ----
10 read (10,*,end=20) xdata(i)
  read (11,*,end=20) ydata(i)
  i = i + 1
  goto 10
20 \text{ ndata} = i - 1
  skip = 0.
***********************
  ---- NORMALIZE THE DATA -----
**<del>******************</del>
  call integrate(xdata,ydata,ndata)
**********
```

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```
---- LOOP, GETTING BETTER PARAMETERS ----
*
***********
30 call curvefit (xdata,ydata,ndata,par,npar,sum)
*************************
 PLOT THE THEORETICAL CURVE AGAINST THE DATA
 USING THE NEW PARAMETERS
×
******************
  if (skip.eq.0.) then
   print *, "which device? screen, plotter, or none"
35
   read *.device
   if (device.ne."none") then
    if (device.ne."screen".and.device.ne."plotter") then
       print*,device,"is an invalid device"
       go to 35
    endif
**********
¥
    ---- CALCULATE THE THEORETICAL CURVE ----
×
×
call gtheory (xtheory, ytheory, par, npts)
    call plotdat (xdata,ydata,xtheory,ytheory,device,ndata,npts)
   endif
 endif
*******************************
  ---- WRITE OUT NEW VALUES AND SAVE THEM ----
×
print *, "sum,
               р0,
                     sigma"
 print *, sum, (par(i), i=1,npar)
 write (20,*) sum, (par(i), i=1,npar)
---- EITHER ASK NEW PARAMETERS OR USE OLD ONES -----
if (skip.eq.0.) then
    print *,"Do you wish to try again? (y/n/s)"
    read *, yesno
    if (yesno .eq. "s") then
      print*, "The number of iterations"
      read*, skip
      go to 30
    endi f
    if (yesno .eq. "y") goto 30
   else
```

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```
skip = skip - 1.
    go to 30
  endif
  stop
  end
  subroutine curvefit(xdata,ydata,ndata,par,npar,sum)
Fits theory to data by a least squares method
       invented by Guass.
×
       xdata.ydata
                    data points to fit(array)
       ndata
                    number of points in array
       par
                    array of quesses for parameters
       npar
                    number of free parameters
parameter (maxp = 5)
  real xdata(*), ydata(*), par(*), q(maxp), u(maxp)
  real dyda(maxp), work1(maxp), work2(maxp), s/maxp*maxp)
  real theory
---- ZERO MAT S AND ARRAY Q --
do 10 i = 1, maxp
10
       q(i) = 0
  do 20 i = 1, maxp*maxp
20
       s(i) = 0
***********************************
  ---- STEP'THROUGH ALL OF THE DATA POINTS -----
weight = 0.
  sum = 0.
  do 30 i = 1.ndata
       xyalue = xdata(i)
       ytheo = theory(par,xvalue)
        sum = sum + (ytheo - ydata(i)) ** 2
       call deriv(par,xvalue,ytheo,dyda)
        do 30 k = 1, npar
             q(k) = q(k) + dyda(k) * (ytheo - ydata(i))
             weight = weight + dyda(k) * ytheo
                   do 30 m=1.npar
                   ***********
                   ---- INDEX ON S LIKE 2 DIMENSION
                   *********
                   km = npar * (m - 1) + k
```

```
s(km) = s(km) + dyda(k) * dyda(m)
30 continue
  weight = 2. * sum / weight
  do 35 k = 1, npar
        kk = npar * (k - 1) + k
        s(kk) = s(kk) + 1. / weight
35 continue
  call gminv (s,npar,det,work1,work2)
  call gmprd (s,q,u,npar,npar,1)
---- VECTOR U NOW CONTAINS PARAMETER ADJUSTMENT ----
  ---- ADD THEM TO VECTOR "PAR" -----
*****************
  do 40 i \approx 1, npar
        par(i) = par(i) - u(i)
40 continue
  sum = 0
  do 50 i= 1,ndata
        ytheo = theory(par,xvalue)
        sum = sum + (ydata(i) - ytheo) ** 2
50 continue
  return
  end
  real function theory(par,xvalue)
THIS FUNCTION CALCULATES A YVALUE FOR THE
×
  DISTRIBUTION
real par(*)
  sigma = par(2)
  x0 = par(1) / sigma
  x = xvalue / sigma
  t = (x * x0) / 3.75
  if (t.ge.1) then
     call bioget(x,x0,t,sigma,P)
    else
     call bivlt1(x,x0,t,sigma,P)
  endif
  theory = P
  return
  end
c
  subroutine bivge1(x,x0,t,sigma,P)
  real I
```

```
I=0.39894228+0.01328592/t+(0.002255319/(t*t))-(0.00157565/t**3)
           +(0.00916281/t**4)-(0.02057706/t**5)+(0.02635537/t:<6)
           -(0.01647633/t**7)+(0.00392377/t**8)
  I = I / sart(x * x0)
  P = ((x * I) / sigma) * exp(-((x - x0) * (x - x0)) / 2.)
  return
  end
C
  subroutine bivlt1(x,x0,t,sigma,P)
  real I
  I=1+3.5156229*t*t+3.0899424*t**4+1.2067492*t**6
          +0.2659732*t**8+0.0360768*t**10+0.0045810*t**12
  P = ((x * I) / sigma) * exp(-(x * x + x0 * x0) / 2.)
  return
  end
  subroutine deriv(par,xvalue,ytheo,dyda)
EVALUATE THE DERIVATIVES (DYDA) OF THE THE THEORY
  WITH RESEPCT TO THE ADJUSTMENT PARAMETERS.
real par(*), dyda(*), I1, I0, Iratio
  sigma = par(2)
  x = xvalue / sigma
  x\theta = par(1) / sigma
  z = x * x0
  Iratio = I1(z) / I0(z)
  dyda(1) = ytheo / sigma + (-x0 + x * Iratio)
  dyda(2) = 1. - (x*x+x0*x0)/2. + z * Iratio
  dyda(2) = -2. * ytheo / sigma * dyda(2)
  return
  end
  real function IO(z)
  real 10
  t = z / 3.75
  if (t.ge.1) then
      poly=0.39894228+0.01328592/t+0.002255319/(t*t)
             -0.00157565/t**3+0.00916281/t**4-0.02057706/t**5
            +0.02635537/t**6-0.01647633/t**7+0.00392377/t**8
      I0 = poly
      I0 = 1.+3.5156229*t*t+3.0899424*t**4+1.2067492*t**6
             + 0.2659732*t**8+0.0360768*t**10+0.0045813*t**12
  endif
```

```
return
  end
  real function I1(z)
  real I1
  t = z / 3.75
  if (t.ge.1) then
      poly=0.39894228-0.03988024/t-0.00362018/(t*t)
            +0.00163801/t**3-0.01031555/t**4+0.02282967/t**5
            -0.02895312/t**6+0.01787654/t**7-0.00420059/t**8
      I1 = poly
    else
      poly=0.5+0.87890594*t*t+0.51498869*t**4+0.15084934*t**6
            +0.02658733*t**8+0.00301532*t**10+0.00032411*t**12
      Ii = poly * z
  endif
  return
  end
  subroutine qminv(a,n,d,1,m)
SUBROUTINE MINV
       PURPOSE
          INVERT A MATRIX
       USAGE
          CALL MINU(A,N,D,L,M)
       DESCRIPTION OF PARAMETERS
          A - INPUT MATRIX, DESTROYED IN COMPUTATION AND REPLACED BY
              RESULTANT INVERSE.
          N - ORDER OF MATRIX A
          D - RESULTANT DETERMINANT
          L - WORK VECTOR OF LENGTH N
          M - WORK VECTOR OF LENGTH N
       REMARKS
          MATRIX A MUST BE A GENERAL MATRIX
        SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED
          NONE
       METHOD
          THE STANDARD GAUSS-JORDAN METHOD IS USED. THE DETERMINANT
          IS ALSO CALCULATED. A DETERMINANT OF ZERO INDICATES THAT
          THE MATRIX IS SINGULAR.
```

認

```
dimension a(1), l(1), m(1)
IF A DOUBLE PRECISION VERSION OF THIS ROUTINE IS DESIRED, THE
       C IN COLUMN 1 SHOULD BE REMOVED FROM THE DOUBLE PRECISION
       STATEMENT WHICH FOLLOWS.
    double precision a,d,biga,hold,dabs
       THE C MUST ALSO BE REMOVED FROM DOUBLE PRECISION STATEMENTS
       APPEARING IN OTHER ROUTINES USED IN CONJUNCTION WITH THIS
       ROUTINE.
       THE DOUBLE PRECISION VERSION OF THIS SUBROUTINE MUST ALSO
       CONTAIN DOUBLE PRECISION FORTRAN FUNCTIONS. ABS IN STATEMENT
       10 MUST BE CHANGED TO DABS.
**************************
       SEARCH FOR LARGEST ELEMENT
************************
  d=1.0
  nk=-n
  do 80 k=1,n
         nk=nk+n
         1(k)≈k
         m(k)=k
         kk=nk+k
         biga=a(kk)
         do 20 j=k,n
               iz=n*(j-1)
               do 20 i=k,n
                      ij≈iz+i
  10
                            if( abs(biga) - abs(a(ij))) 15,20,20
  15
                            biga=a(ij)
                      1(k)=i
                      m(k)=j
  29
               continue
*********
         ---- INTERCHANGE ROWS ----
*************************
         j=1(k)
         if(j-k) 35,35,25
  25
               k i = k - n
         do 30 i=1,n
               ki=ki+n
               hold=-a(ki)
```

```
ji=ki~k+j
               a(Ki)≈a(ji)
  30
                     a(ji) =hold
                 **************
            INTERCHANGE COLUMNS ----
***************
  35
               i=m(k)
        if(i-k) 45,45,38
               jp=n*(i-1)
  38
        do 40 j=1.n
               jk=nk+j
               j i = jp + j
               hold=-a(jk)
               a(jk)≈a(ji)
                     a(ji) =hold
  40
        DIVIDE COLUMN BY MINUS PIVOT (VALUE OF PIVOT
        ELEMENT IS CONTAINED IN BIGA)
45
               if(biga) 48,46,48
               d=0.0
  46
        return
  48
               do 55 i=1,n
               if(i-k) 50,55,50
  50
                     ik=nk+i
               a(ik)=a(ik)/(-biga)
  55
               continue
        ---- REDUCE MATRIX ----
<del>```````````</del>
        do 65 i=1.n
               ik=nk+i
               hold=a(ik)
               ij=i-n
               do 65 j=1,n
                      i,i=i,j+n
                      if(i-k) 60,65,60
  60
                            if(j-k) 62,65,62
                            kj=ij-i+k
  62
                      a(ij)=hold*a(kj)+a(ij)
  65
               continue
```

THE RESERVE

---- DIVIDE ROW BY PIVOT ----

```
**************************
       k_i = k - n
       do 75 j=1,n
             k_j = k_j + n
             if(j-k) 70,75,70
 70
                   a(kj)=a(kj)/biga
  75
             continue
***********
       ---- PRODUCT OF PIVOTS ----
×
d=d*biga
  ************************
       ---- REPLACE PIVOT BY RECIPROCAL ----
*************************
       a(kk)=1.0/biga
  80
       continue
********************************
         FINAL ROW AND COLUMN INTERCHANGE ----
K=n
 ~i00
       k=(k-1)
  if(k) 150,150,105
       i=1(k)
 105
  if(i-k) 120,120,108
 108
       jq=n*(k-1)
  jr=n*(i-1)
  do 110 j=1,n
       jk=jq+j
       hold=a(jk)
       ji=jr+j
       a(jk)=-a(ji)
 110
             a(ji) =hold
 120
       j=m(K)
  if(j-k) 100,100,125
 125
       ki = k - n
  do 130 i=1,n
       ki=ki+n
       hold=a(ki)
        ji=K_1-K+j
        a(ki)=-a(ji)
 130
             a(ji) = hold
  go to 100
 150
       return
```

```
· end
```

```
subroutine omprd(a,b,r,n,m,1)
<del>*****************************</del>
        SUBROUTINE GMPRD
        PURPOSE
          MULTIPLY TWO GENERAL MATRICES TO FORM A RESULTANT GENERAL
          MATRIX
        USAGE
           CALL GMPRD(A,B,R,N,M,L)
        DESCRIPTION OF PARAMETERS
           A - NAME OF FIRST INPUT MATRIX
           B - NAME OF SECOND INPUT MATRIX
           R - NAME OF OUTPUT MATRIX
           N - NUMBER OF ROWS IN A
           M - NUMBER OF COLUMNS IN A AND ROWS IN B
           L - NUMBER OF COLUMNS IN B
        REMARKS
           ALL MATRICES MUST BE STORED AS GENERAL MATRICES
           MATRIX R CANNOT BE IN THE SAME LOCATION AS MATRIX A
           MATRIX R CANNOT BE IN THE SAME LOCATION AS MATRIX B
           NUMBER OF COLUMNS OF MATRIX A MUST BE EQUAL TO NUMBER OF ROW
           OF MATRIX B
        SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED
           NONE
        METHOD
           THE M BY L MATRIX B IS PREMULTIPLIED BY THE N BY M MATRIX A
           AND THE RESULT IS STORED IN THE N BY L MATRIX R.
dimension a(1),b(1),r(1)
   ir=0
   ik=-m
   do 10 K=1,1
          ik≈ik+m
          do 10 j=1,n
                  in-in+1
                  ji≕j−n
                  ib=ik
                  r(ir)=0
                  do 10 i=1,m
                         ji=ji+n
```

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```
ib=ib+1
  10
                               r(ir)=r(ir)+a(ii)*b(ib)
  return
  end
  subroutine plotdat(xm,ym,xt,yt,device,ndata,npts)
*************************
  Subroutine to Plot Measured Data With Theory
******************************
  include "/usr/include/libmp.f"
  integer*4 gls(sizeofgca)
  character*64 device
  real xm(*),ym(*),xt(*),yt(*)
  integer bun(2), lin(2)
  bun(1) = 0
  bun(2) = 66
  lin(1) = 1
  lin(2) = 0
  if (device.eq."screen") call system("clearop")
  call mpinit(qls)
  call mplotsrcx(gls,i,ndata,0,xm,"F",i,i,null,null)
call mplotsrcy(gls,i,ndata,0,ym,"F",1,i,null,null)
  call mplotsrcx(gls,2,npts,0,xt,"F",i,i,null,null)
  call mplotsrcy(gls,2,npts,0,yt,"F",1,1,null,null)
  call mplotchrs(gls, "*",1,nullintray,nullintray)
  call mplines(gls,2,bun,lin)
  if (device.eq."screen") then
      call mpdevice(gls, "mcd", 2,0)
      call mpdevice(qls, "hpql0", 2,0)
  endif
  call mplot(gls.0.0.0)
  call mpend(qls)
  read*,wait
  if (device.eq."screen") call system("clearqp")
  return
  end
  subroutine otheory (xt,yt,par,npts)
---- CALCULATES THE THEORETICAL CURVE ----
real xt(*), yt(*), lolim, uplim, par(*), incr. diff
  real theory
```

```
print *, "upper limit"
  read *, uplim
  print *, "lower limit"
  read *, lolim
  diff = uplim - lolim
  incr = diff / (npts - 1)
  xt(1) = lolim
  yt(1) = theory(par,xt(1))
  do 100 i = 2, npts
        xt(i) = xt(i-1) + incr
        yt(i) = theory (par,xt(i))
100
        continue
  return
  end
  subroutine integrate(xdata,ydata,ndata)
*************************
  INTEGRATES THE DATA USING THE TRAPOZID METHOD
¥.
**************************
  real xdata(*), ydata(*)
  area = 0.
  do 10 i = 1, ndata - 1
         dx = xdata(i+1) - xdata(i)
         avghi = (ydata(i+1) + ydata(i)) / 2.
         area = area + dx * avghi
10 continue
************************
  ---- NORMALIZE THE DATA NOW ----
do 20 i = 1, ndata
         ydata(i) = ydata(i) / area
20 continue
  return
  end
```

 Ω

```
program stordat
      character*64 root, xroot, yroot
      print*, "Input root for data file"
      read*,root
      xroot = "x"//root
      yroot = "y"//root
      open(1,file=xroot,status="new")
      open(2,file=yroot,status≈"new")
      print*, "Input number of points"
      read*, npoints
      print*,"Input position of peak in dB"
      read*,pdb
      print*,"Input position of peak from scale"
      read*,pscale
      print*,"Input height of peak"
      read*,height
      print*,"Input position of reference peak in dB"
      read*,prefdb
      scale = 1. / height
      Pref = 10**(prefdb / 20.)
      do 30 i = 1, npoints
        print*,"Input x",i,",y",i
        read*,p,prob
        xdb = pdb + 20. * logi0(p / pscale)
        x = 10**(xdb / 20.) / Pref
        y = prob * scale
        write(1,*) x
        write(2,*) y
30
      continue
      stop
      end
```

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```
This program creates the data for constructing
c
     a scatter plot
c
c
     program scatter
      open(1,file="phase.dat")
      open(2,file="ampl.dat")
      open(3,file="xfile")
      open(4,file="yfile")
      open(20,file="limits")
      rewind 1
      rewind 2
      xmax=-100000
      xmin=100000
      ymax=-100000
      ymin=100000
      conv = 3.14159/180.
10
    read(1,*,end=20) phase
      read(2,*,end=20) amp1,amp2
     if (ampi.ne.0.and.amp2.ne.0.) then
      amp = abs(amp1 / amp2)
    _____
      Convert the data from rectangular
C
     to polar coordinates
        x = amp * cos(phase * conv)
       y = amp * sin(phase * conv)
      Find the range of the data
        xmax = amax1(x,xmax)
        ymax = amax1(y,ymax)
        xmin = amin1(x,xmin)
        ymin = amin1(y,ymin)
        write(3,*) \times
        write(4,*) y
      endif
      go to 10
      xmax = amax1(abs(xmax),abs(xmin))
20
      ymax = amaxi(abs(ymax),abs(ymin))
      xmin = -xmax
      ymin = -ymax
      write(20, €) xmax,xmin,ymax,ymin
      stop
      end
```

```
******************
C
     c
c
                      nuphazscat.f
               Finds the amplitude and phase
     ******
C
                  difference between two
C
     *****
                   different channels.
     *****
C
               For use in the scatter program
C
     ****
                                           *****
     *******************
     ************
c
     program nuphazscat
     integer hiwin, i, iblk, ch1, ch2, dgfreq, ipts, j
     integer k, lowin, n1, n2, xcycl1, xcycl2, nk
     integer npass, numch
               data(1024,2)
     integer*2
           areal, area2, bias1, bias2
     real
           data1(1024), data2(1024), lastp1, lastp2
     real
           noise1, noise2, phasinc, phastot, pi
     real
           period, sumtim, tsampl, timkp1, timkp2
     real
           time(1024,2), phase(2048), ampl(1024,2)
     parameter (pi=3.141592654)
     open(1,file='holder',status='old')
     open(2,file='ampl.dat')
     open(4,file='phase.dat')
     open(20,file='data',access='direct',recl=2)
     rewind 1
     read(1,*), numch
     read(1,*),dgfreq
     read(1,*), ipts
     read(1,*),chi
     read(1,*),ch2
     tsamp1 = 1 / float(dgfreq)
     npass = ipts / (numch * 1024)
     xcycli = 0
     xcyc12 = 0
     lastol = 0.
     lastp2 = 0.
     areal = 0.
     area2 = 0.
     phastot = 0.
     iblk = 0
     nk = 0
     <del>*********************</del>
     ** Read In 1024 Points From Each Channel **
     ** Skip First Hundred Points
     lowin = ch1 + nk ★ numch + 100 ★ numch
10
```

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```
hiwin = ch1 + (nk + 1023) * numch + 100 * numch
    j = 1
    do 2 i=lowin, hiwin, numch
       read(20, rec=i), data(j, 1)
       read(20, rec=i+ch2-ch1), data(j,2)
       j = j + 1
2
    continue
    nk = nk + 1024
     *****************
C
          Determine DC Bias (Just Average Over
C
          Complete Cycles, 1020 instead of 1024)
                                           ****
C
     <del>***********************</del>
c
    bias1 = 0.0
    bias2 = 0.0
     do 15 i=1,1020
       biasi = biasi + float(data(i,1))
       bias2 = bias2 + float(data(i,2))
15
     continue
    biasi = biasi / 1020.
    bias2 = bias2 / 1020.
     *************
_
     ** Remove DC Bias **
     *******
C
     do 20 i = 1, 1024
       data1(i) = data(i,1) - bias1
       data2(i) = data(i,2) - bias2
20
     continue
c
     ni=xcycli+i
     n2=xcyc12+1
     *<del>******************</del>
c
     ***** Determine Local Zeroes For Channels 1 & 2 *****
C
     call cycle(1,data1,n1,lastp1,timKp1,area1,time,amp1,
                  tsamp1)
     n1=n1-1
     call cycle(2,data2,n2,lastp2,timkp2,area2,time,ampl.
                  tsamp1)
     n2=n2-1
     ************
C
                                    ****
c
           Zero Crossings are now in
           Time Array. Compute Period
c
     sumtim = 0.0
     do 65 i = 1, n1
           sumtim = sumtim + time(1,1)
65
     continue
     period = 2. * sumtim / float(n1)
     ********
C
           Check Signal to Noise Ratio for this Block
                                                ***
C
```

```
C
     noisei=float(nzeri)/float(ni)*100.
     noise2=float(nzer2)/float(n2)*100.
     if (noise1.1t.5.) then
          if (noise2.1t.5.) then
            *********
C
                  Compute Phase
C
            *********
C
               phasinc=(time(1,1)-time(1,2))/period*360.
               phase(1)=phastot+phasinc
               k=min0(n1,n2)
               do 70 i=2.k
                 phasinc=(time(i,1)-time(i,2))/period#360.
                  phase(i)=phase(i-1)+phasinc
70
               continue
               do 75 i=1.k
                  if (iblk.eq.0.and.i.eq.1) go to 75
                  write(2,*)ampl(i,1),ampl(i,2)
                  write(4,*)phase(i)
75
               continue
               phastot=phase(K)
               print*,'Ch 2. Too Noisy. Skip Data. Hold Phase.'
          endif
        el se
          print*,'Chi. Too Noisy. Skip Data. Hold Phase.'
     endi f
     iblk=iblk+1
     if (iblk.ge.npass) go to 95
     xcycl1 = 0
     xcyc12 = 0
     if (n2.qt.n1) then
         C
¢
              More Cycles on Ch 2
        *********
        xcyc12=n2-n1
        do 85 i=1,xcyc12
          time(i,2)=time(n1+i,2)
          ampl(i,2)=ampl(ni+i,2)
85
        continue
     endif
     if (n1.gt.n2) then
        C
c
              More Cycles on Ch i
                                ****
        C
        xcycli=n1-n2
        do 90 i=1,xcycl1
          time(i,1)=time(n2+i,1)
          ampl(i,1)=ampl(n2+i,1)
90
        continue
```

```
endif
    go to 10
95
    stop
    end
C
C
    ***********
C
    ** Finds the Zero Crossing Between **
c
           (0,y1) And (dx,y2)
c
    C
    real function zerox(y1,y2,dx)
          y1, y2, slope, dx
    real
    slope = (y2 - y1) / dx
    zerox = -y1 / slope
    return
     end
C
c
     subroutine cycle(nch,data,ncyc,lastpt,timekp,area,
                  time, ampl, tsampl)
     ************
C
        Processes Cycles in Each Block of 1024 Points
ς
        Records Time and Amplitude of each 1/2 cycle
                                               **
C
     ******************
C
c
     integer
             i, neye, nch
             amp1(1024,2), time(1024,2), data(1024)
     real
     real
             aftime, zerox, thispt, lastpt, prod, timekp, tsampl
     real
             pi, area
     parameter (pi=3.141592654)
C
     do 10 i=1,1024
        thispt=float(data(i))
       prod = thispt*lastpt
        if (prod.ge.0) then
          *********
C
          ***** Same Side of Zero
                               ****
c
          C
          timekp = timekp + tsampl
          area = area + tsampl*(thispt+lastpt)/2
          if (thispt.eq.0) then
c
             *********
             ***** Hit Zero Exactly ****
C
             time(ncyc,nch) = timekp
             amp1(ncyc,nch) = (pi*area)/(2*timekp)
            ncyc = ncyc + 1
             timekp = 0
             area = 0
          endif
```

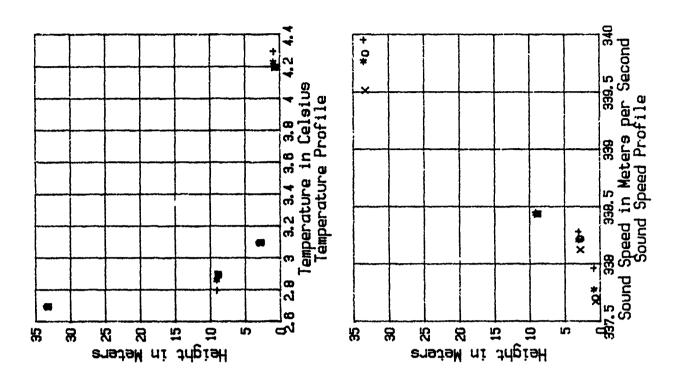
 \aleph

```
else
C
         C
         ***** Crossed Zero -- End of 1/2 Cycle *****
C
         *******************
         aftime = zerox(lastpt,thispt,tsampl)
         timeKp = timeKp + aftime
         area = area + lastpt*aftime/2
         time(ncyc,nch) = timekp
         ampl(ncyc,nch) = (pi*area)/(2*timekp)
         ncyc = ncyc + 1
         ***********************************
C
         **** Get Prepared For Next 1/2 Cycle *****
C
         ****************
         timekp = tsamp1 - aftime
         area = thispt*timekp/2
       endif
       *************
c
       ***** Remember This Data Point ****
       *********
       lastpt = thispt
10
    continue
C
    return
    end
```

APPENDIX C

五二五

Plots of the meteorological parameters measured during the experiment.

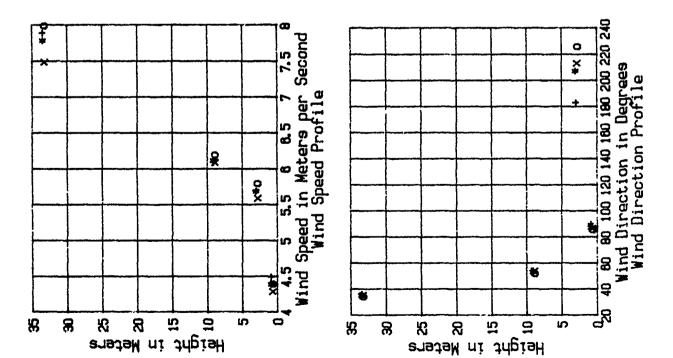


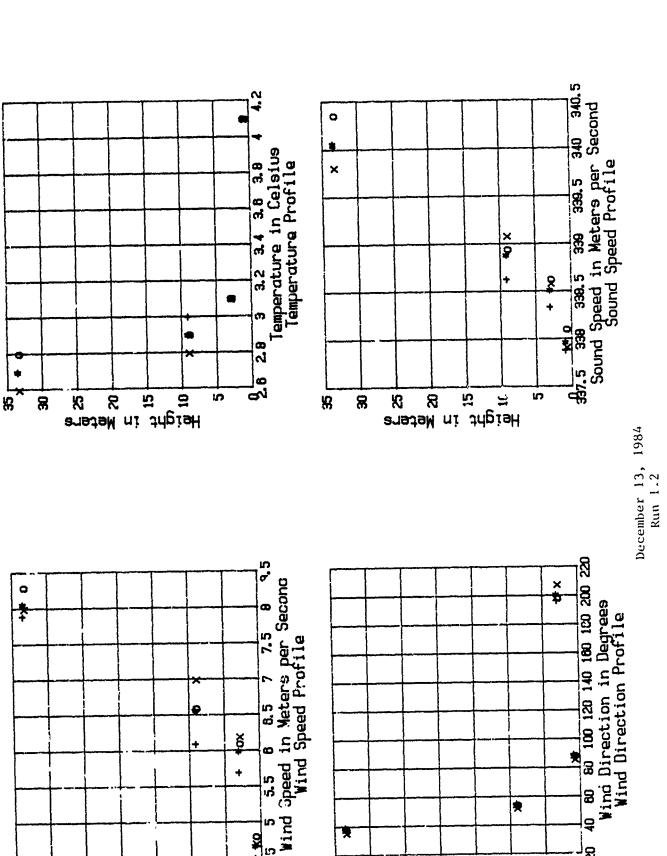
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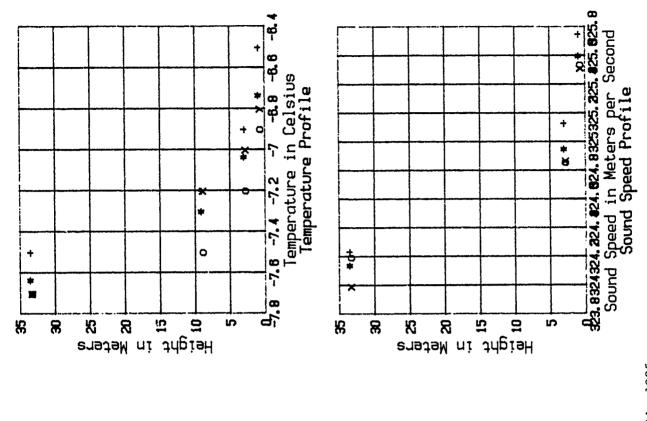
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Wind Speed in Meters per Second Wind Speed Profile

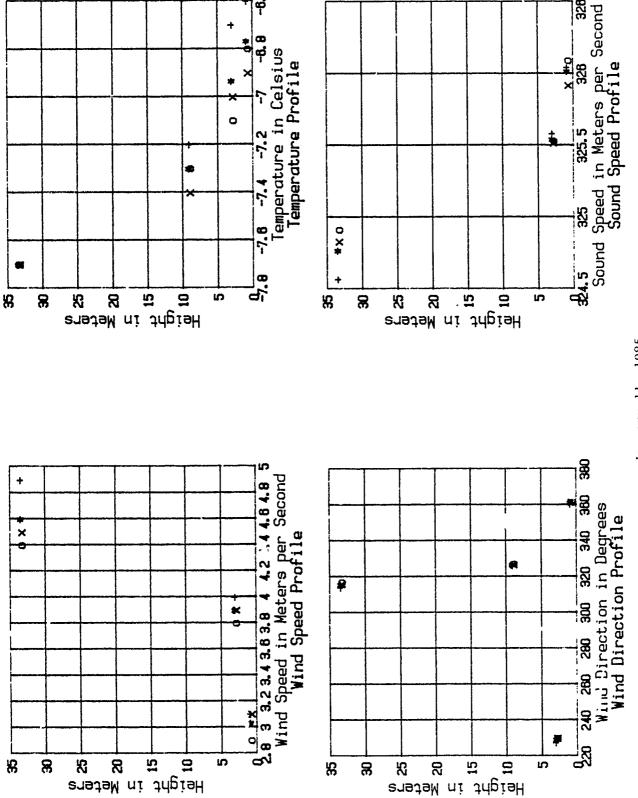
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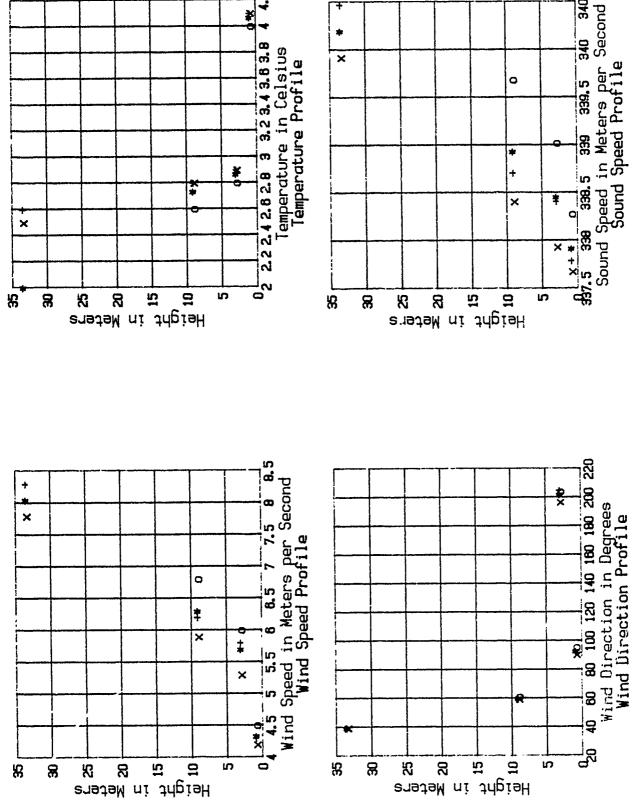
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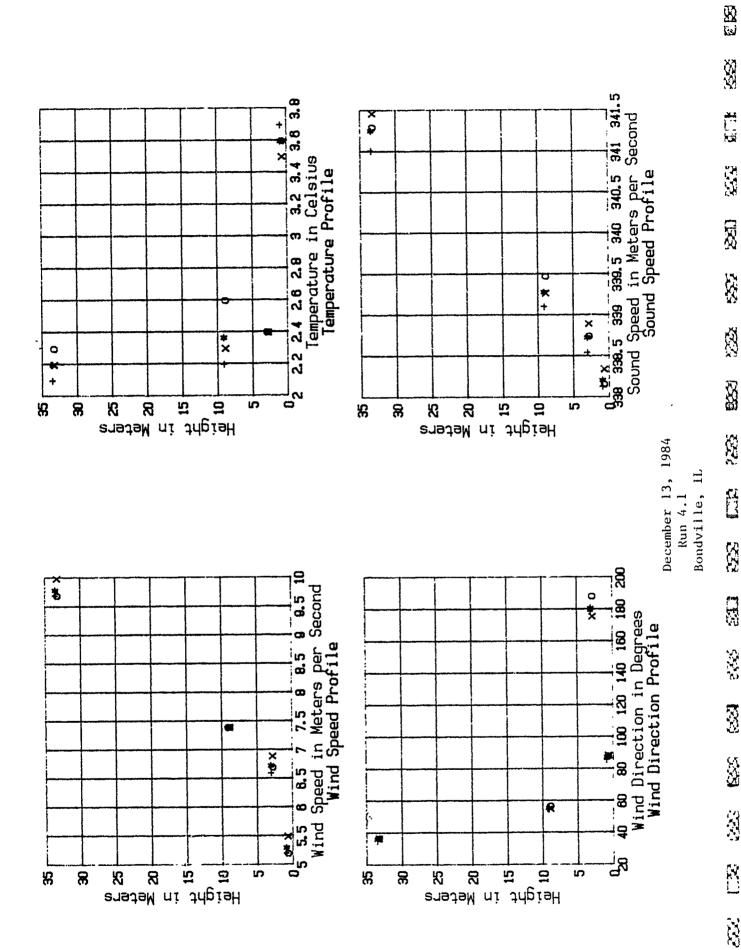
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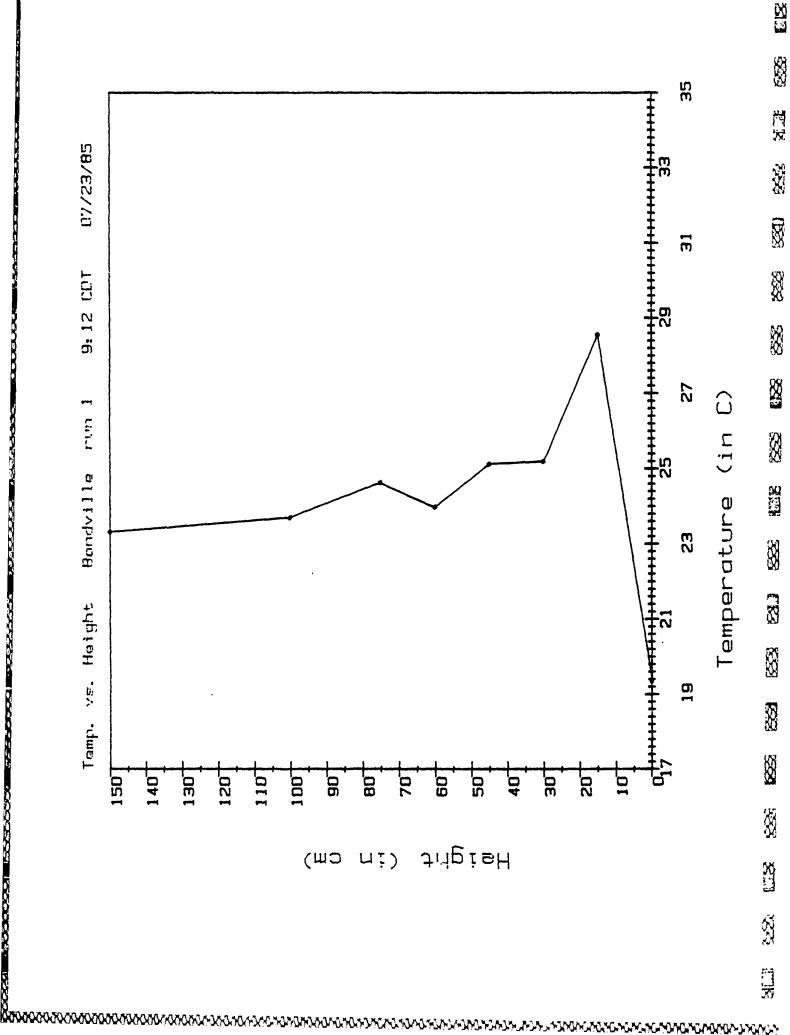
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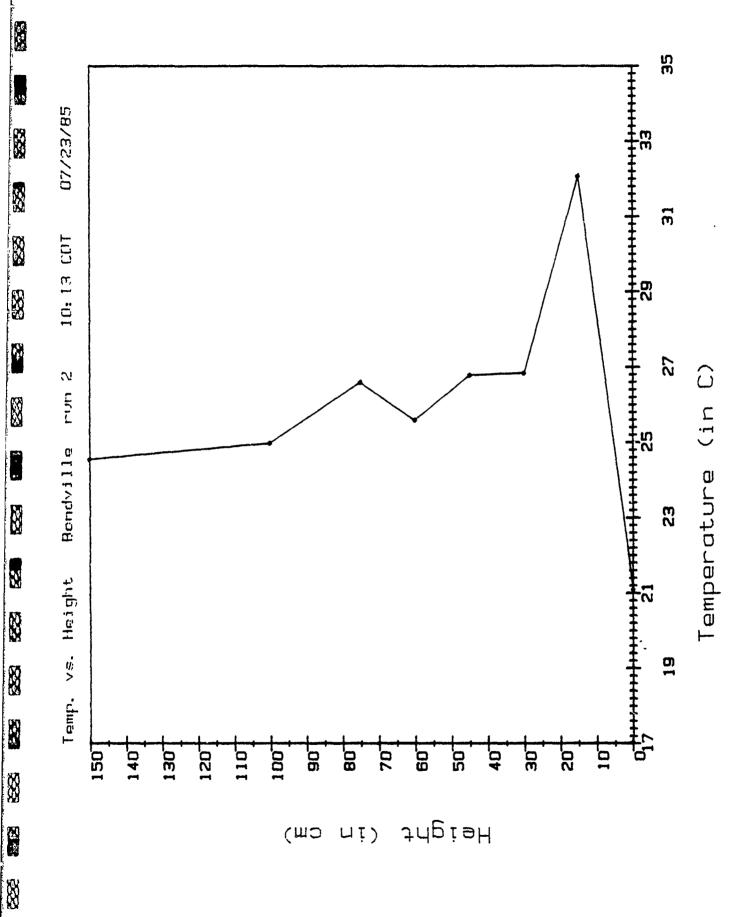
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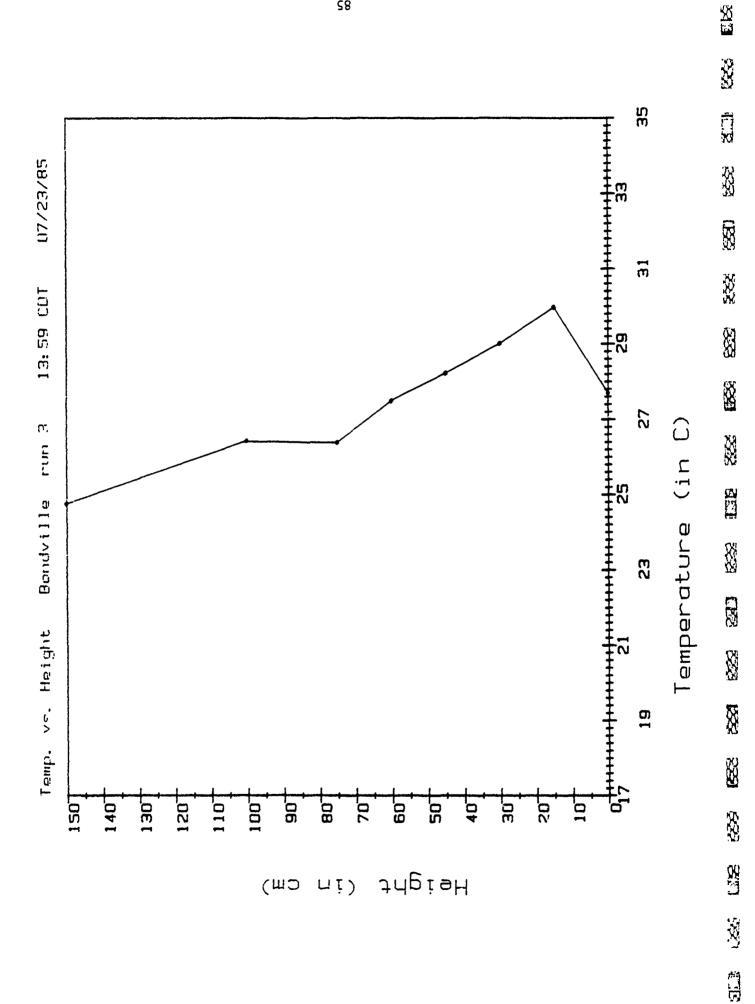
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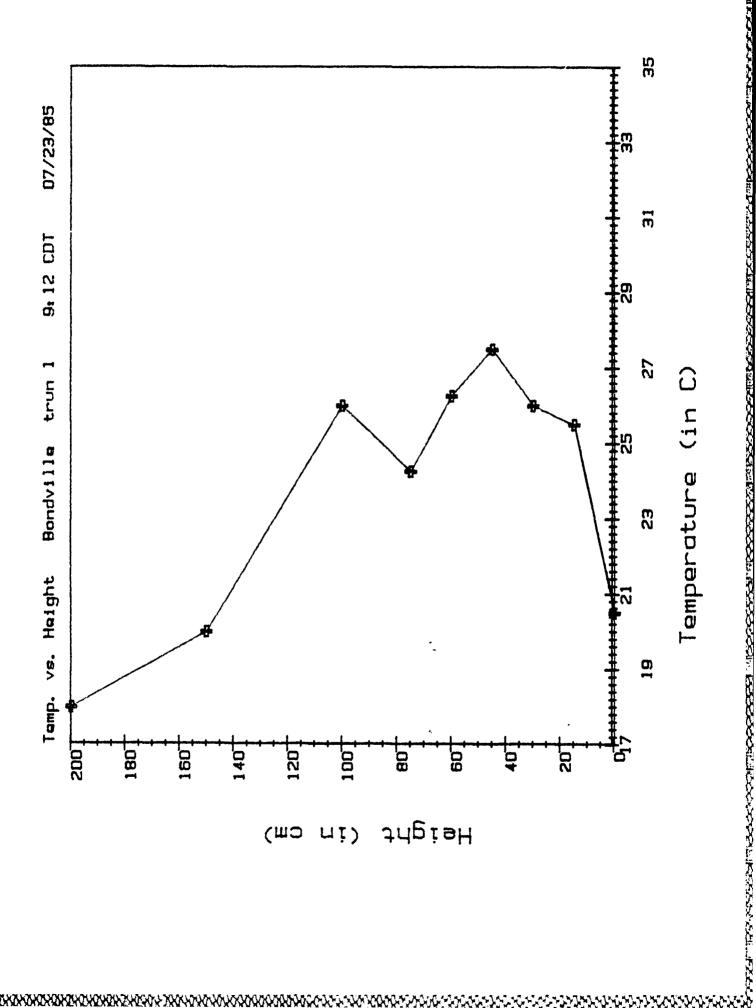


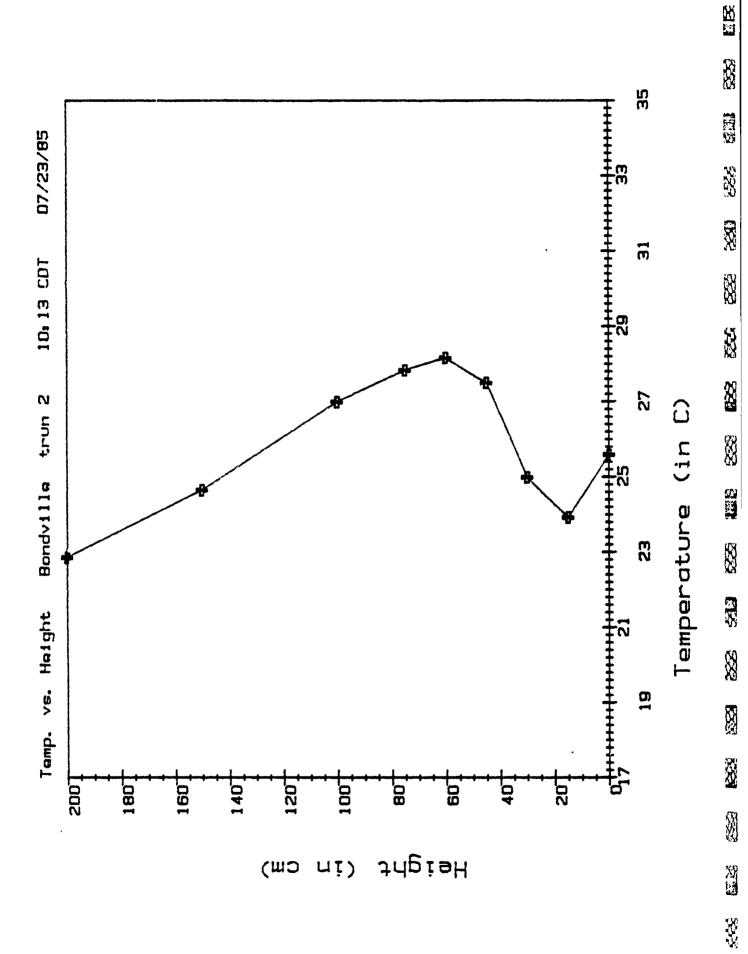


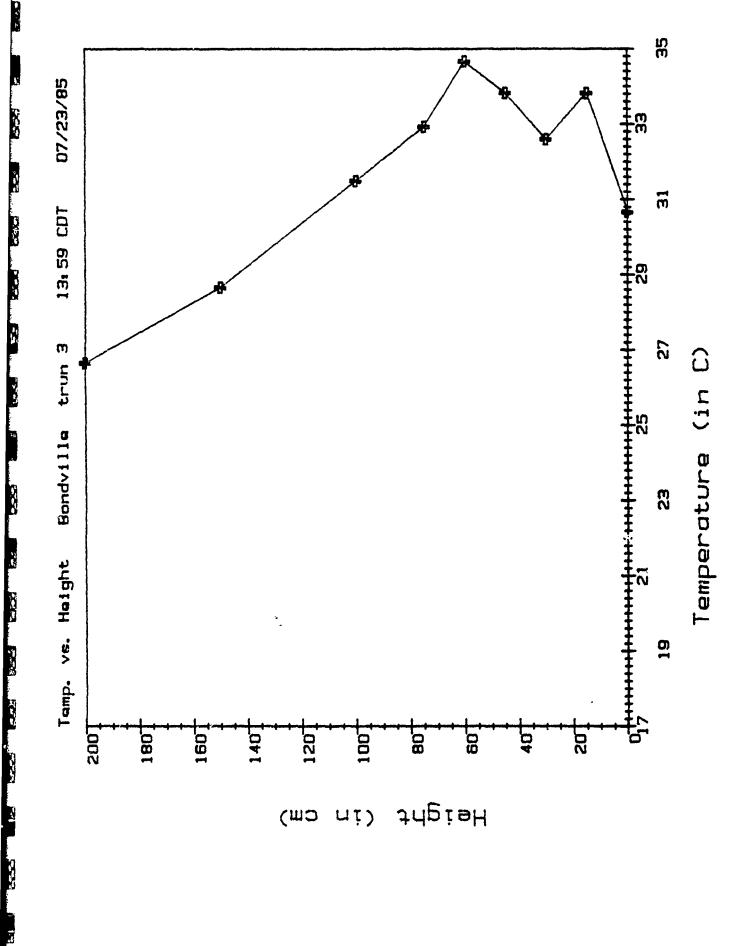


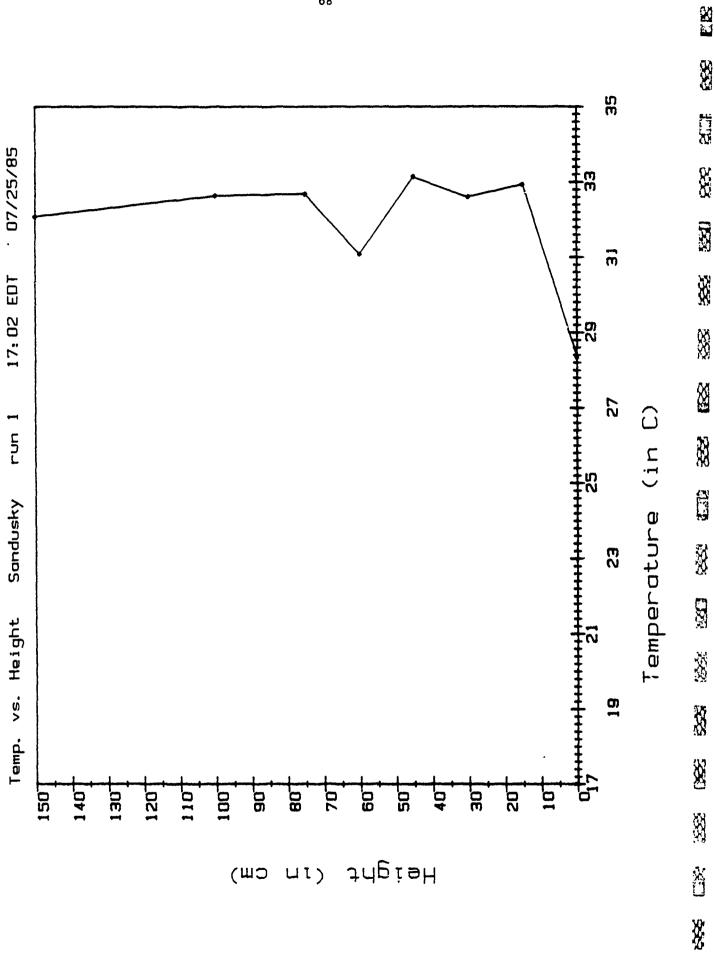
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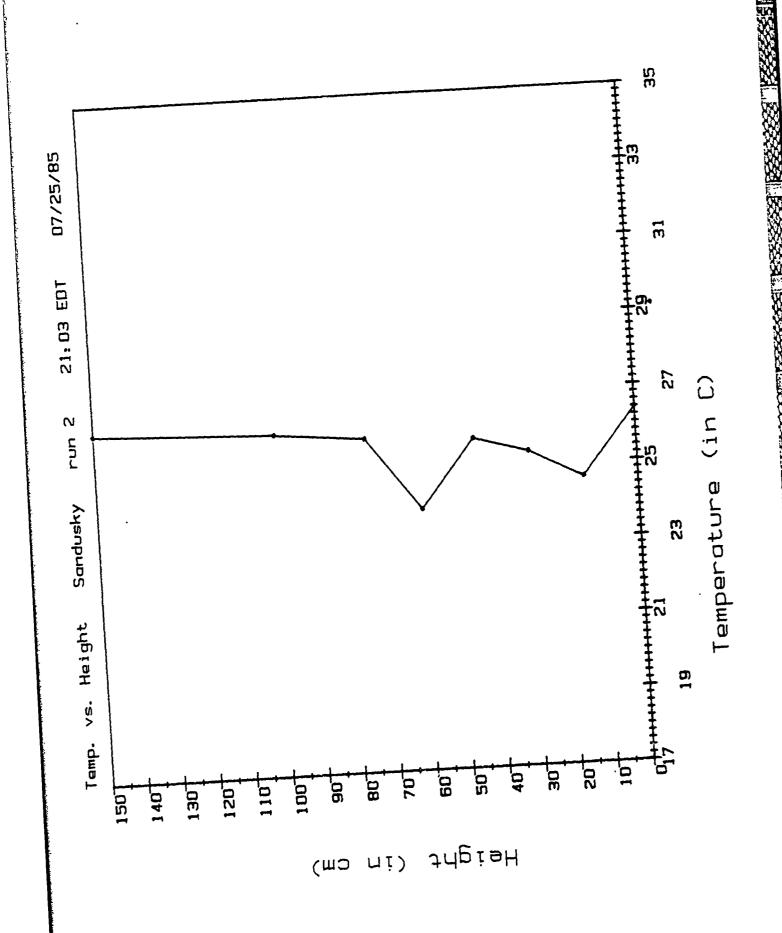
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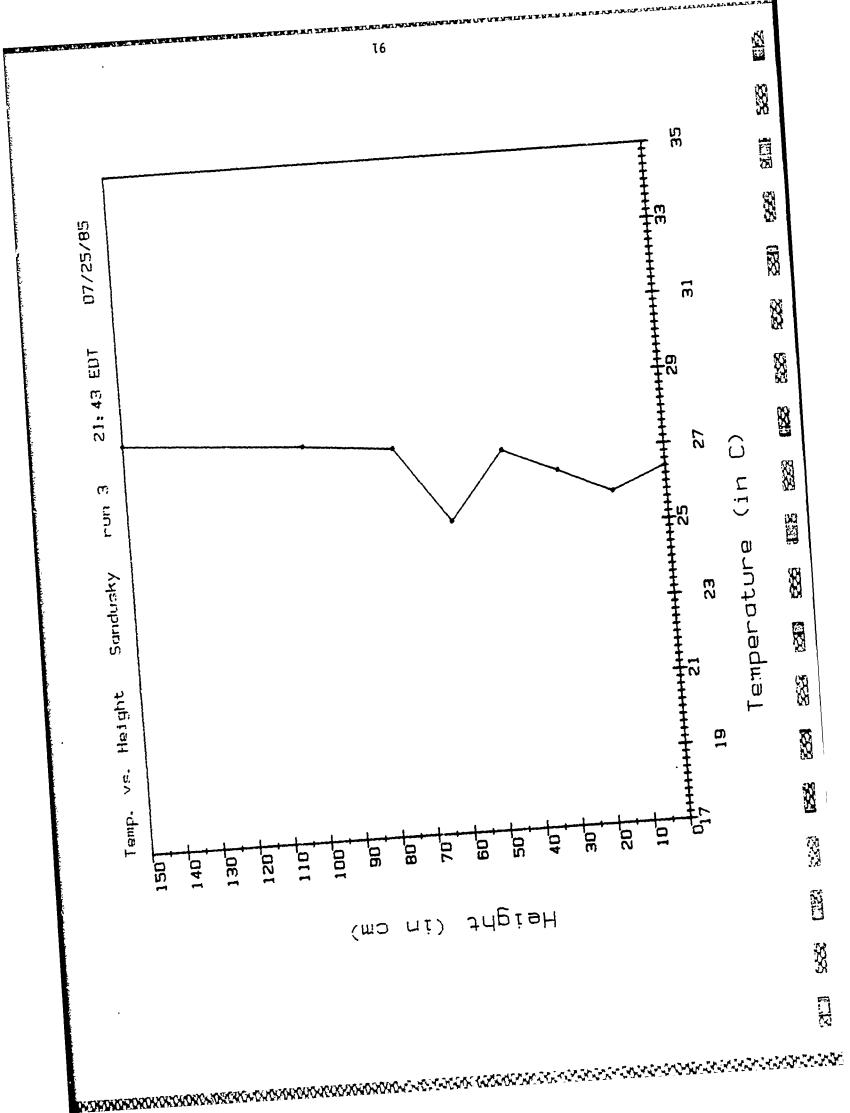




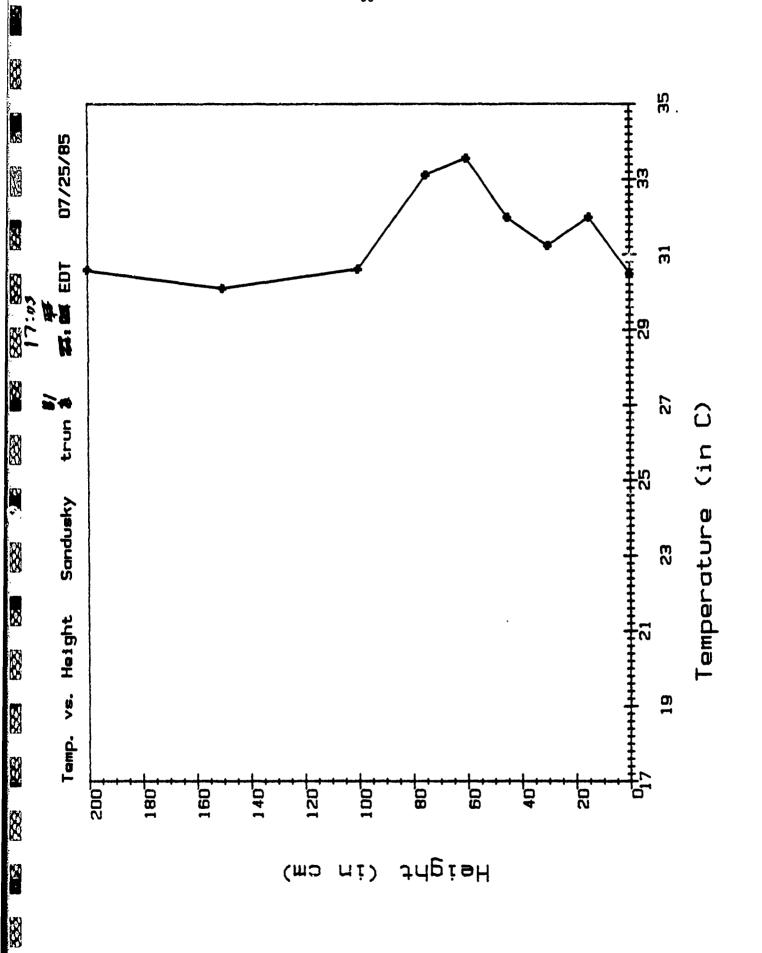


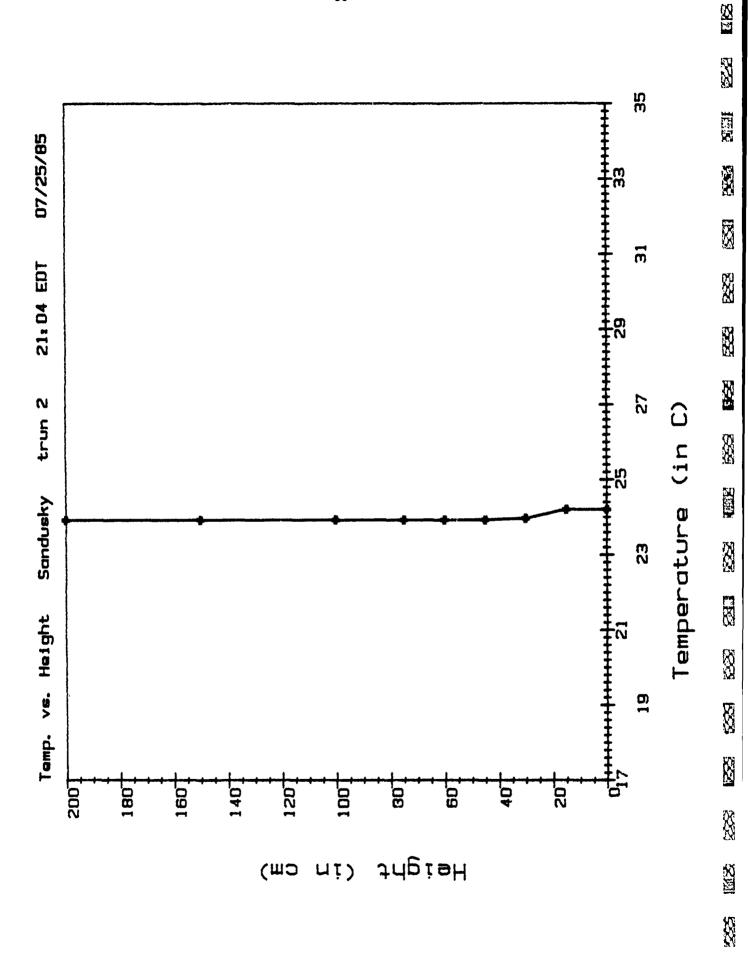






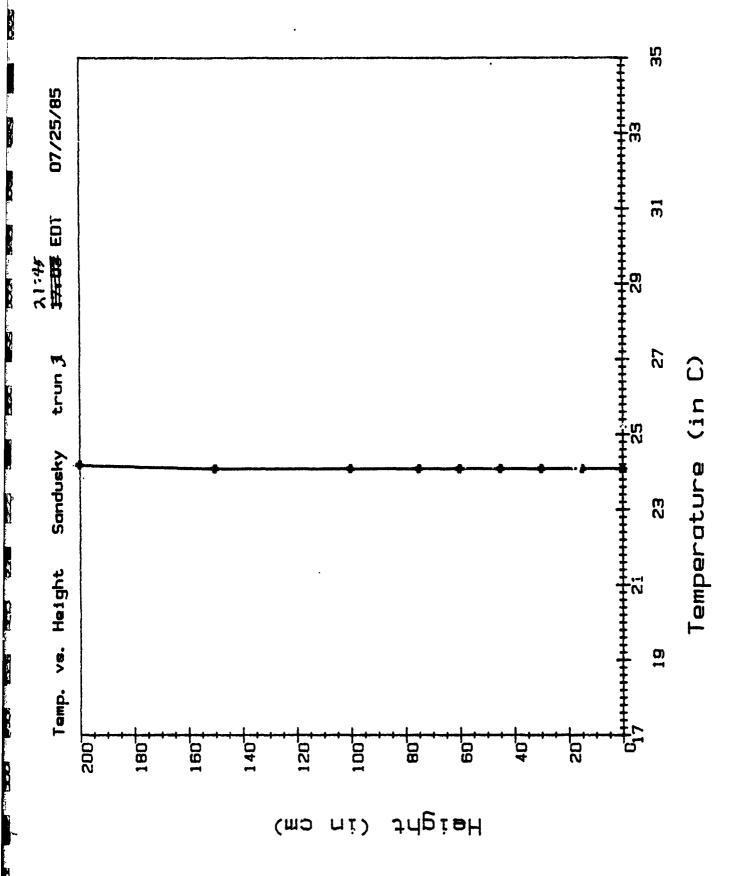


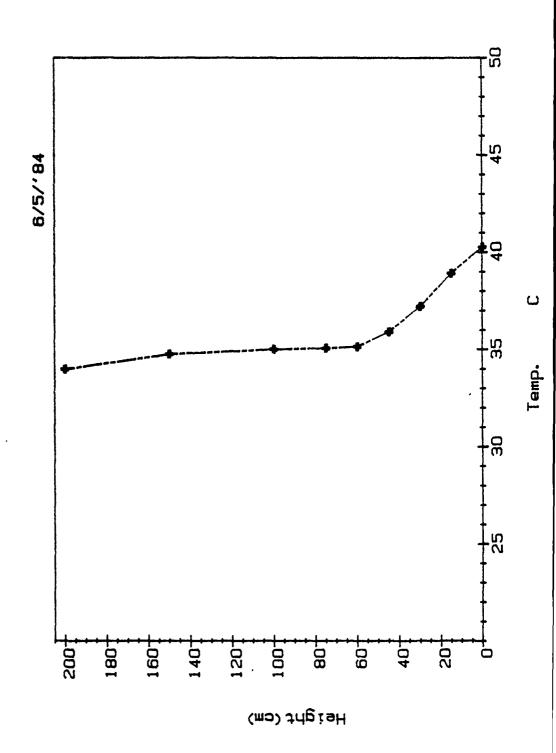


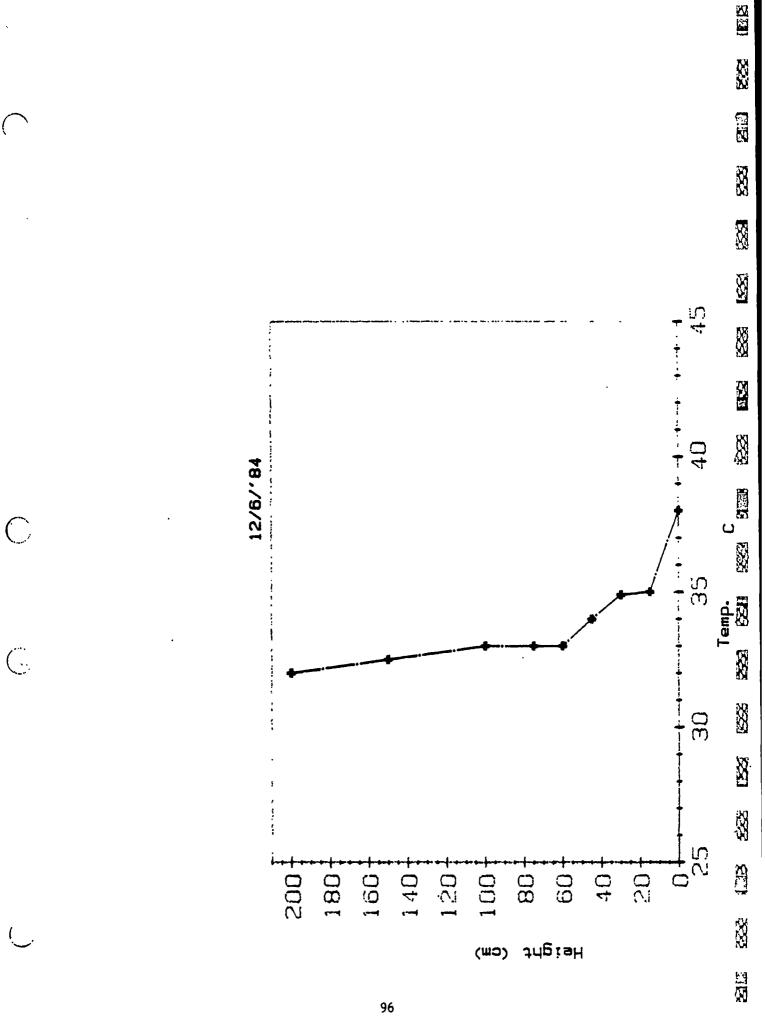


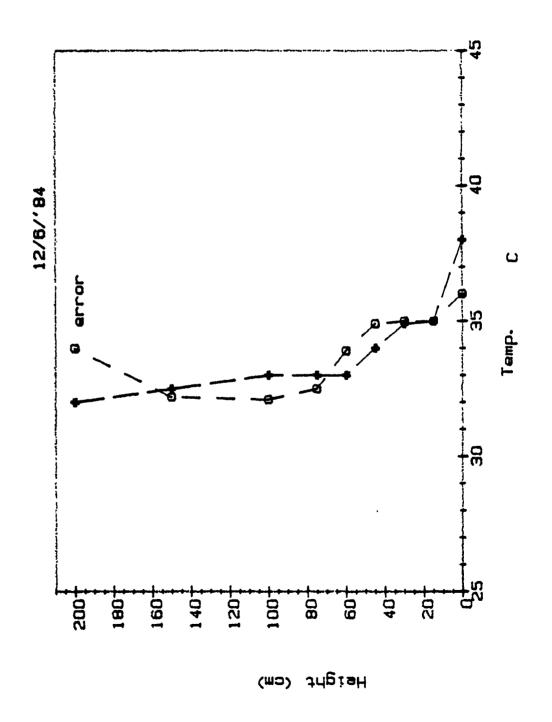
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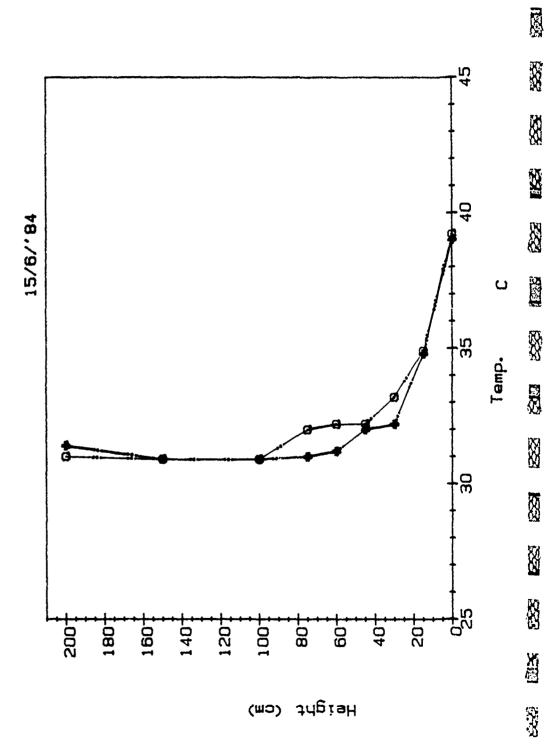
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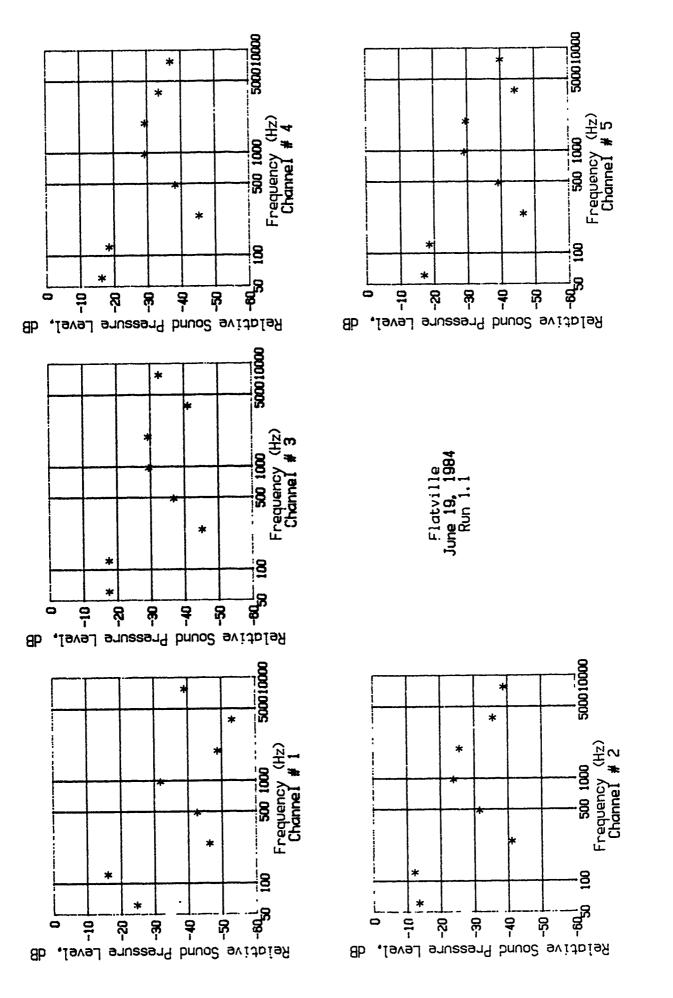


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APPENDIX D

Plots of the relative sound pressure level for each microphone and each experiment.



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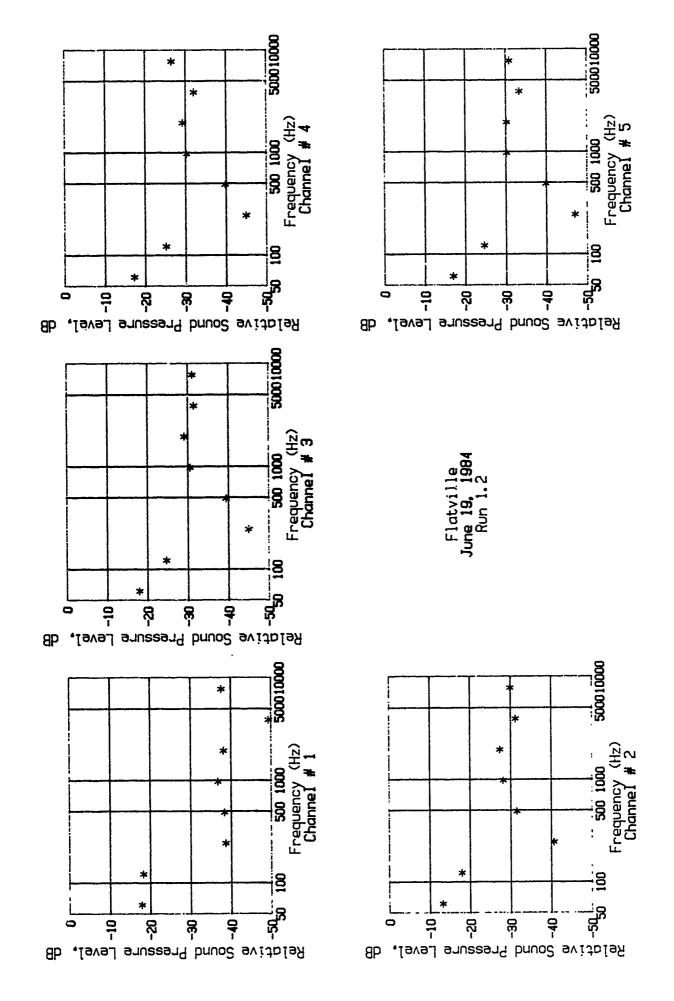
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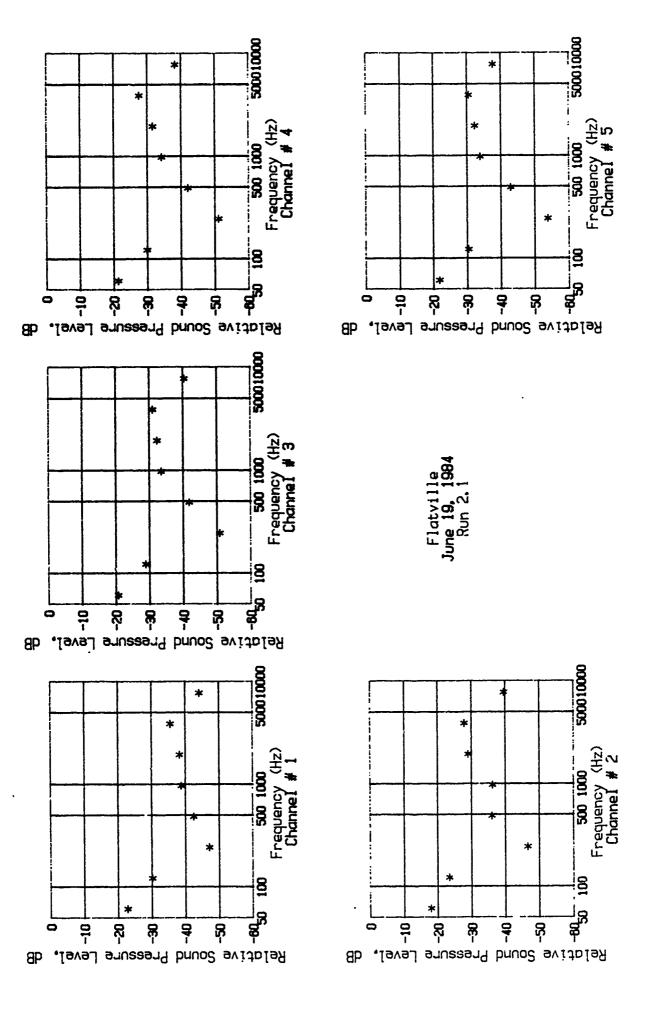
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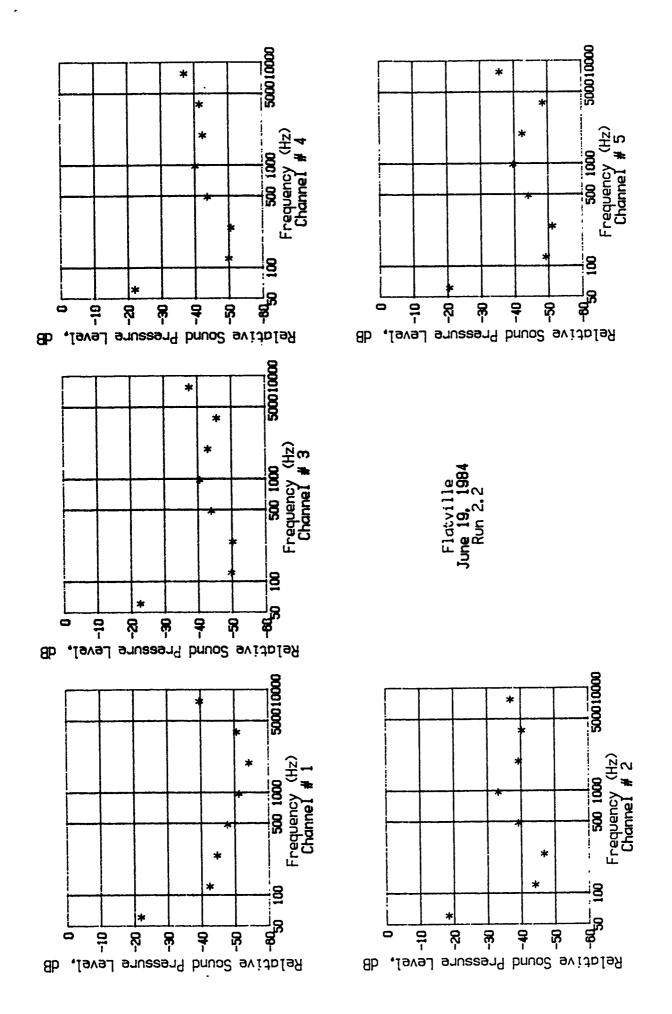
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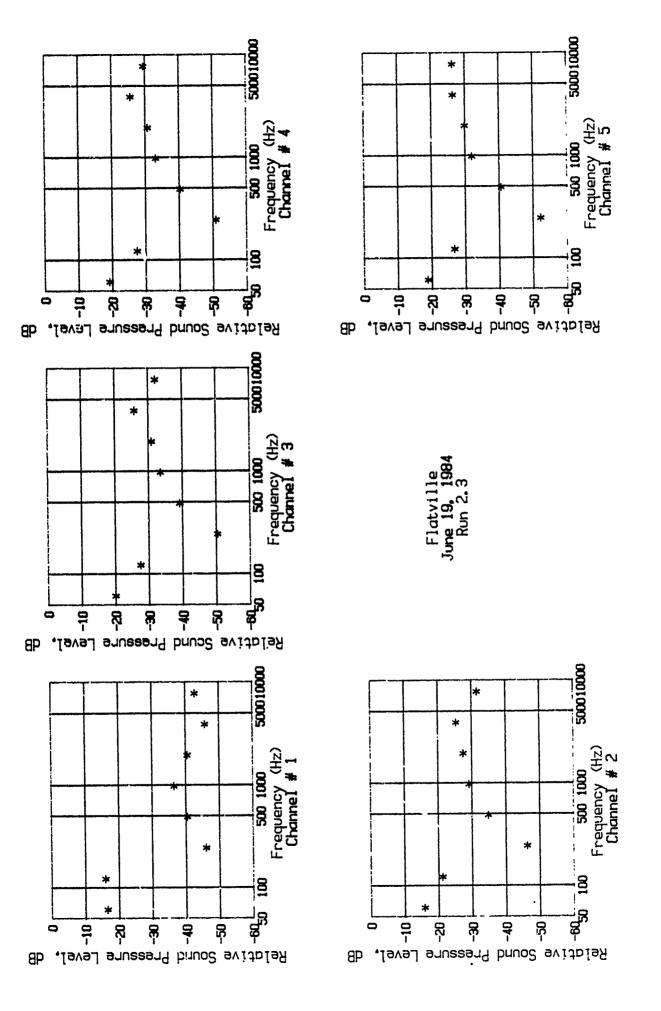
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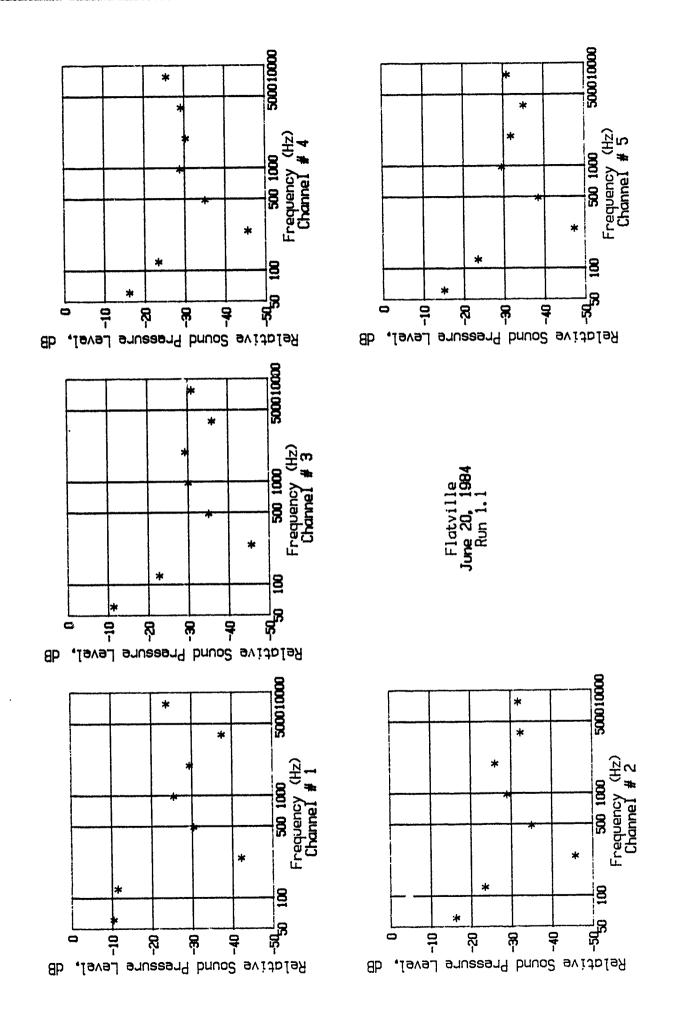
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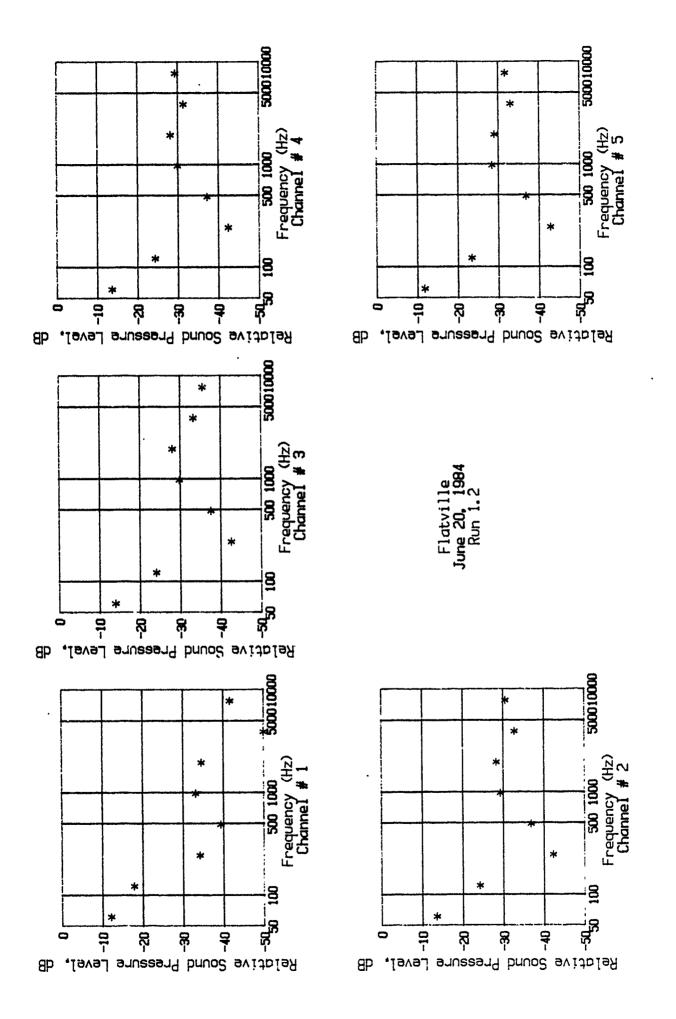
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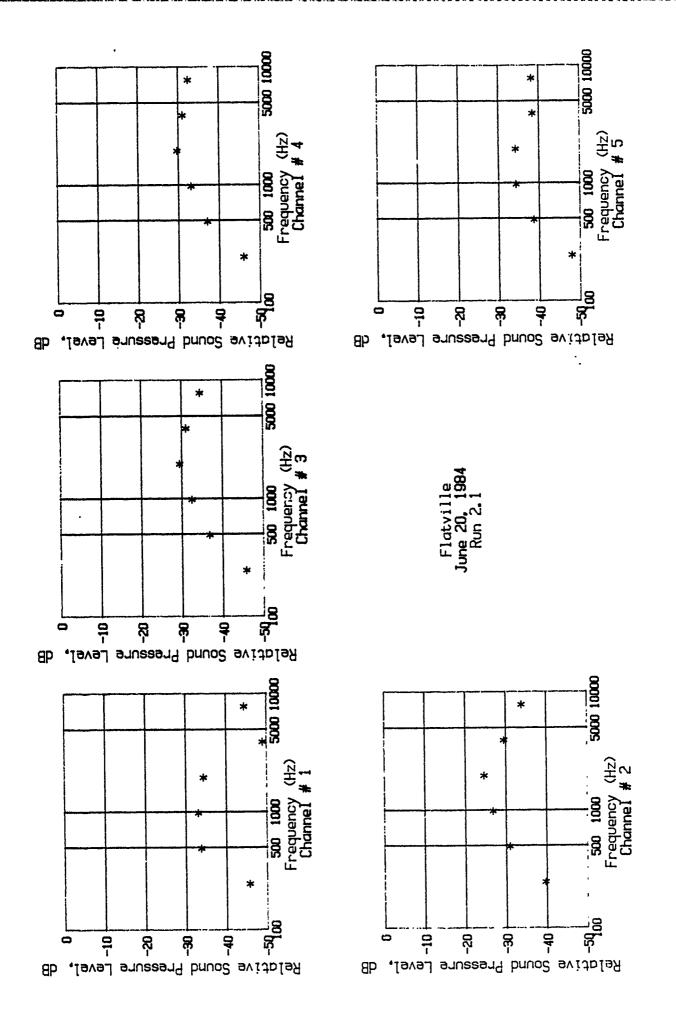
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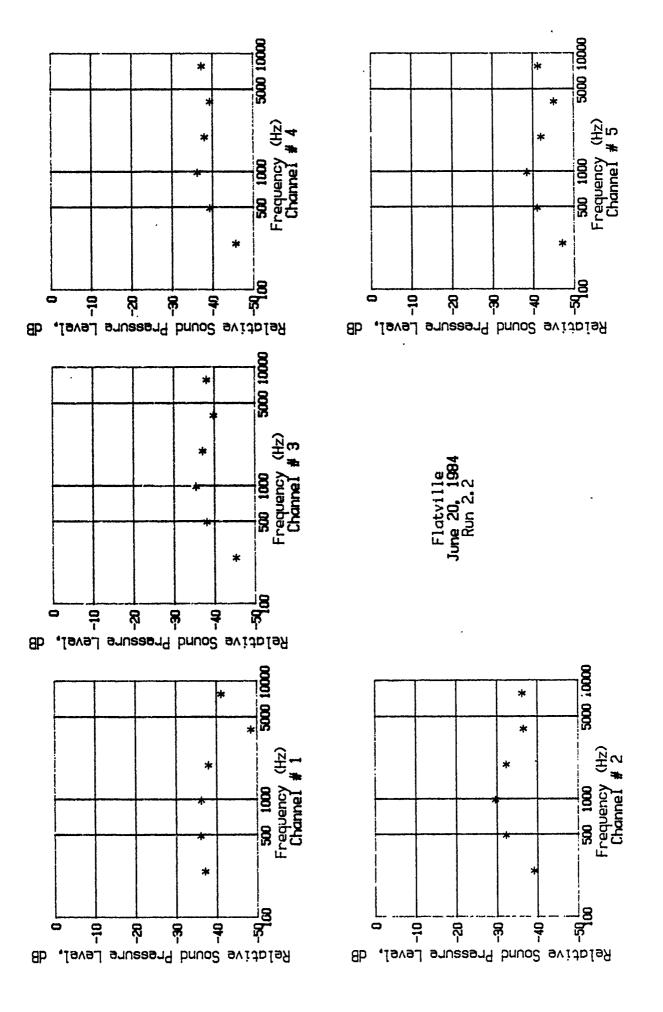
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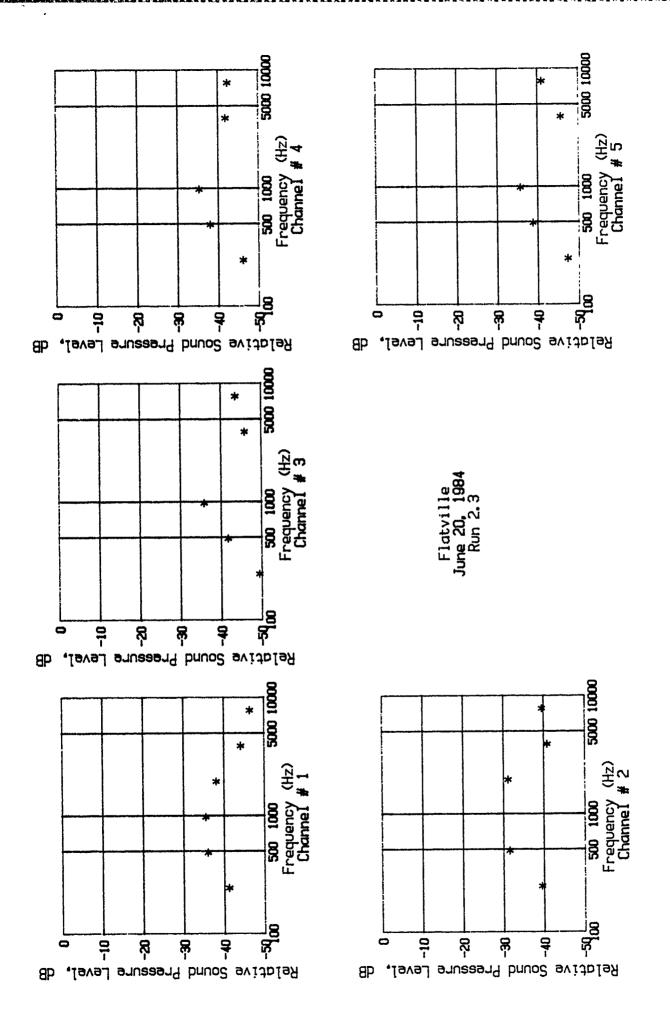
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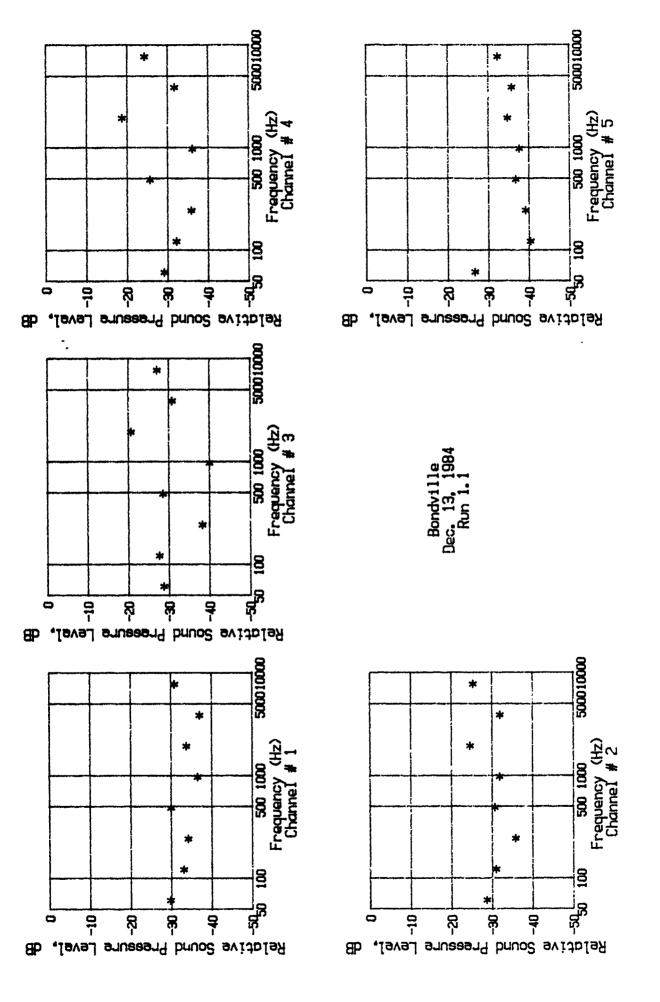
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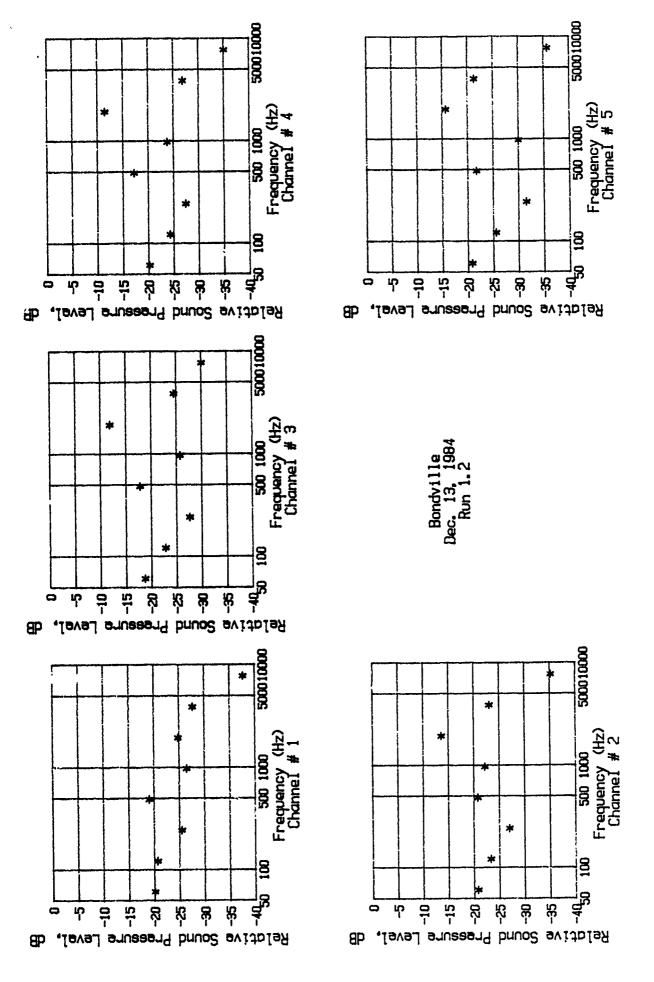


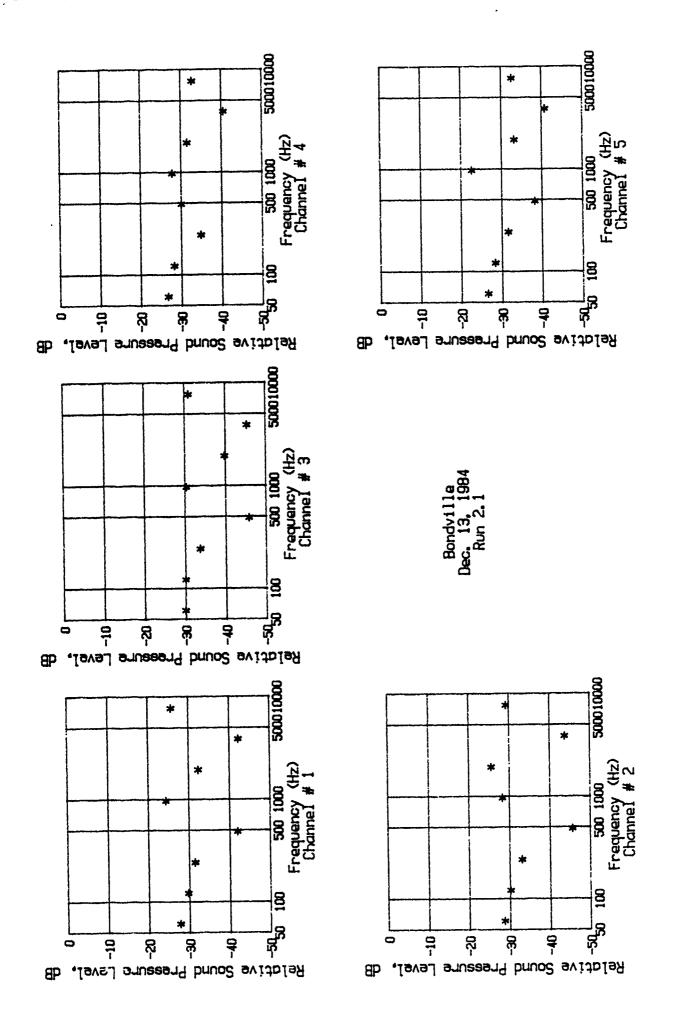


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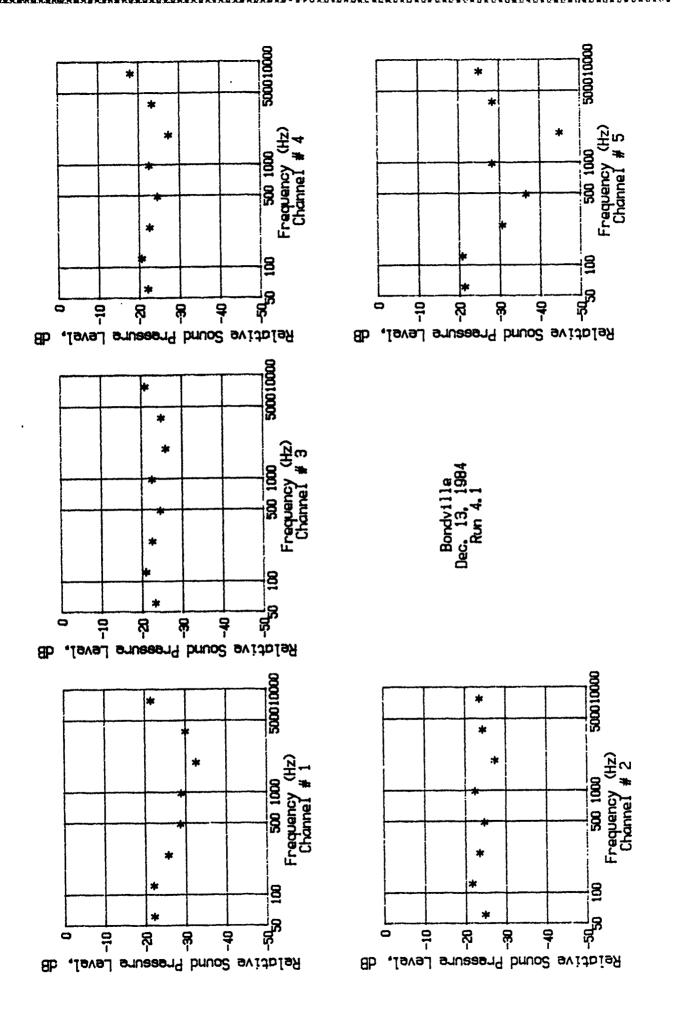
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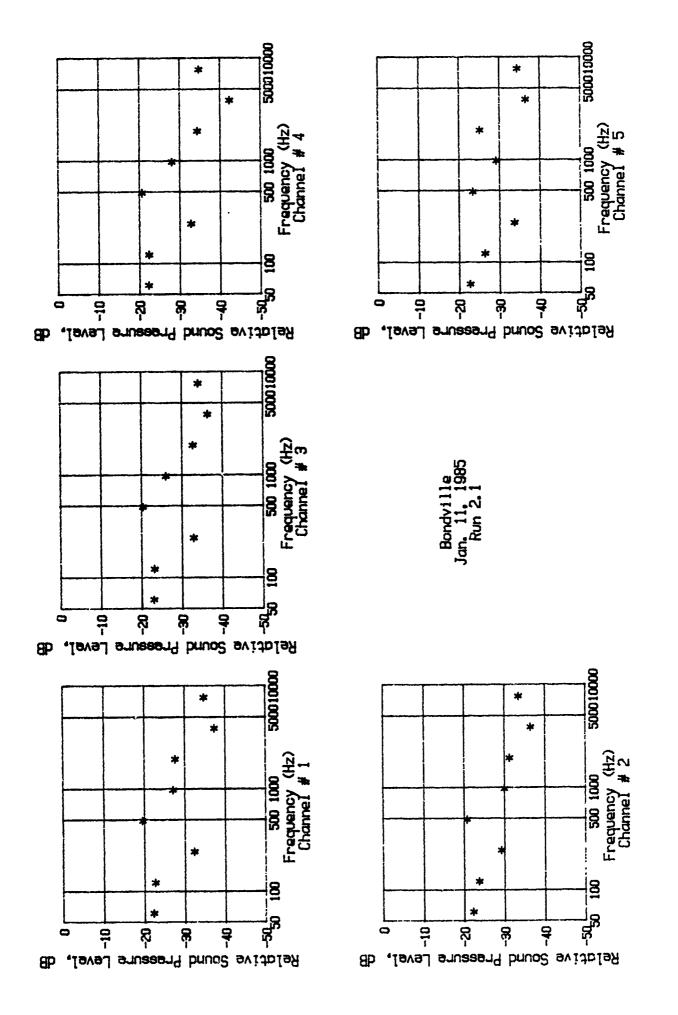
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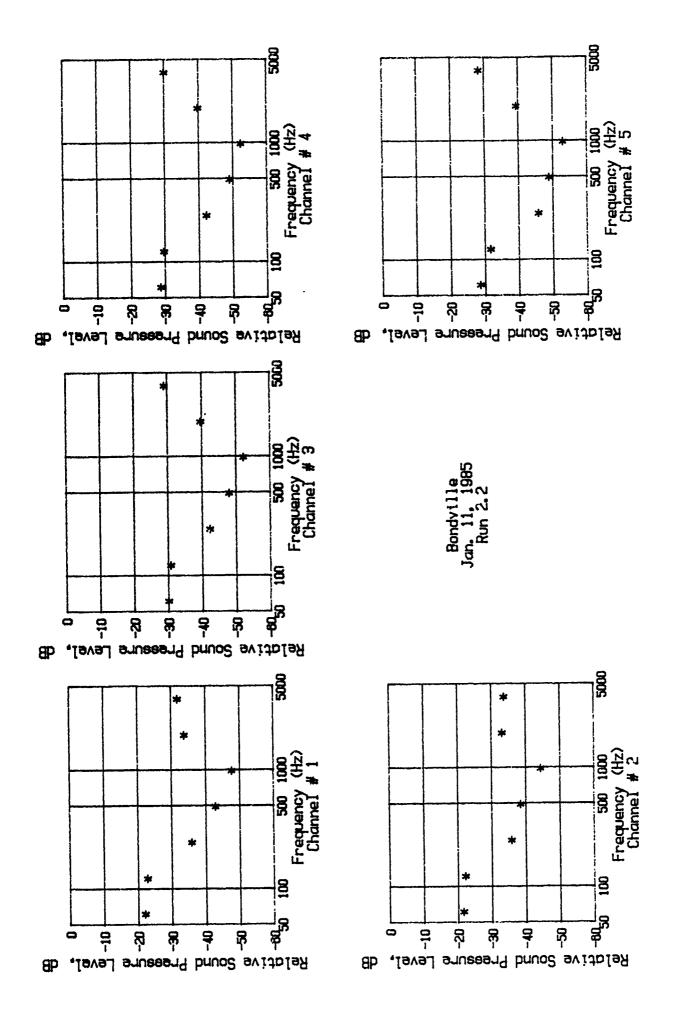
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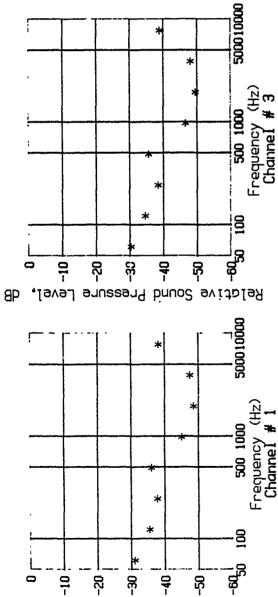
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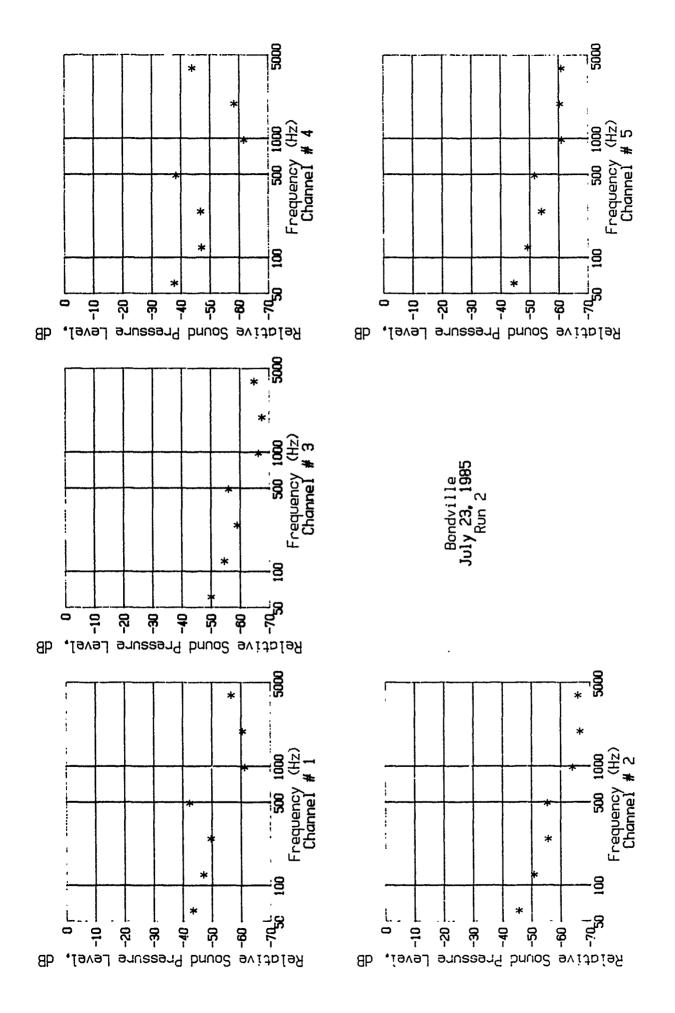
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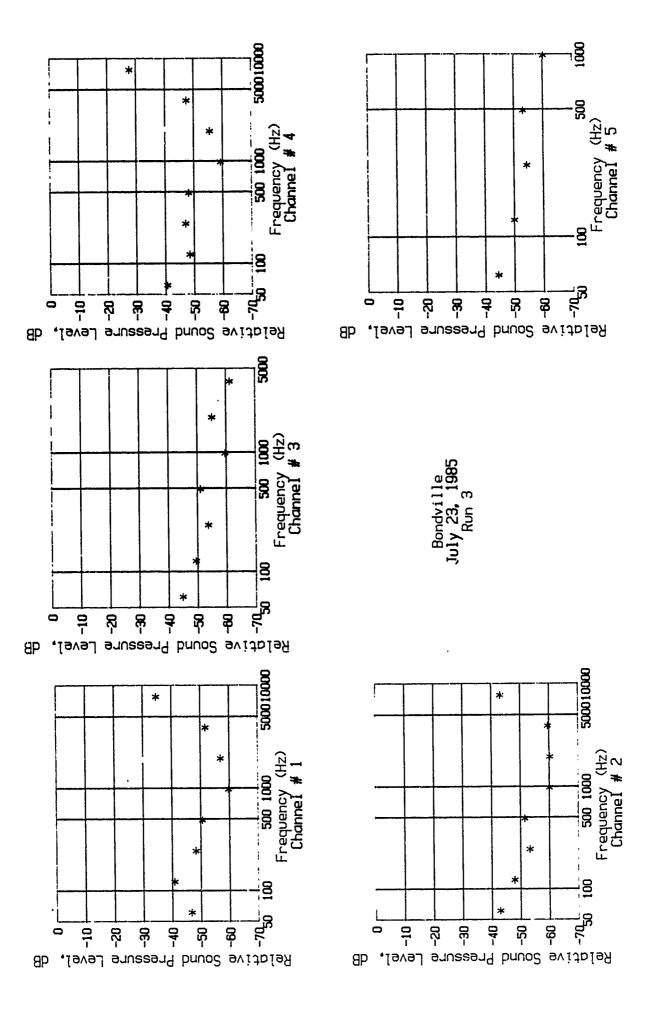
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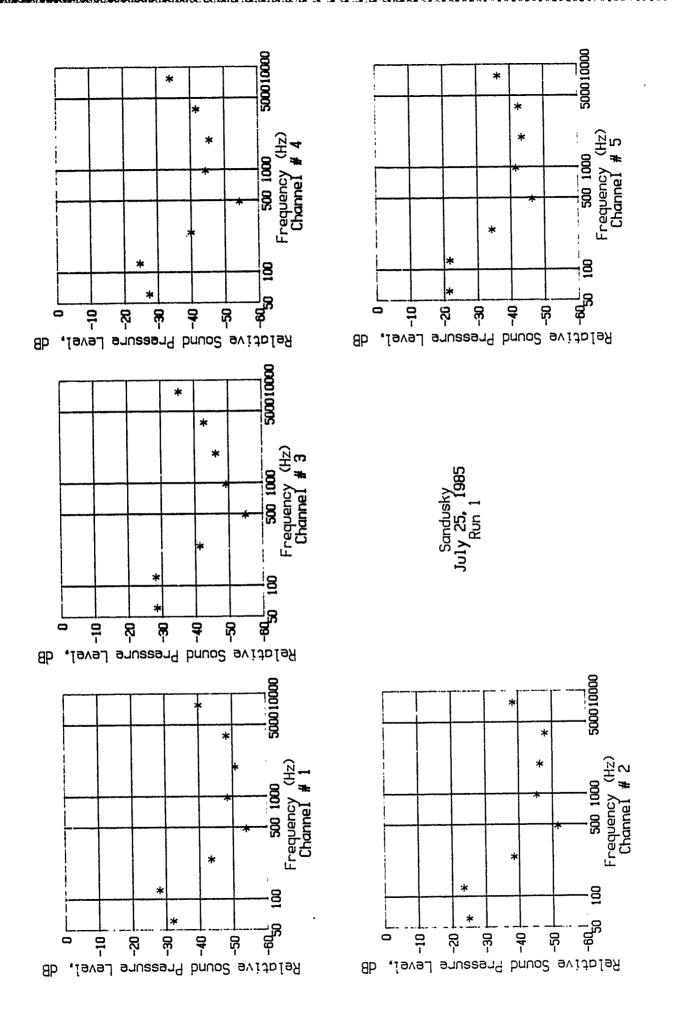


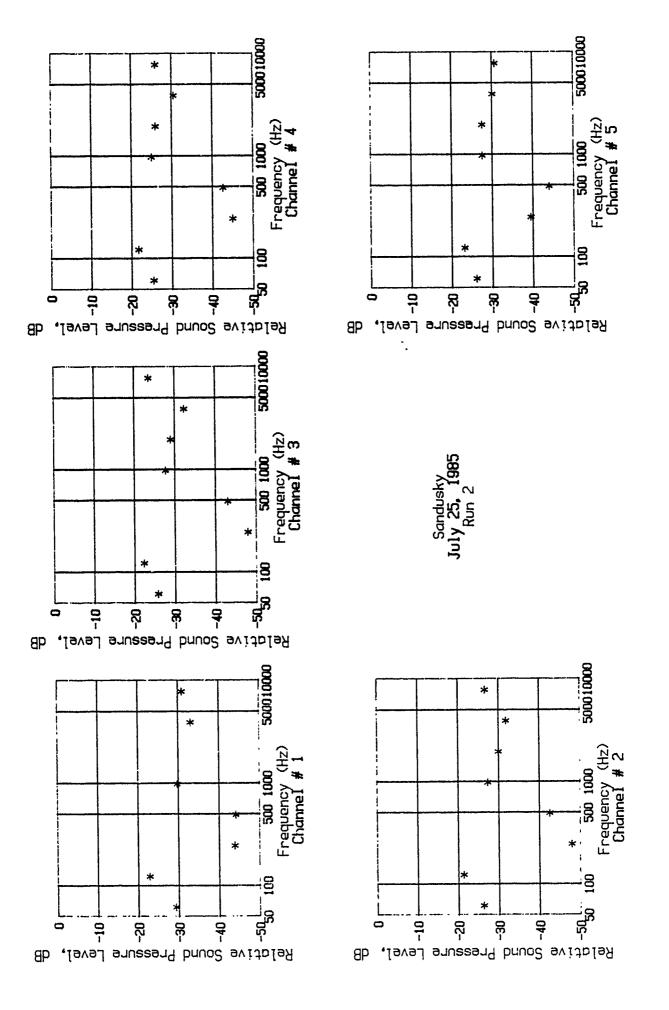


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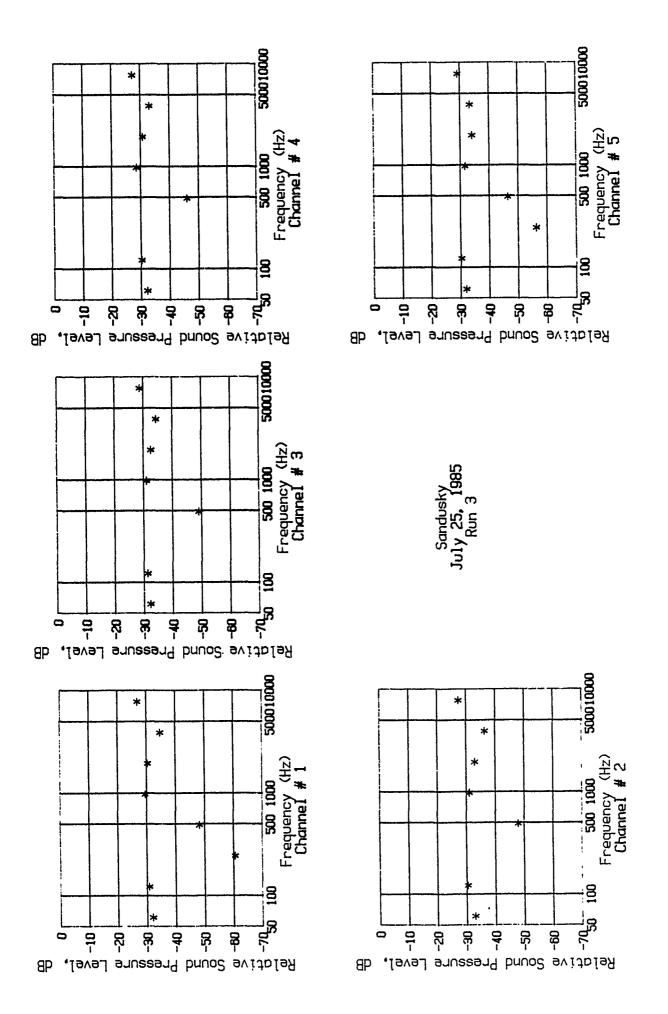


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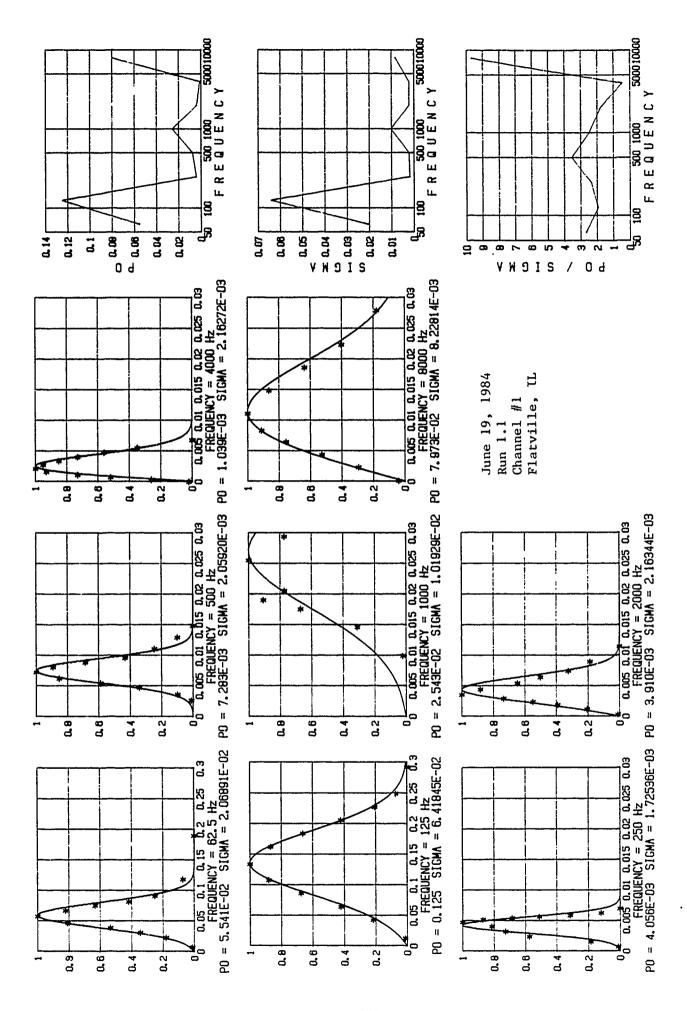
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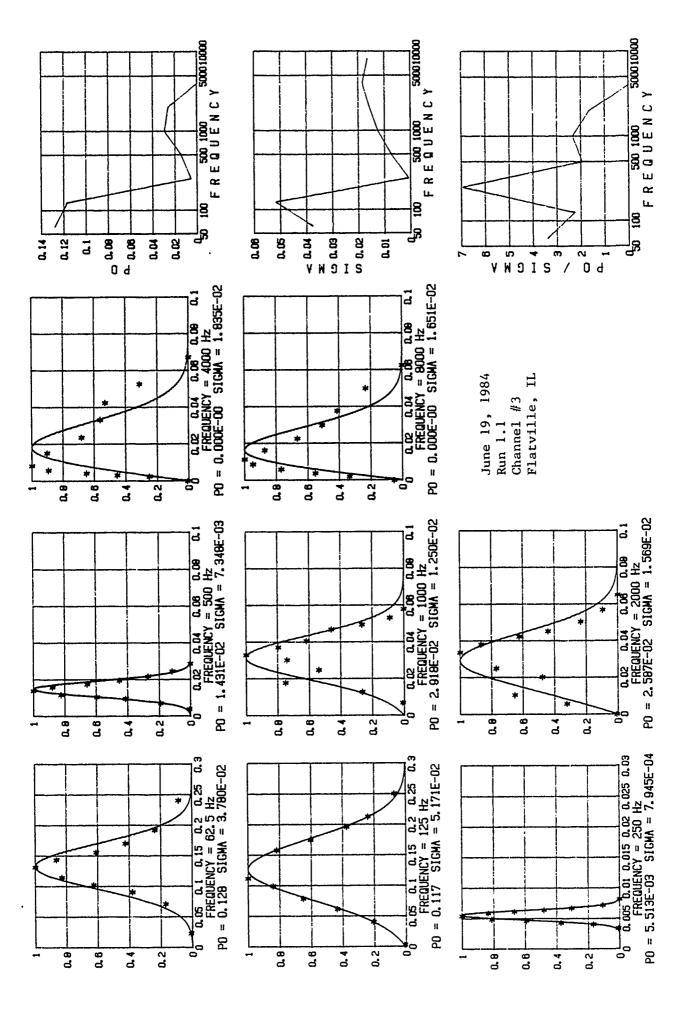
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APPENDIX E

Comparison of the MCA data with the bivariant normal probability function.





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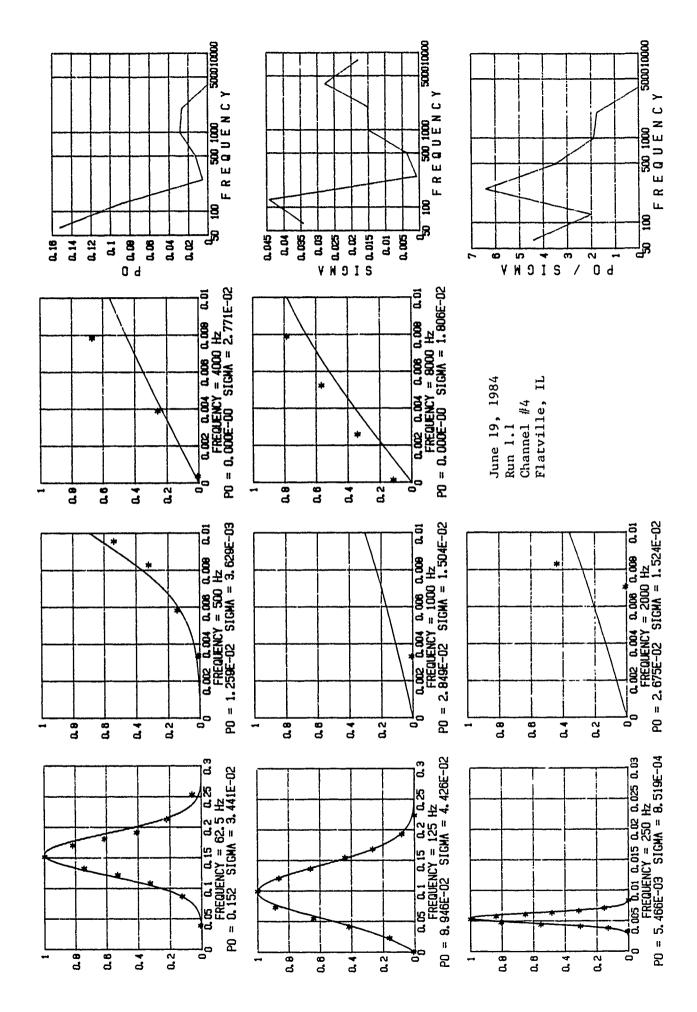
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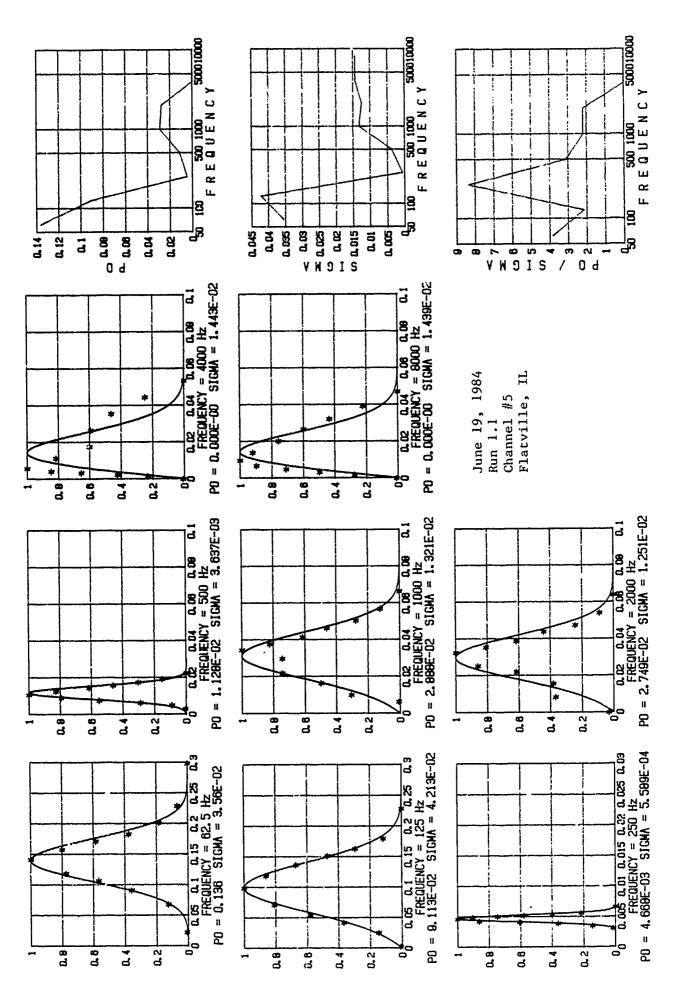
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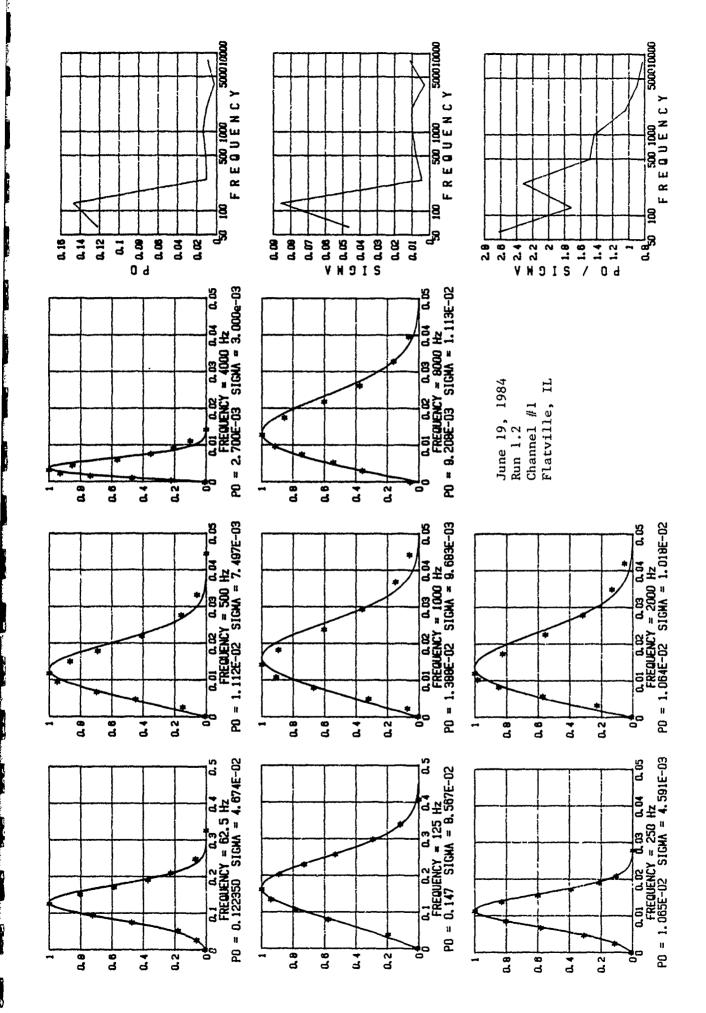
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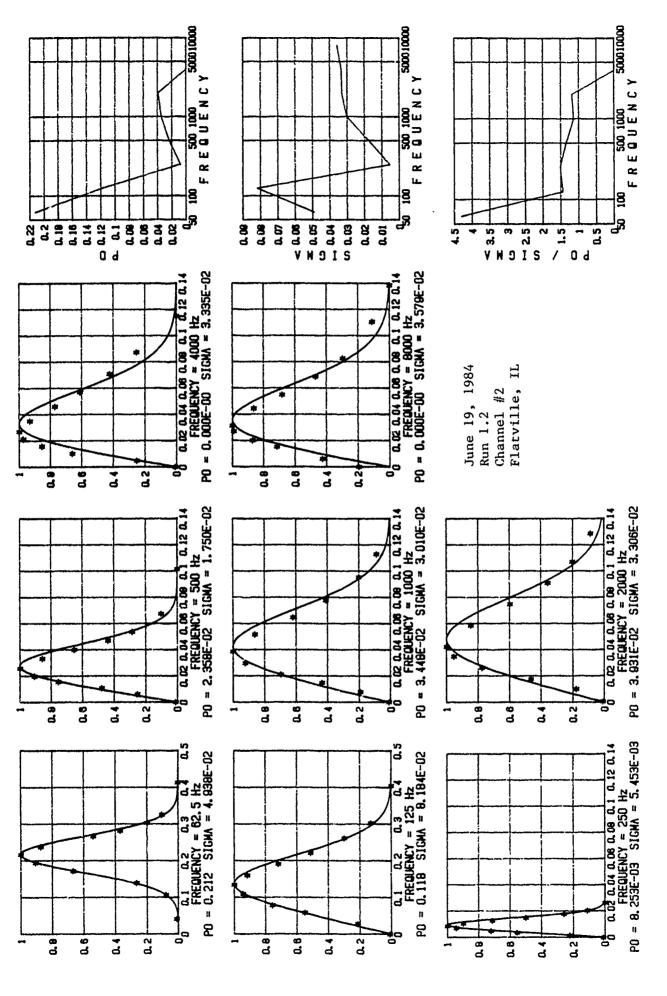
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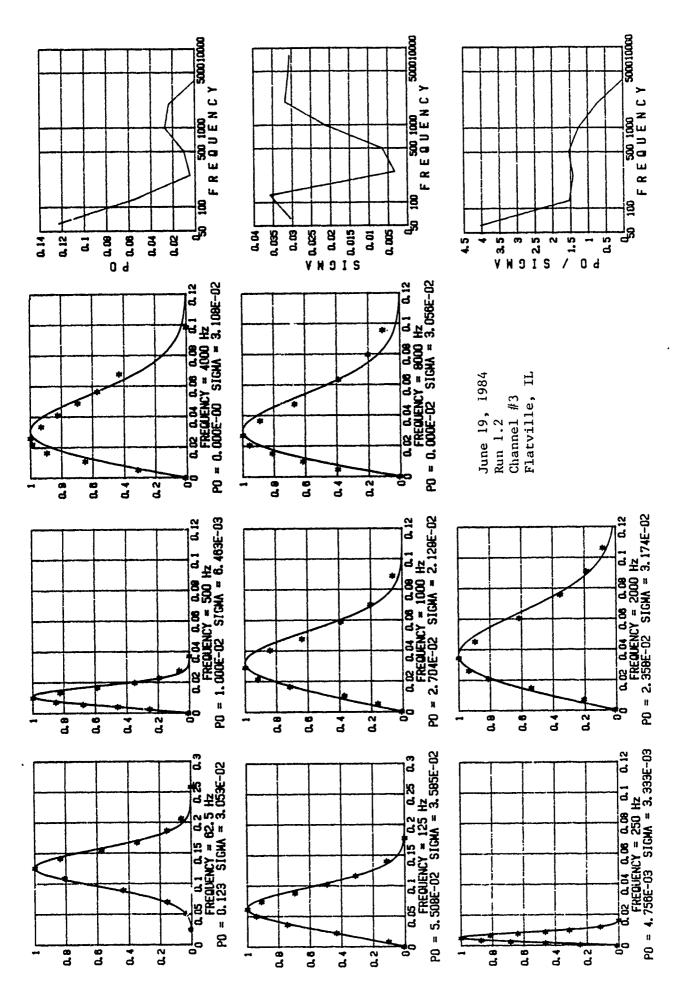
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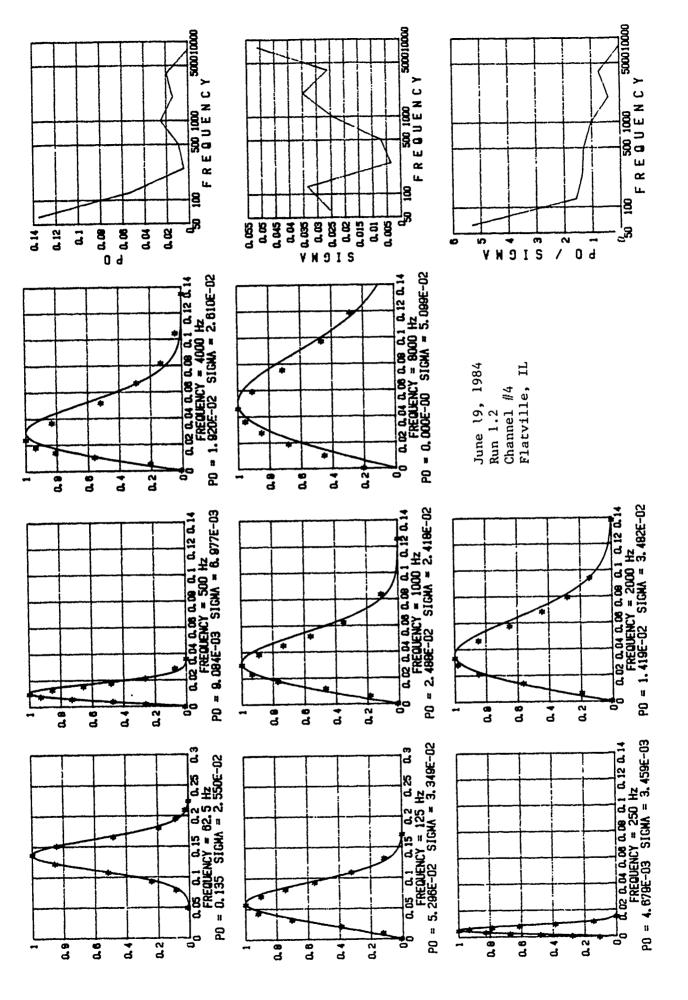
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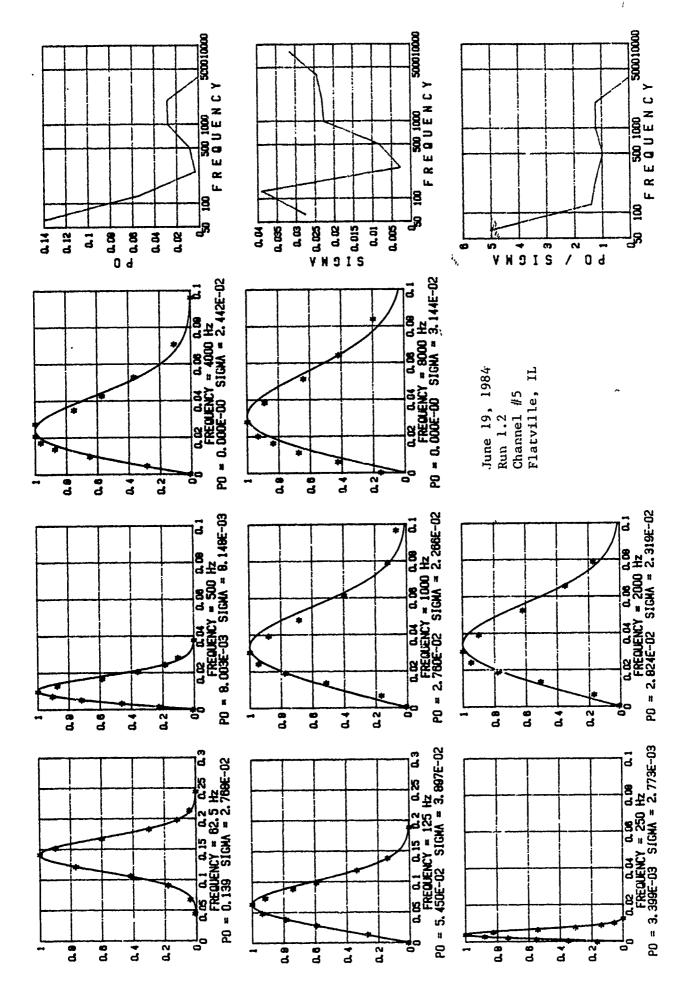
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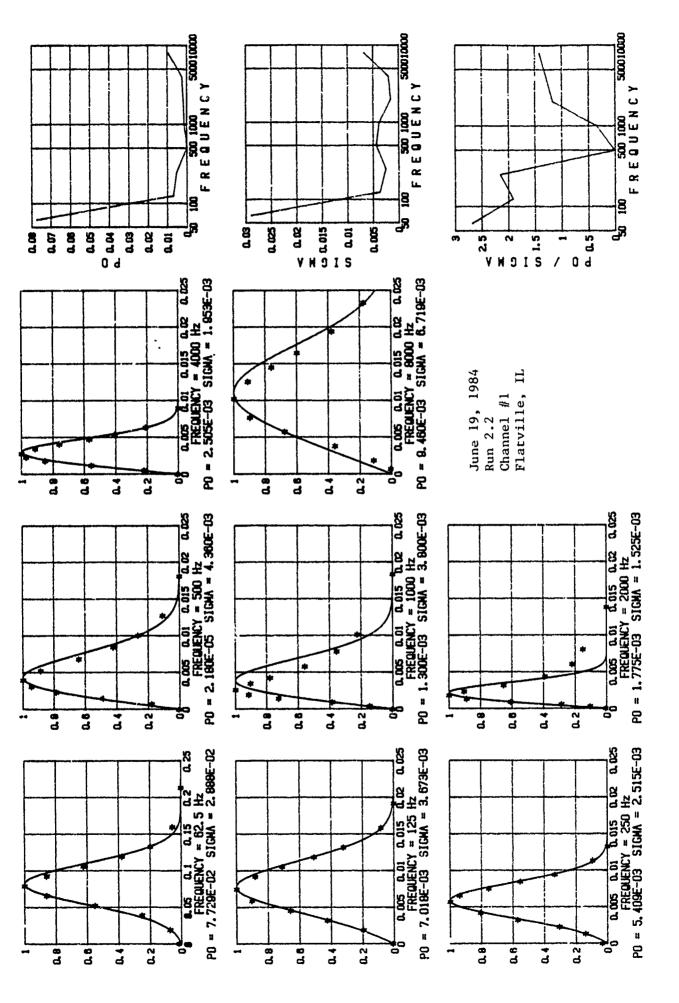
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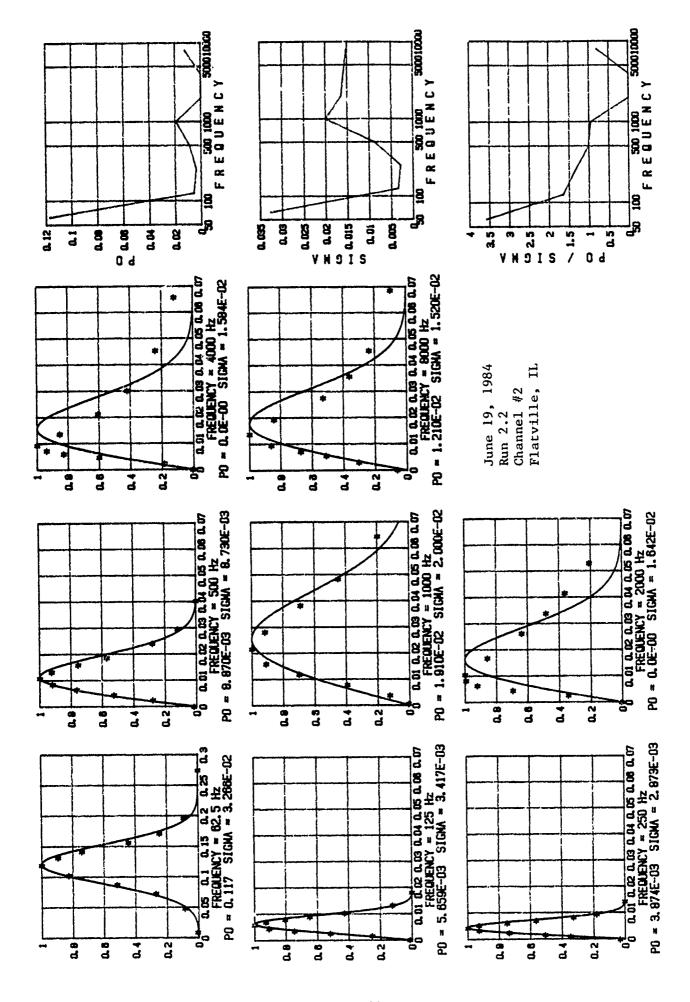
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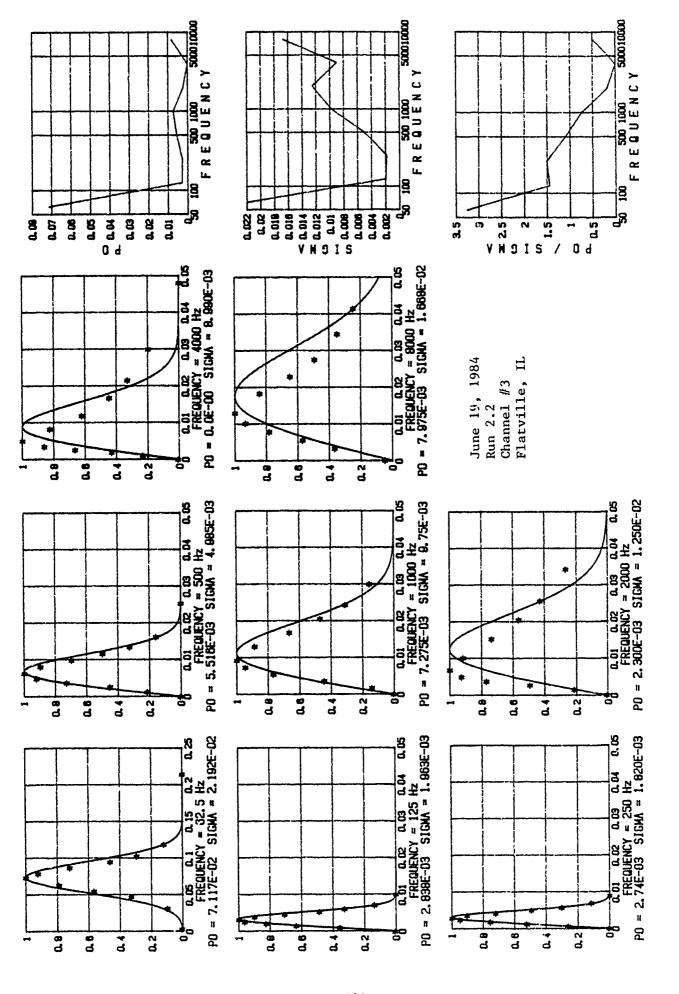
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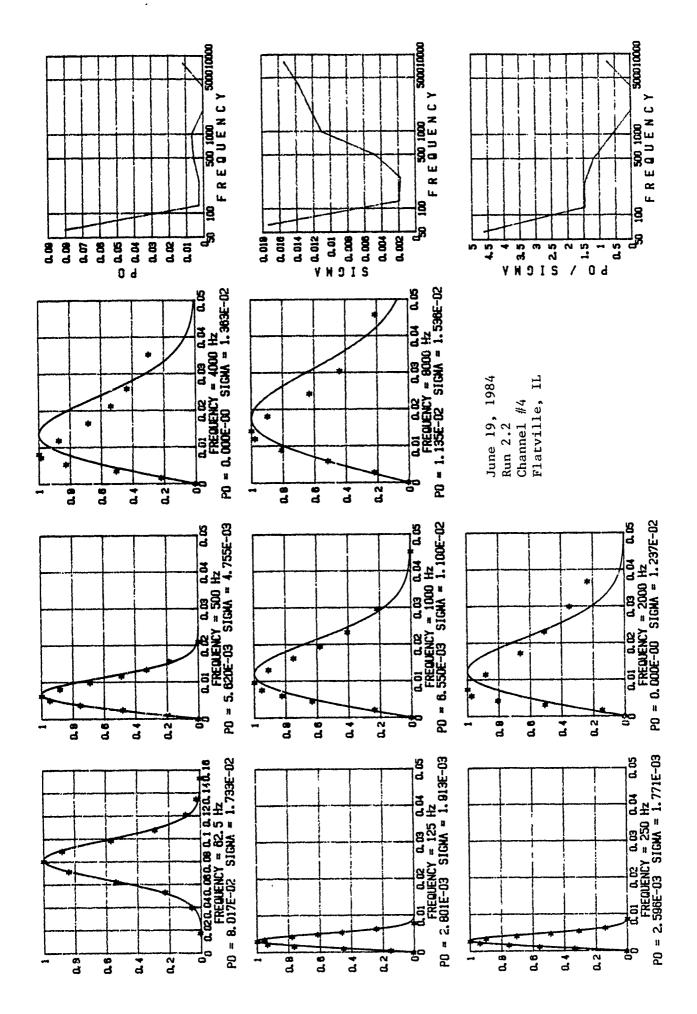
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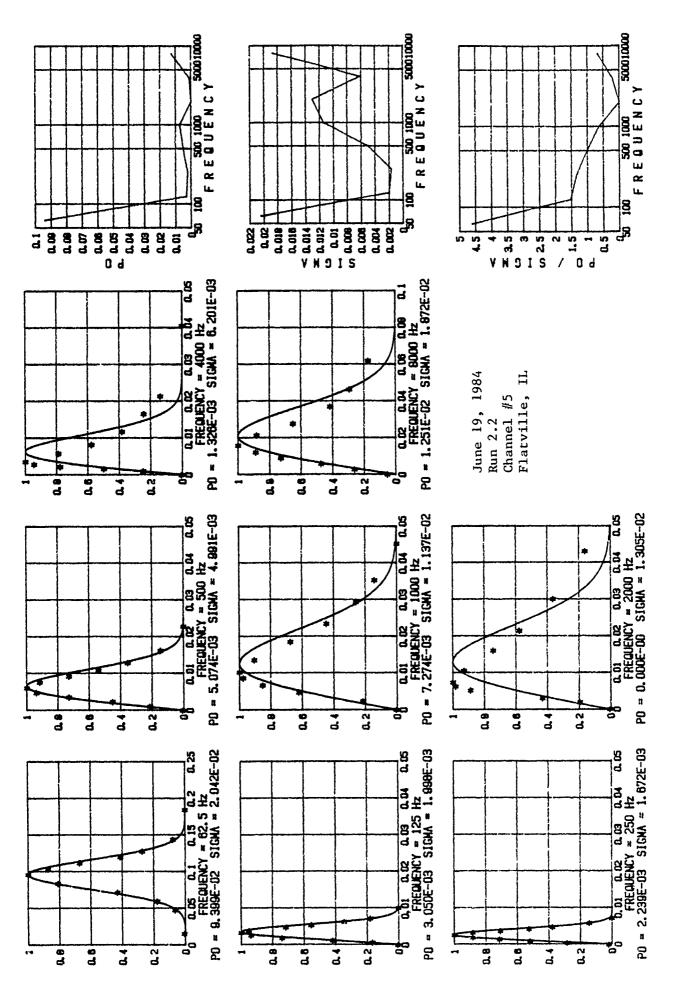
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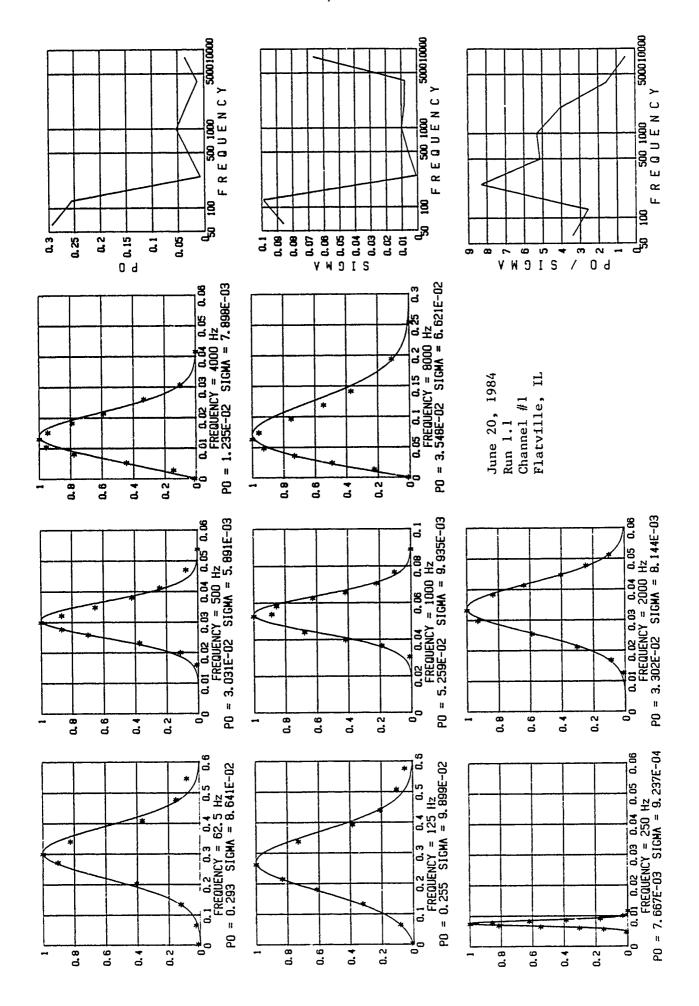
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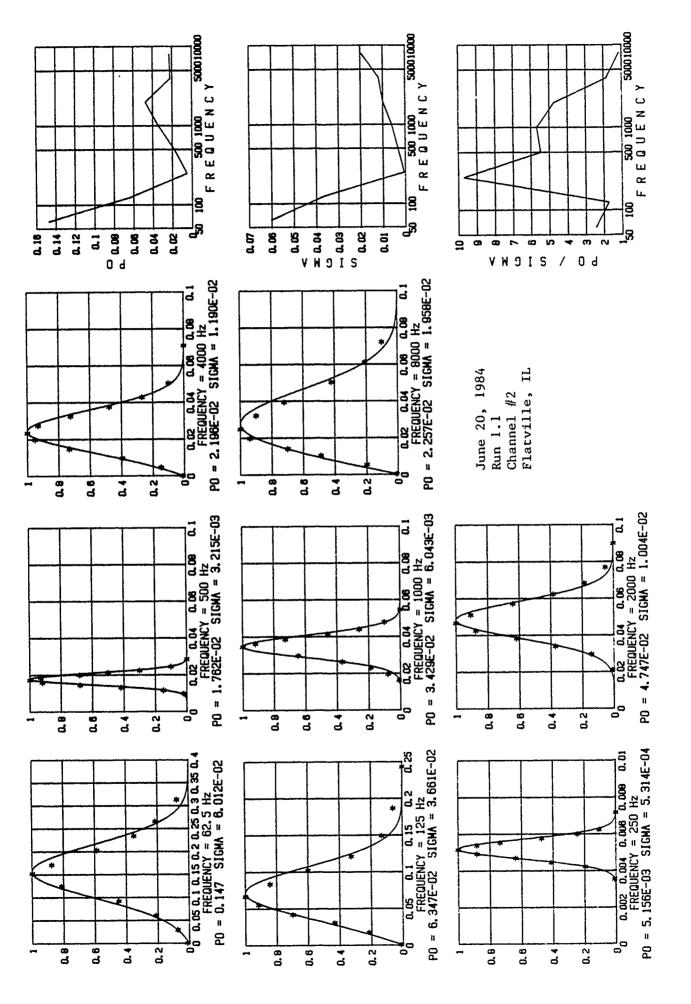
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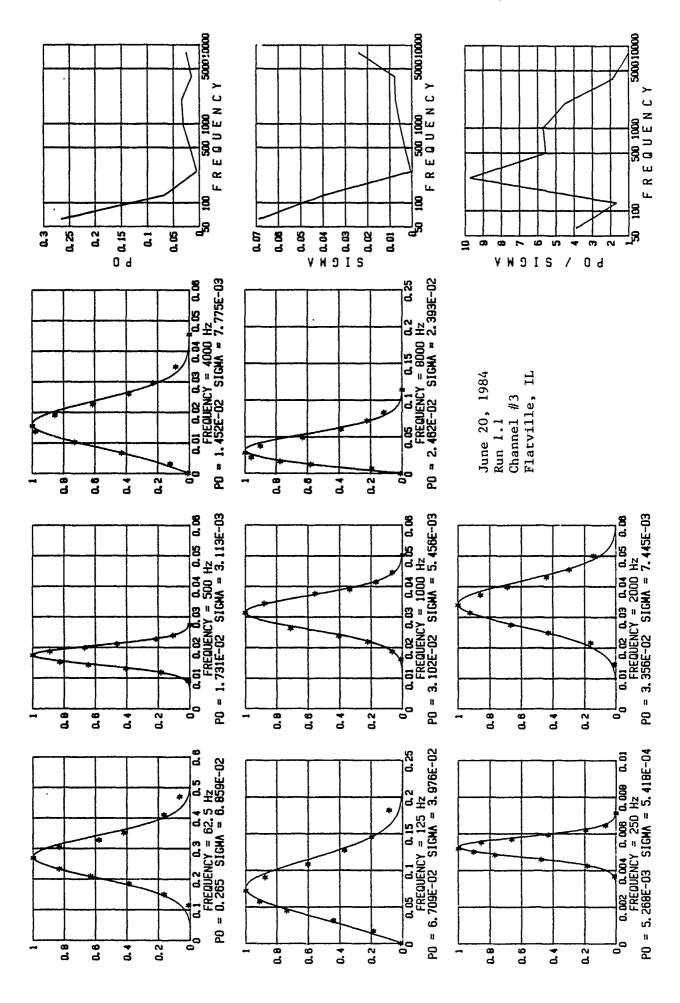
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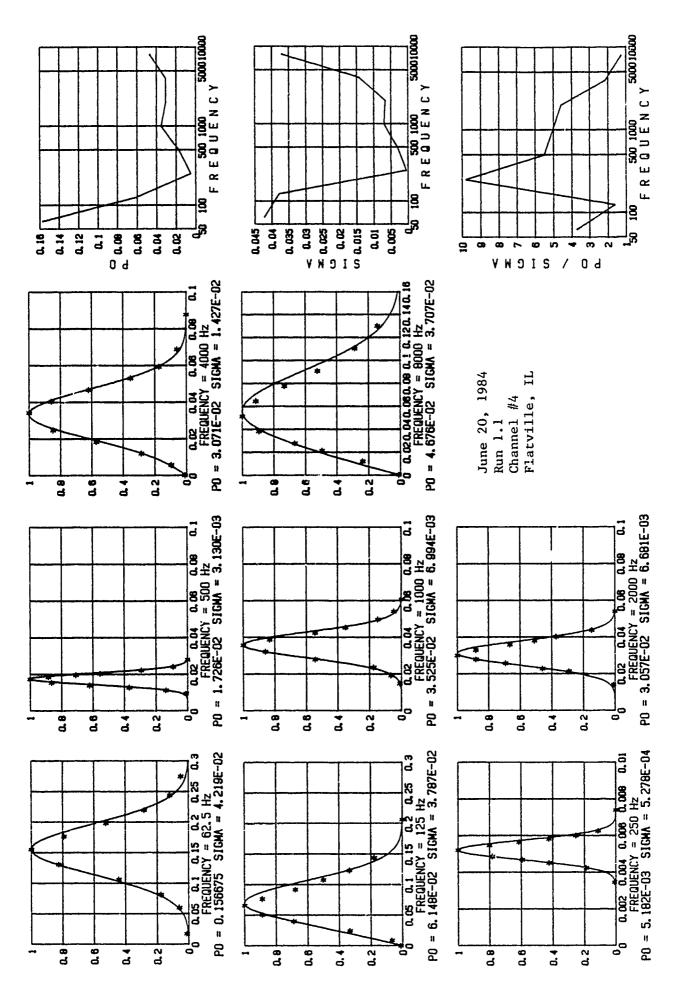


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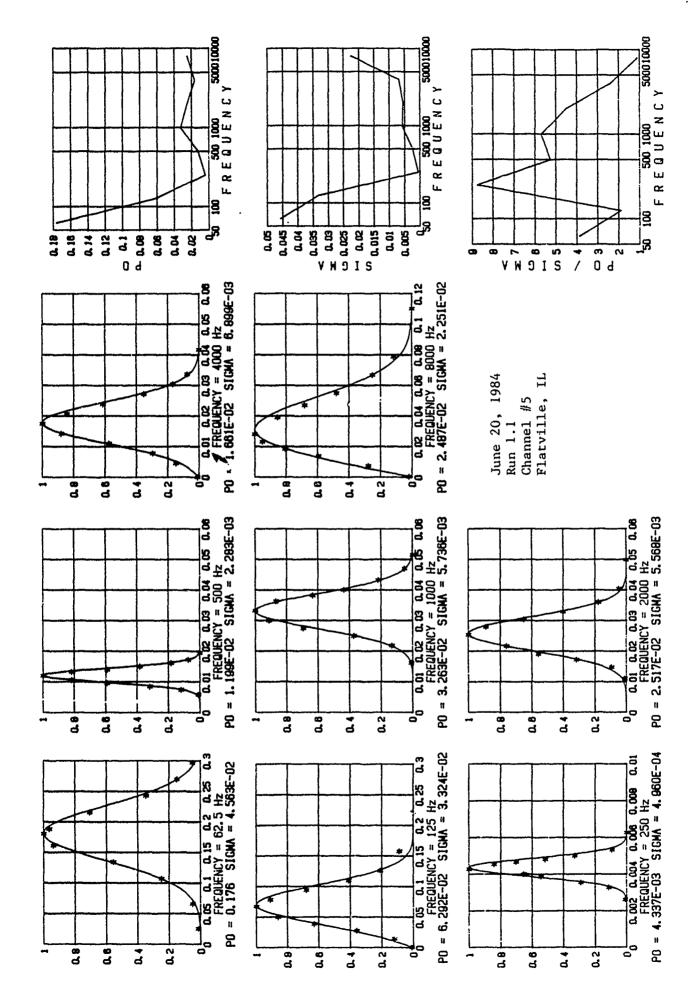
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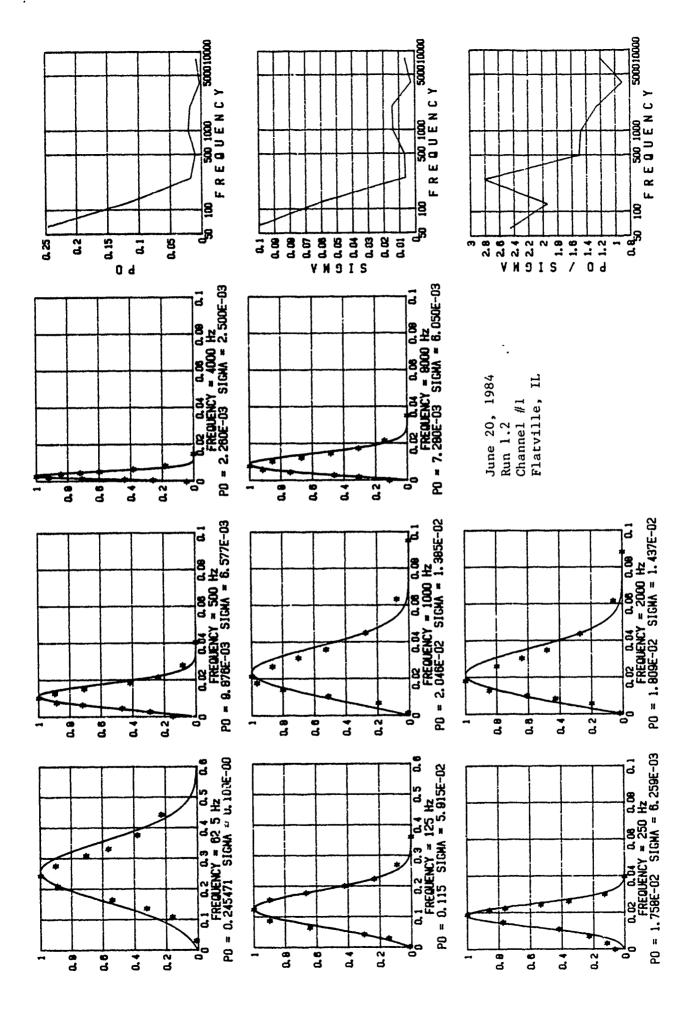
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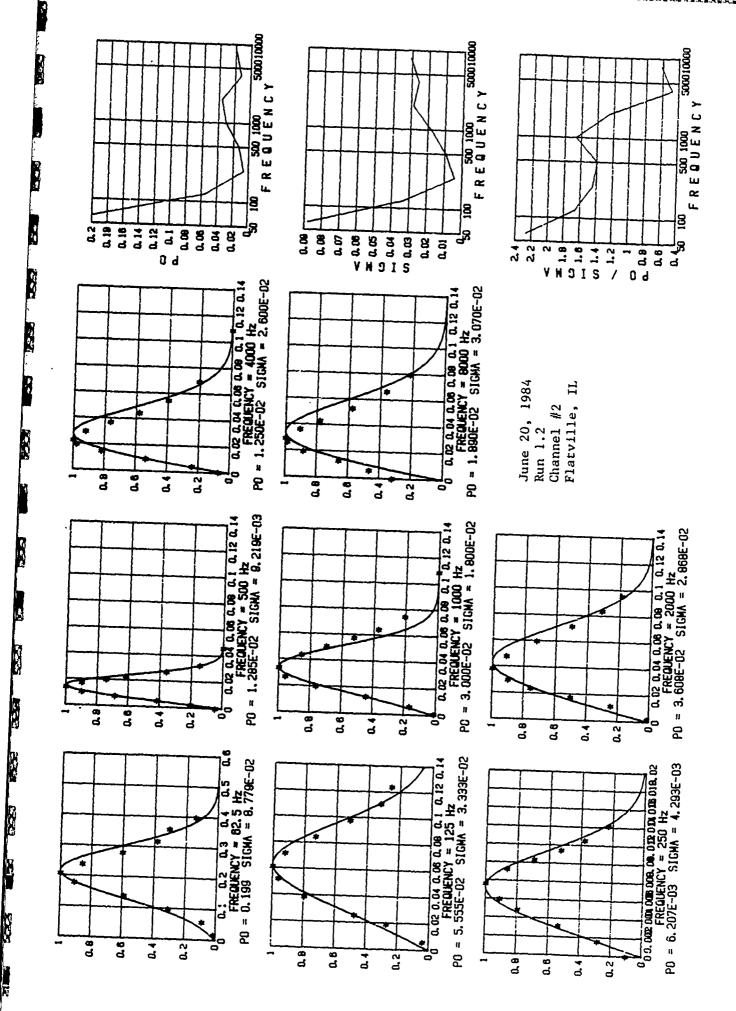
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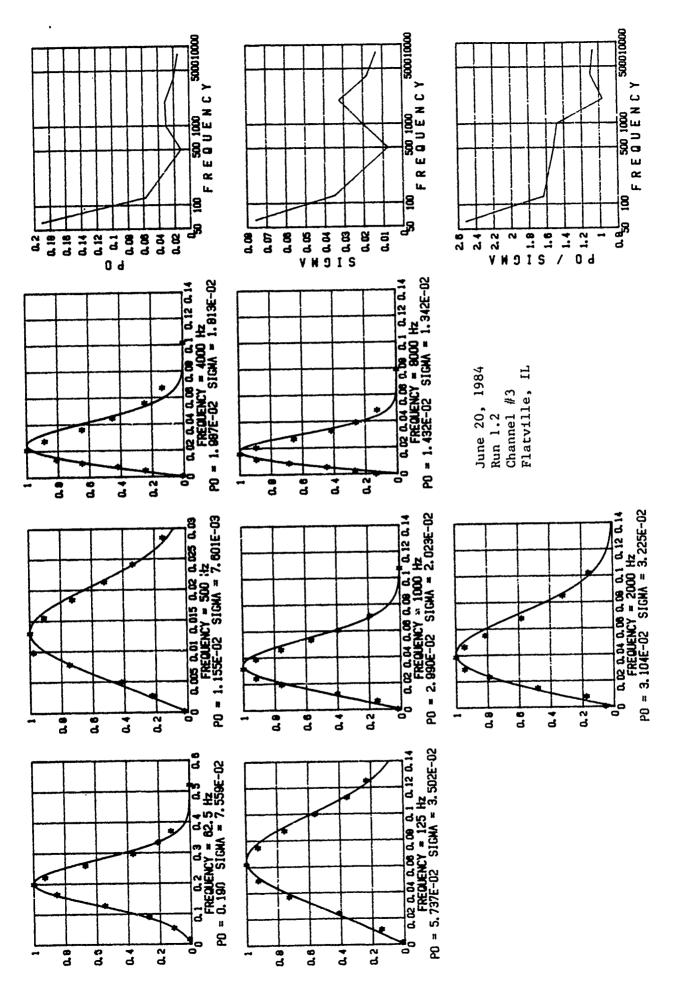
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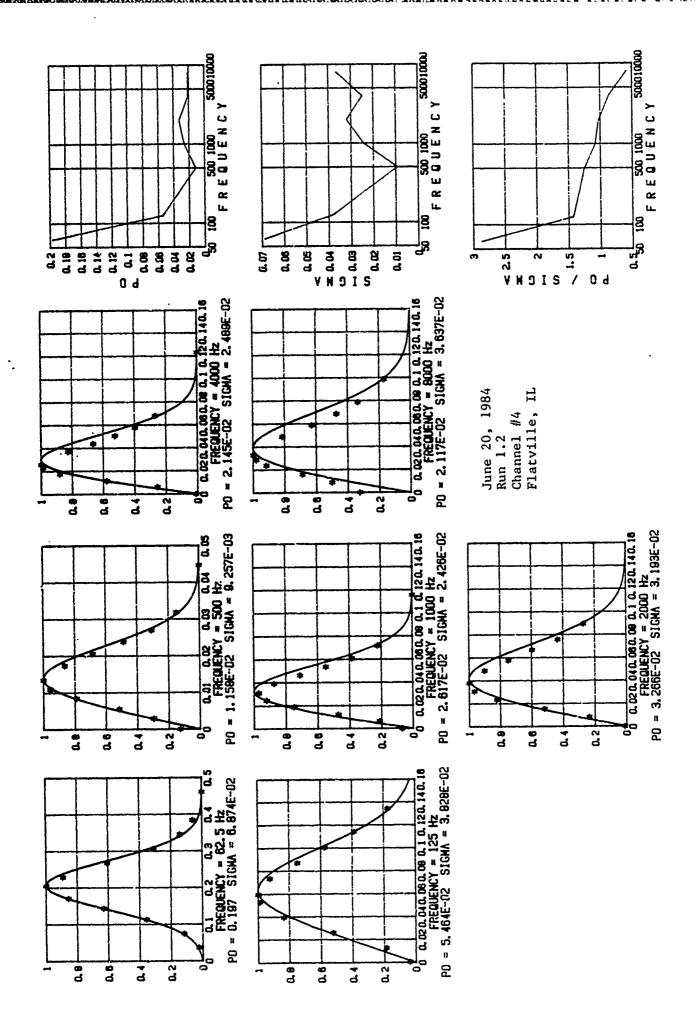
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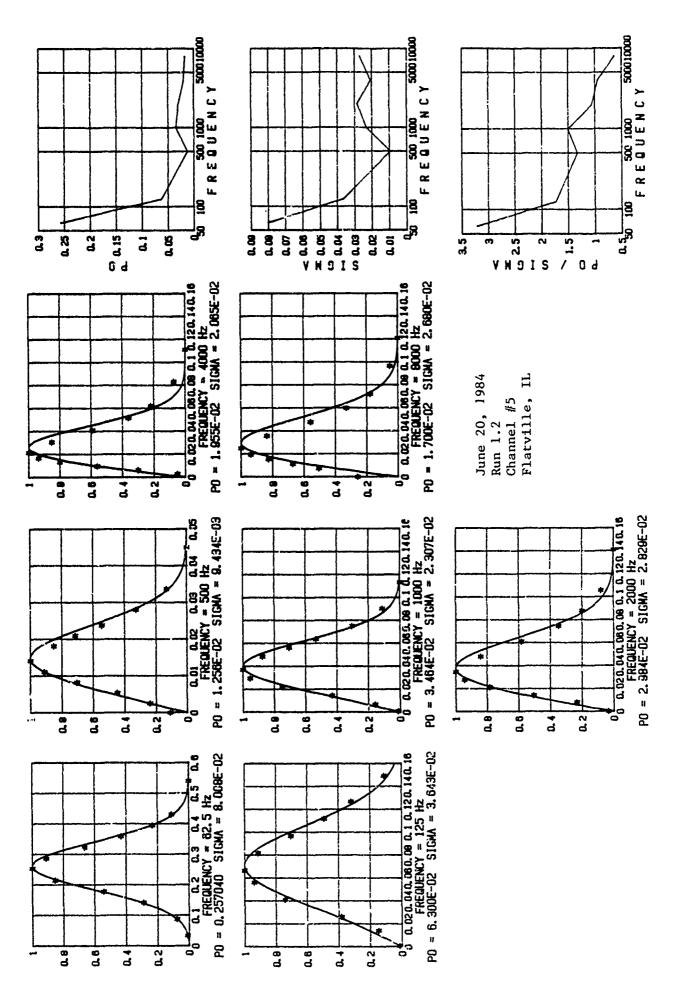
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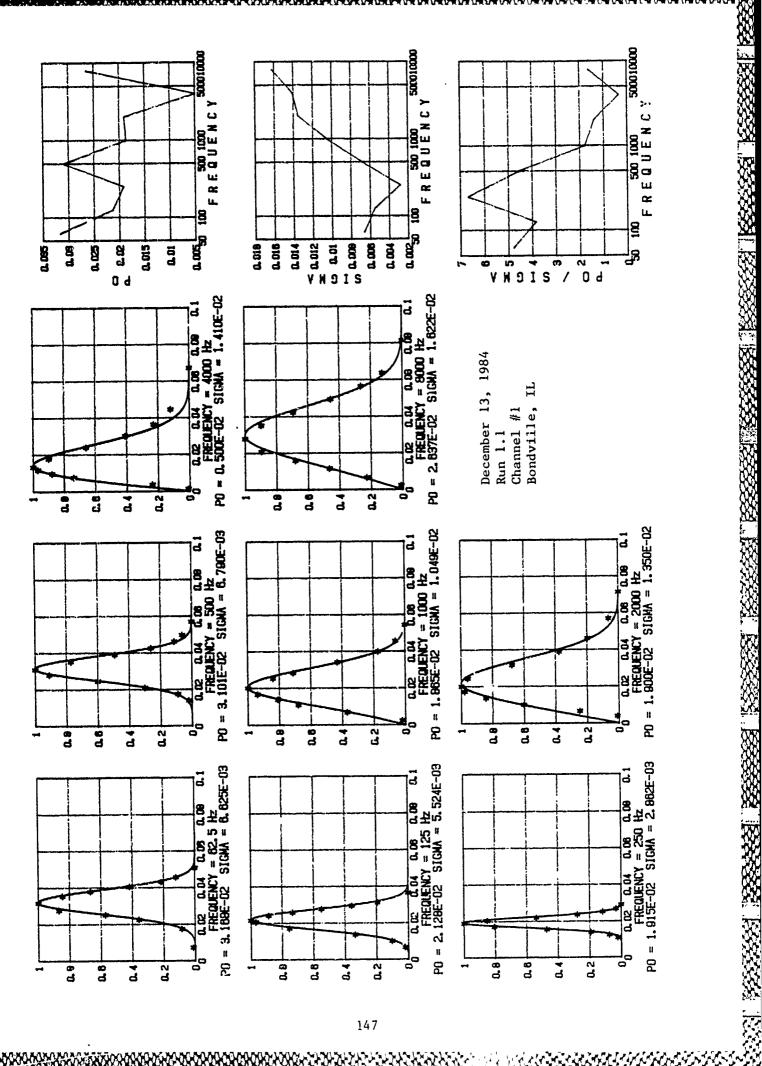
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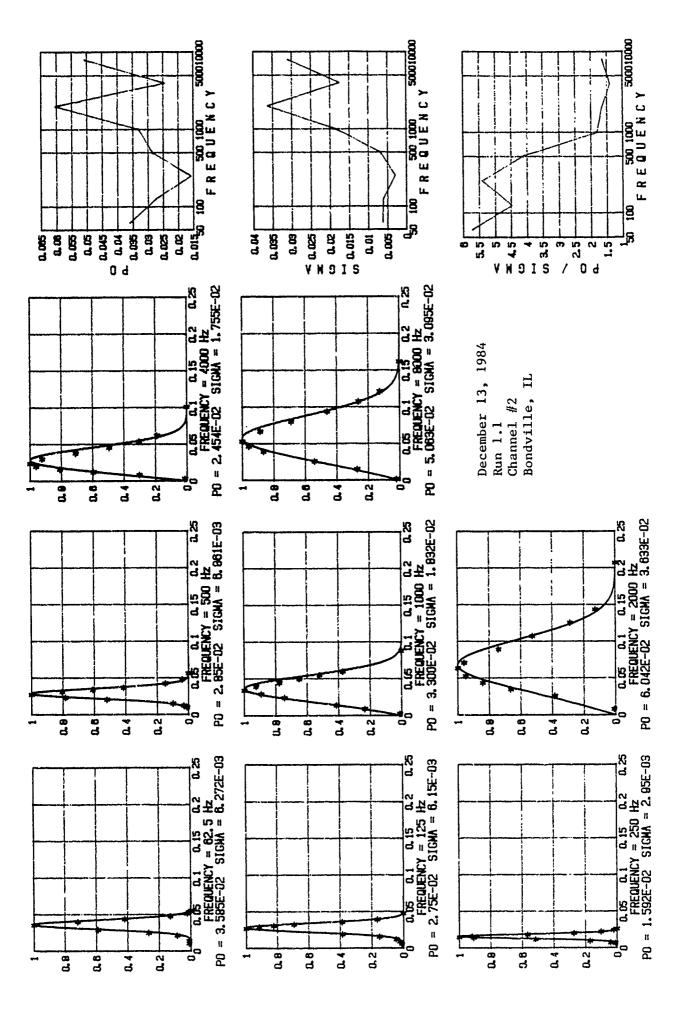
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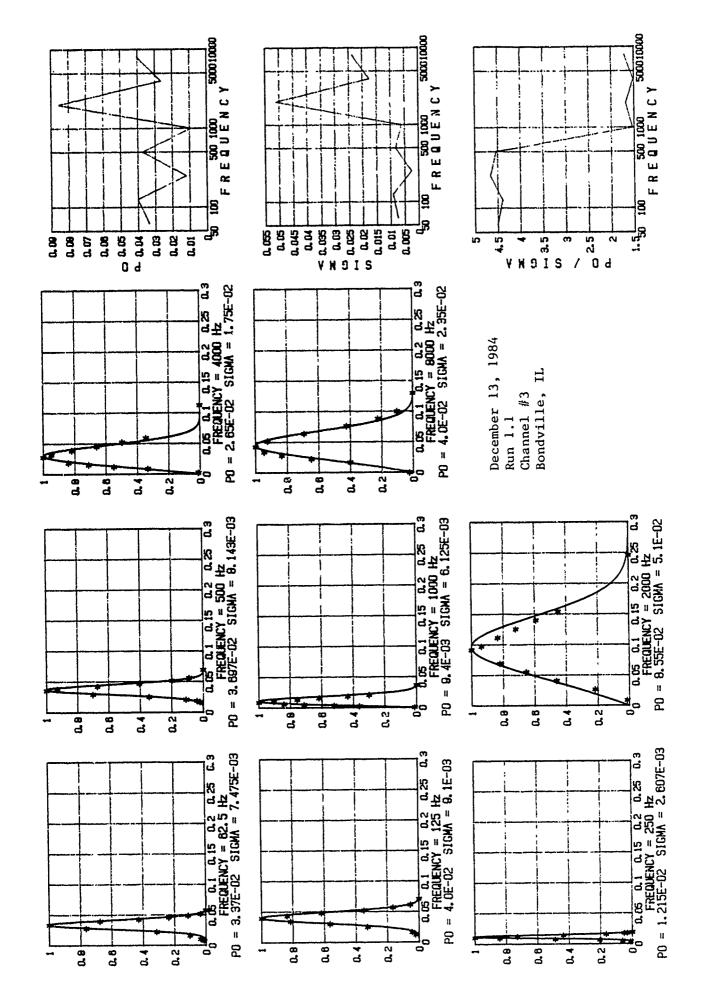
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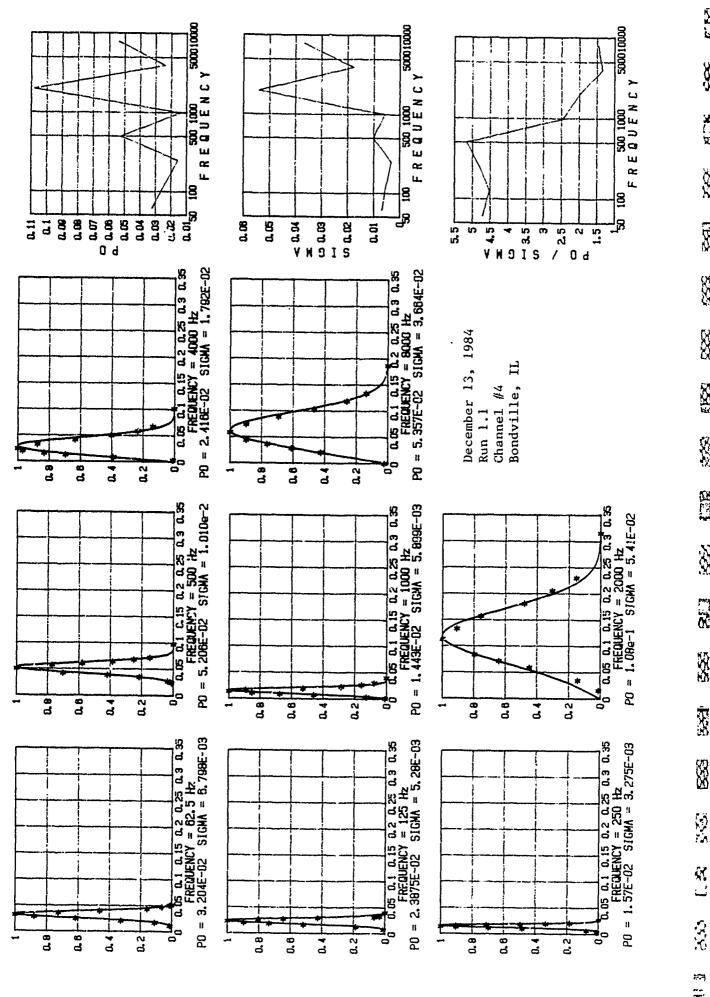
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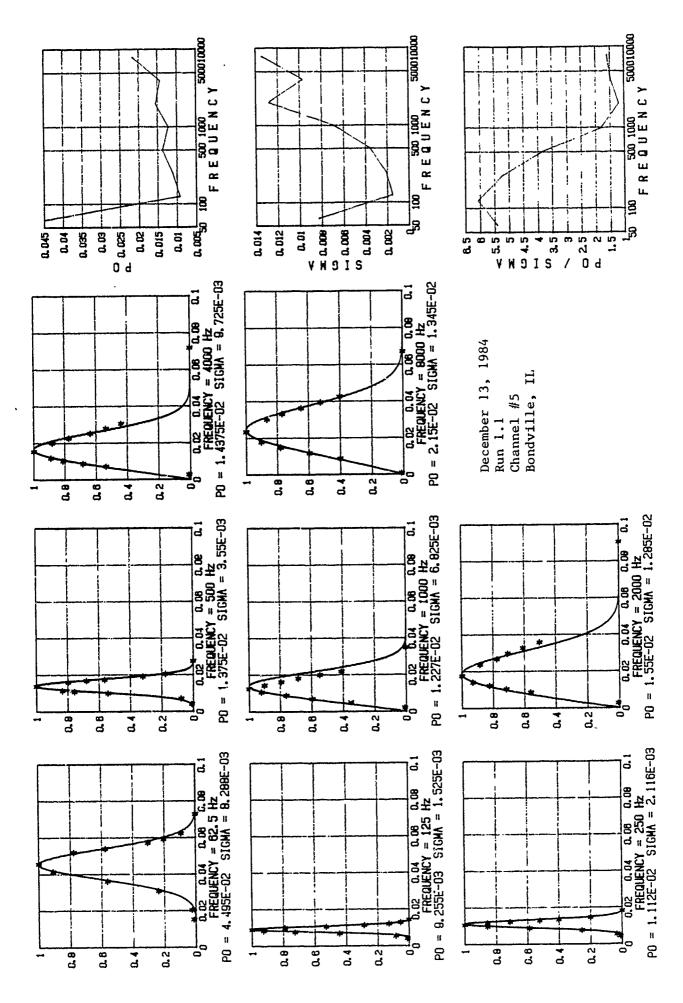
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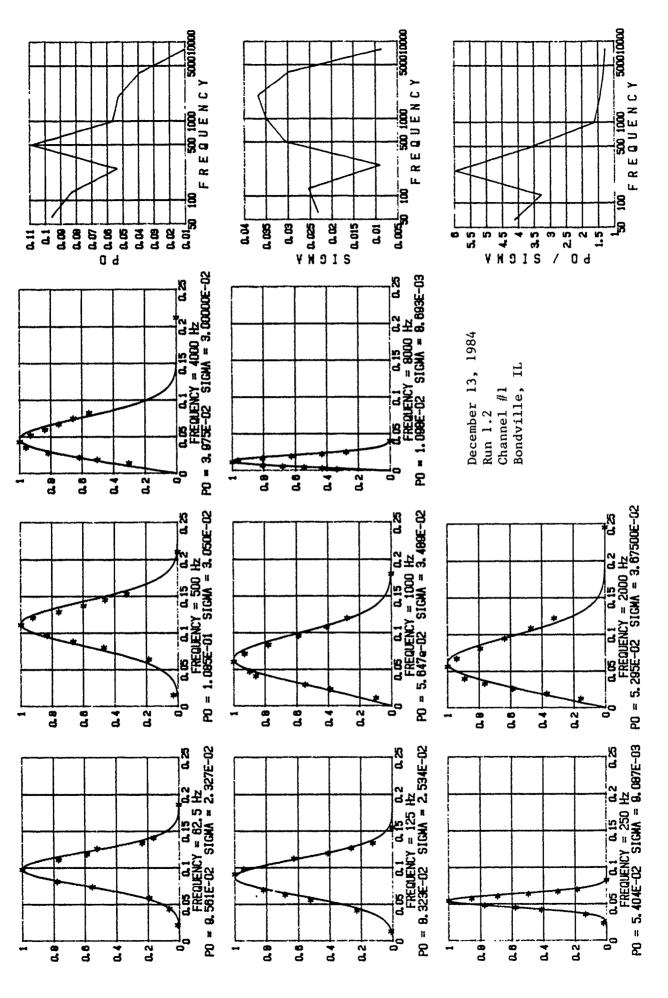
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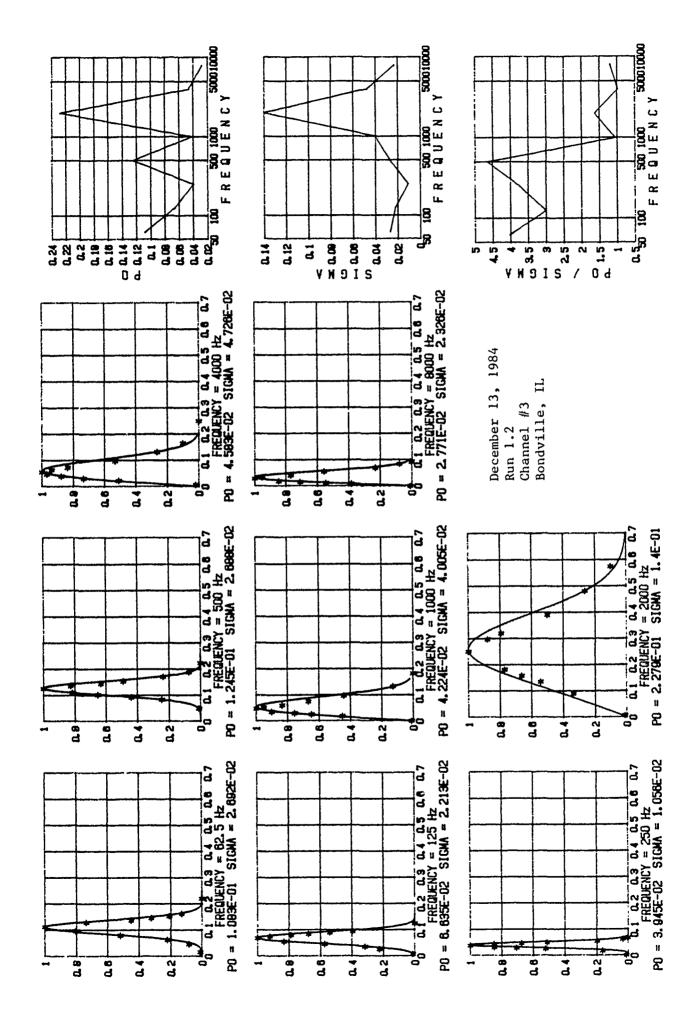
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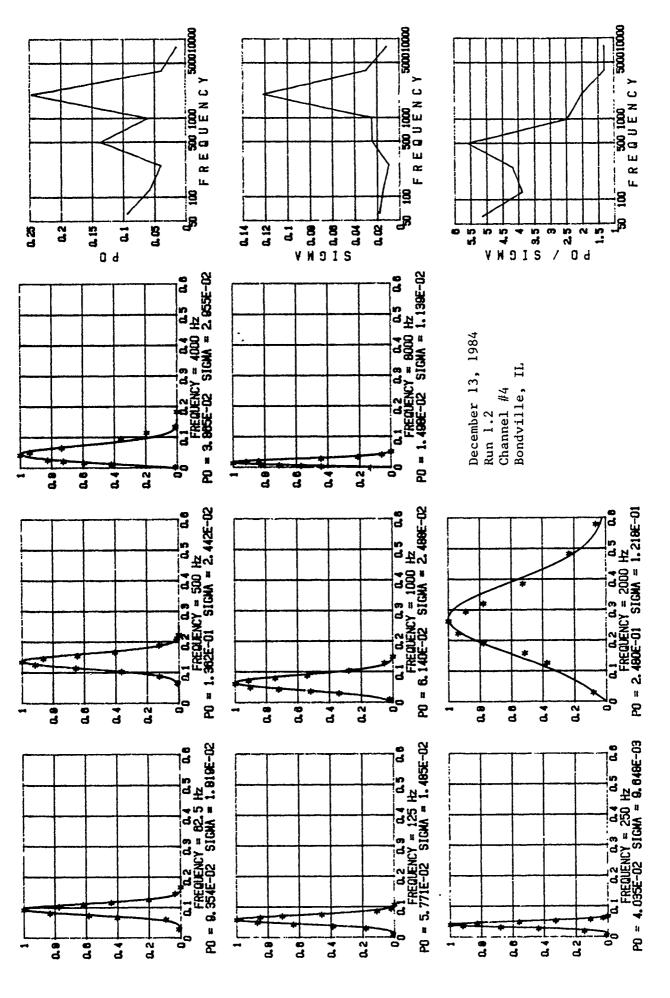
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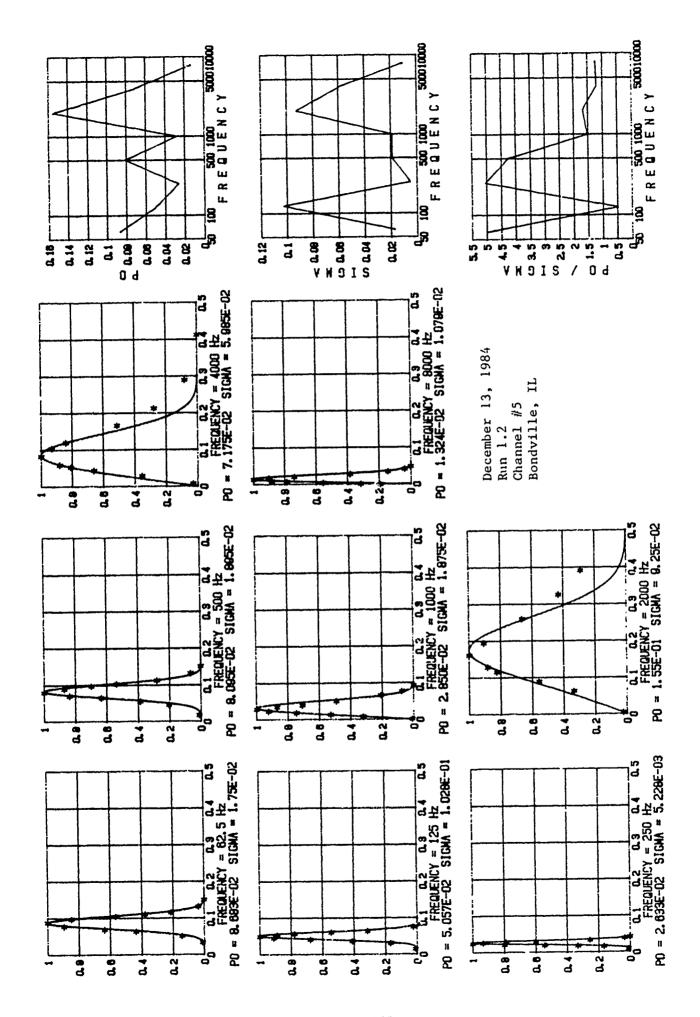
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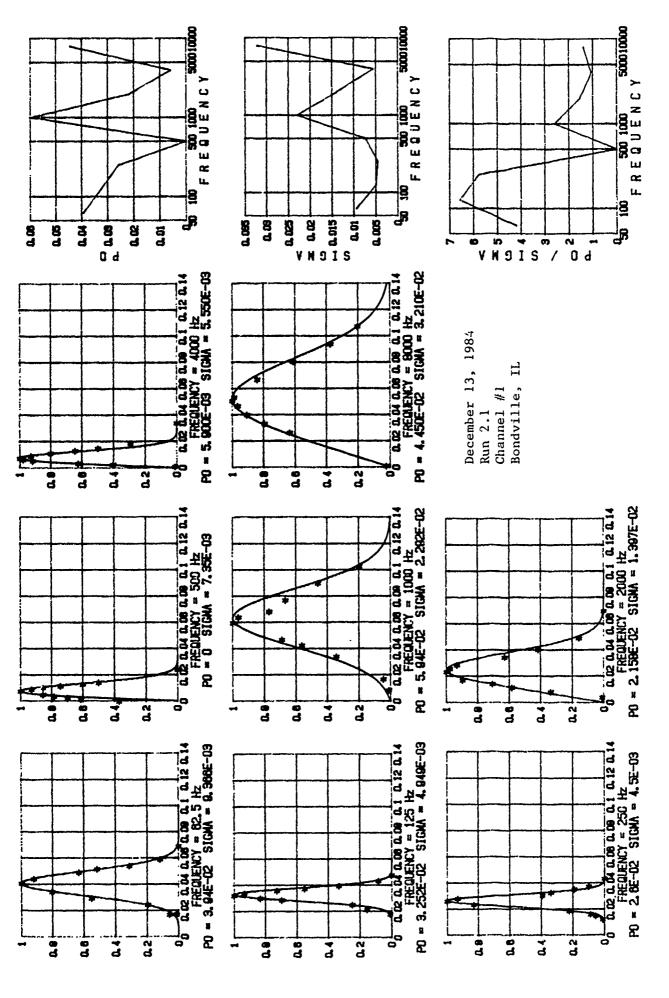
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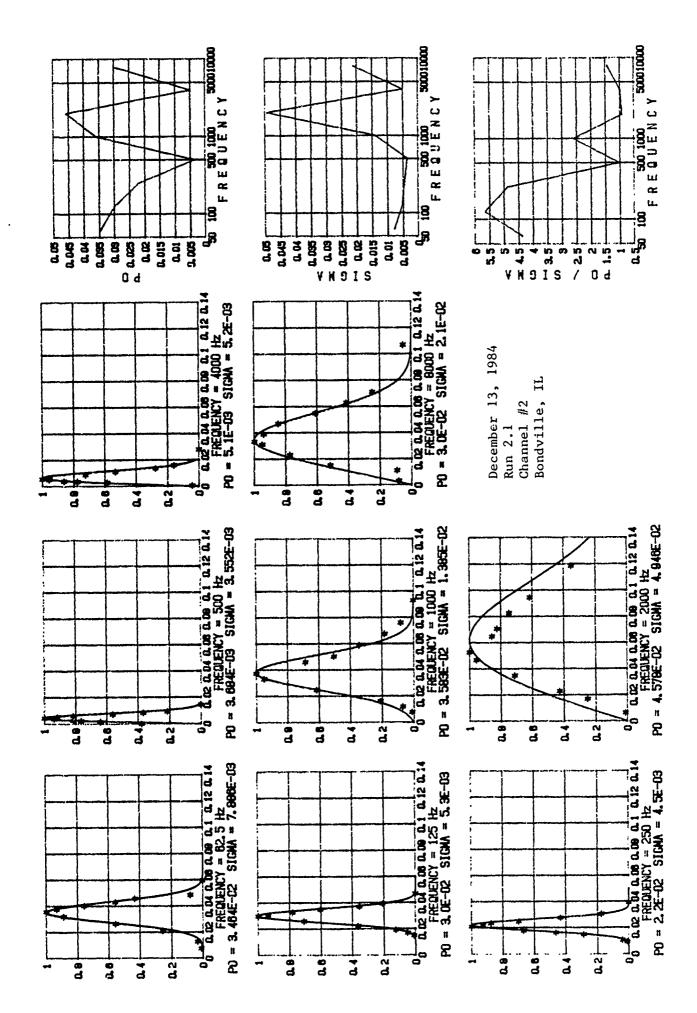
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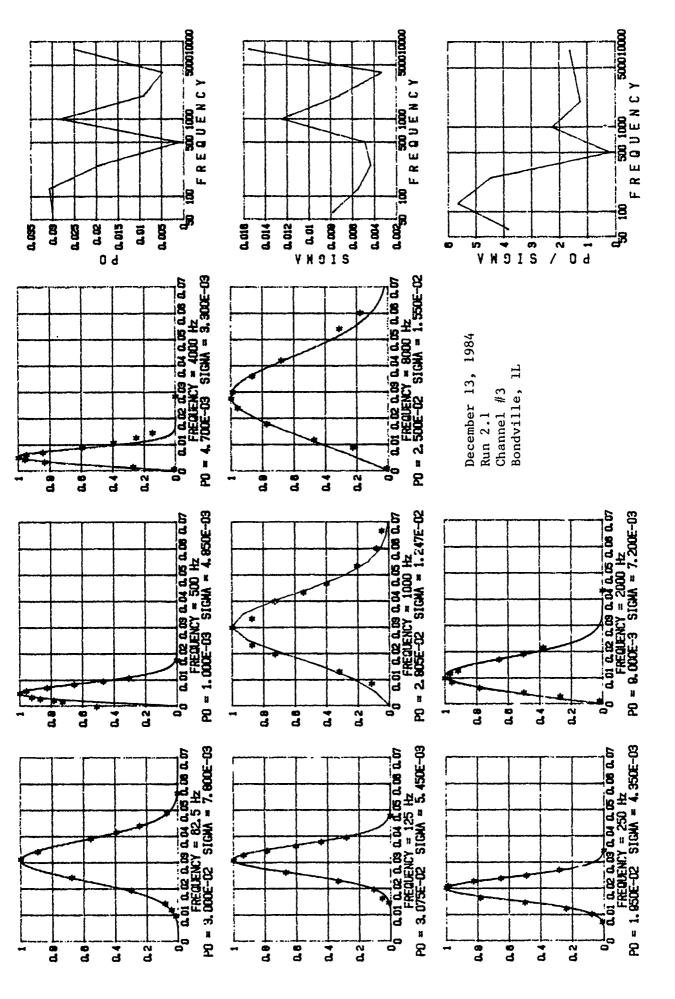
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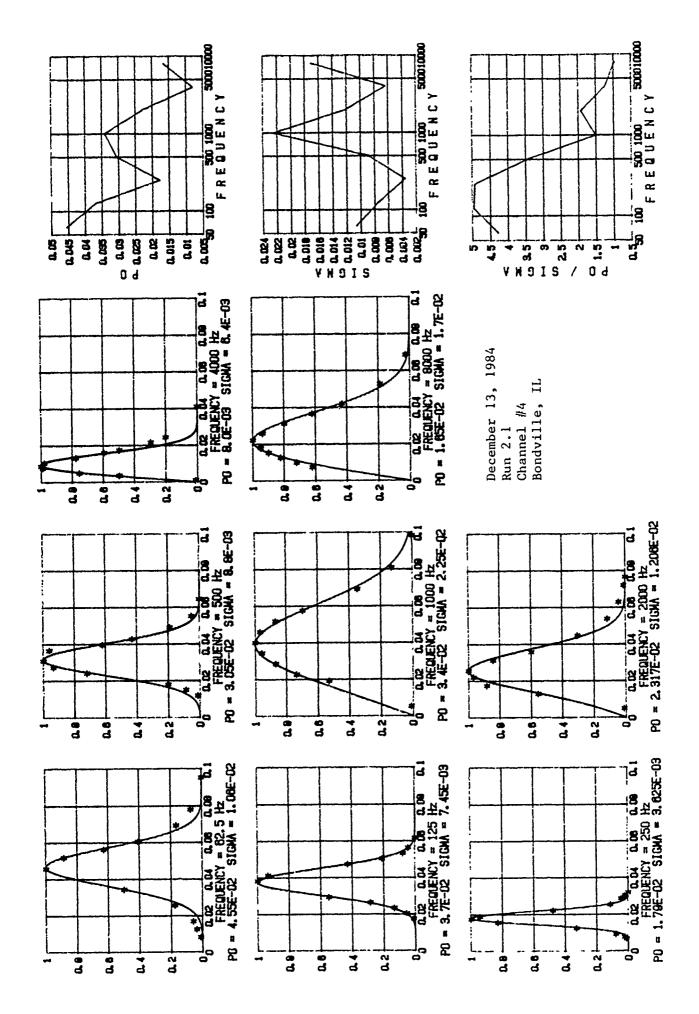
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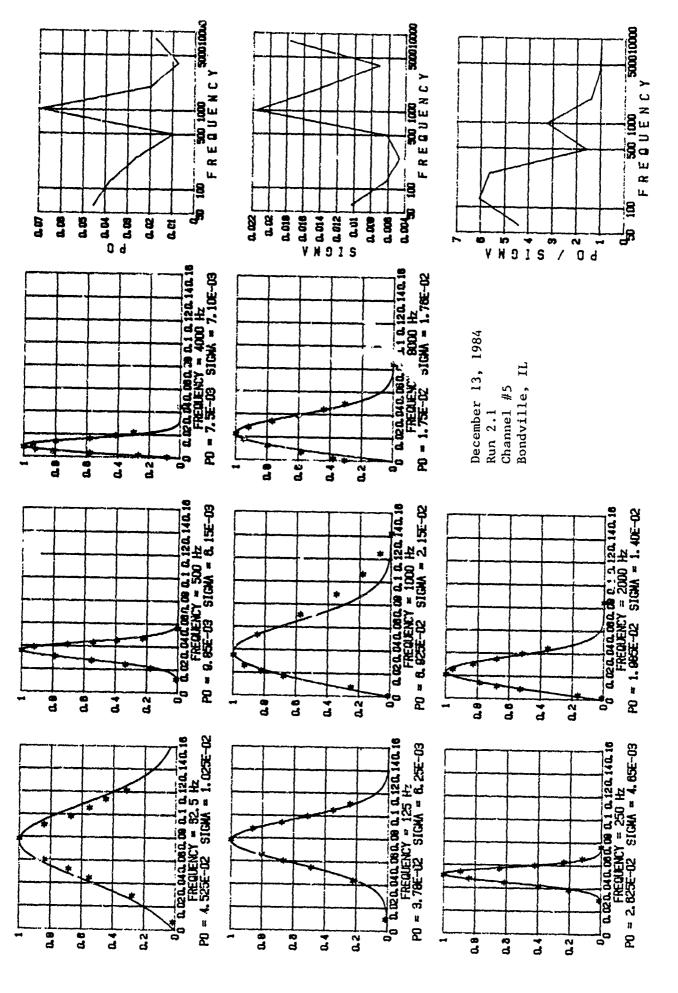
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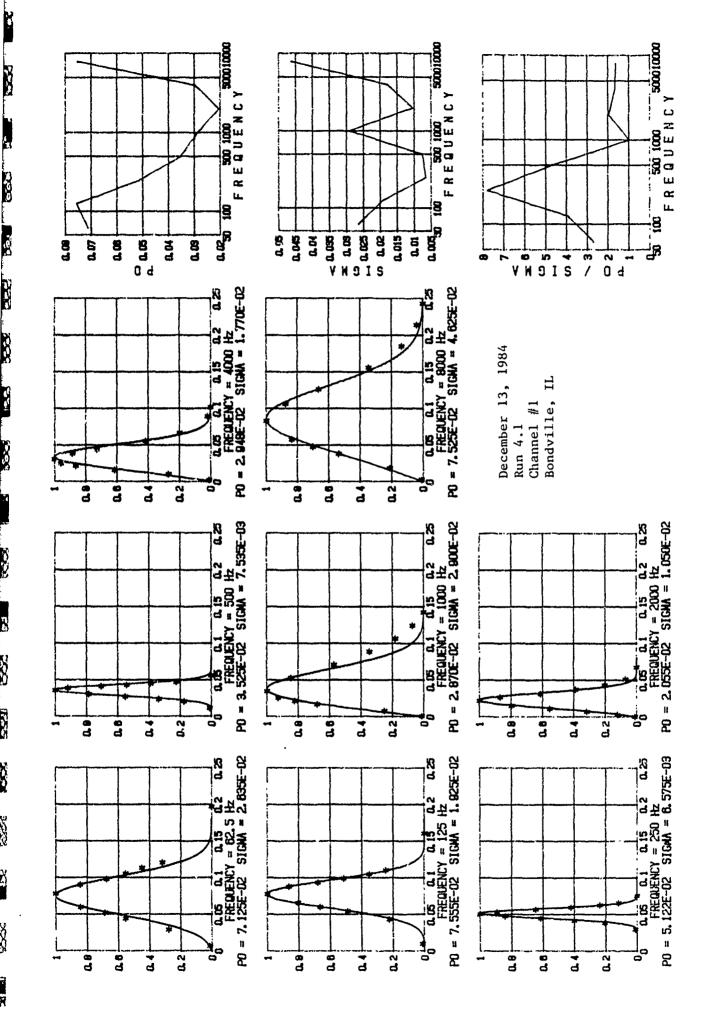
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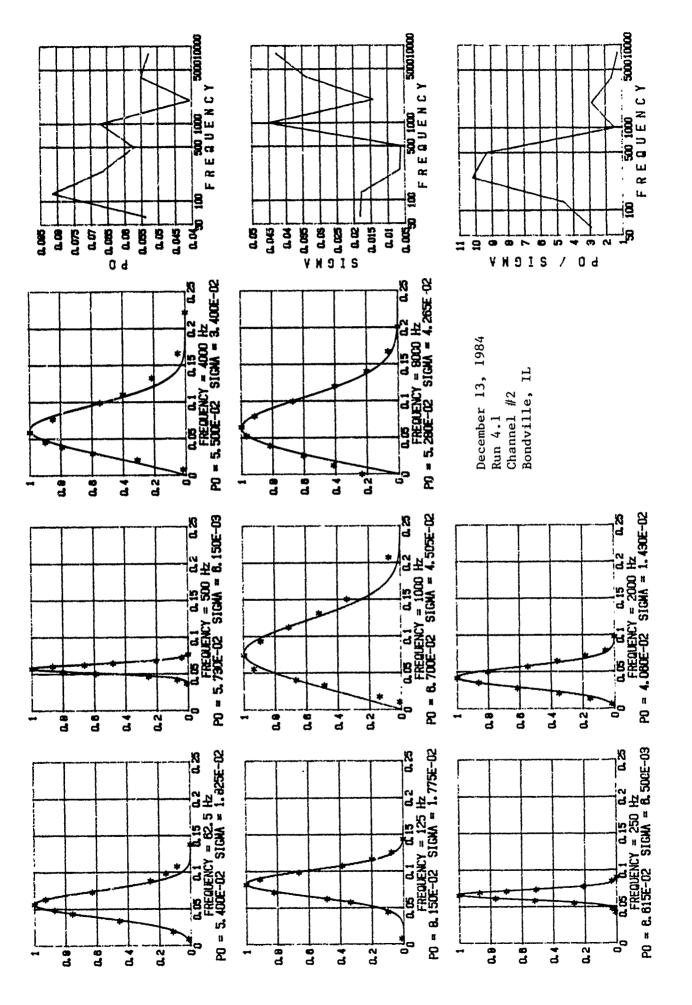
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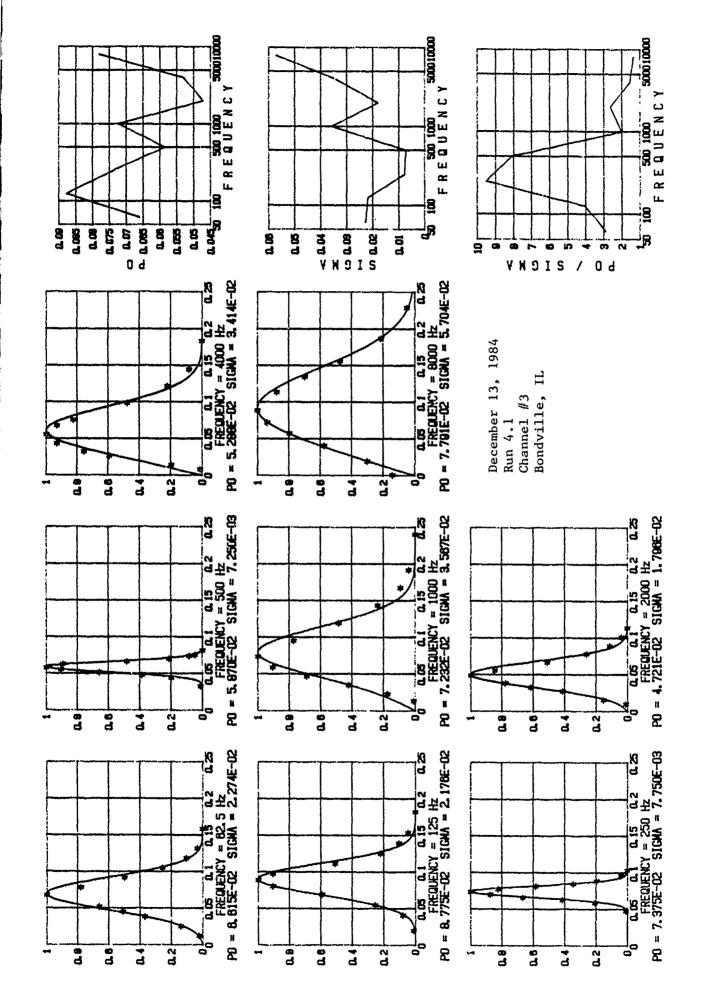


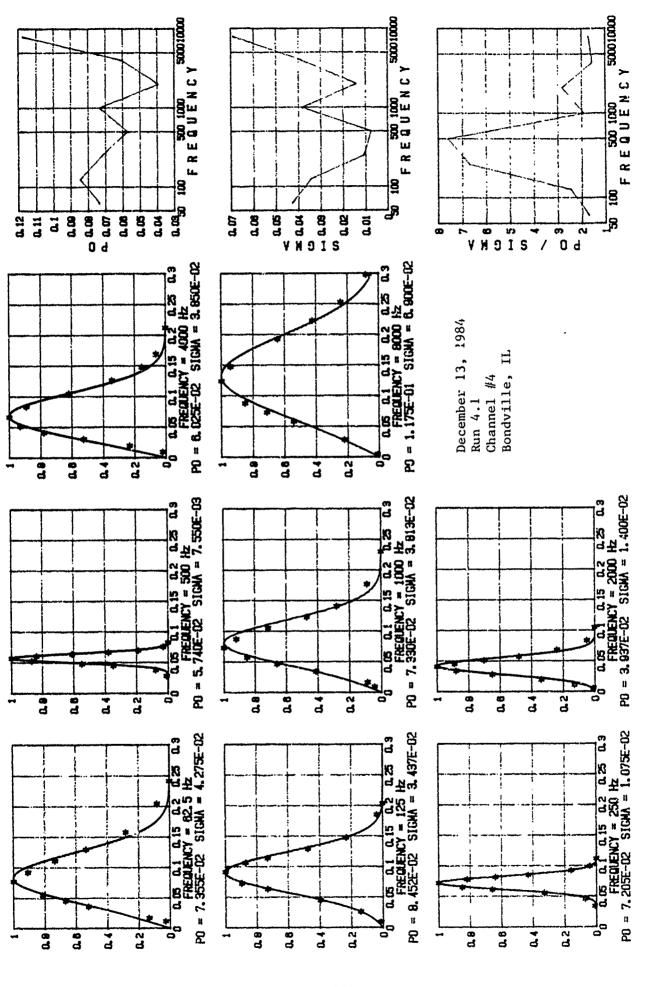
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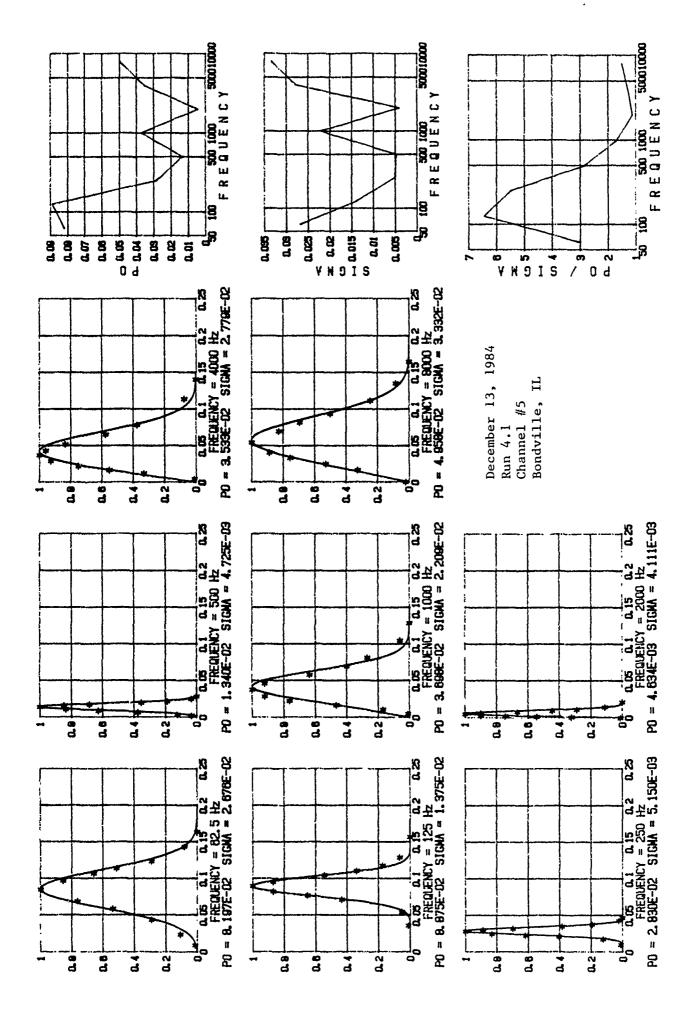
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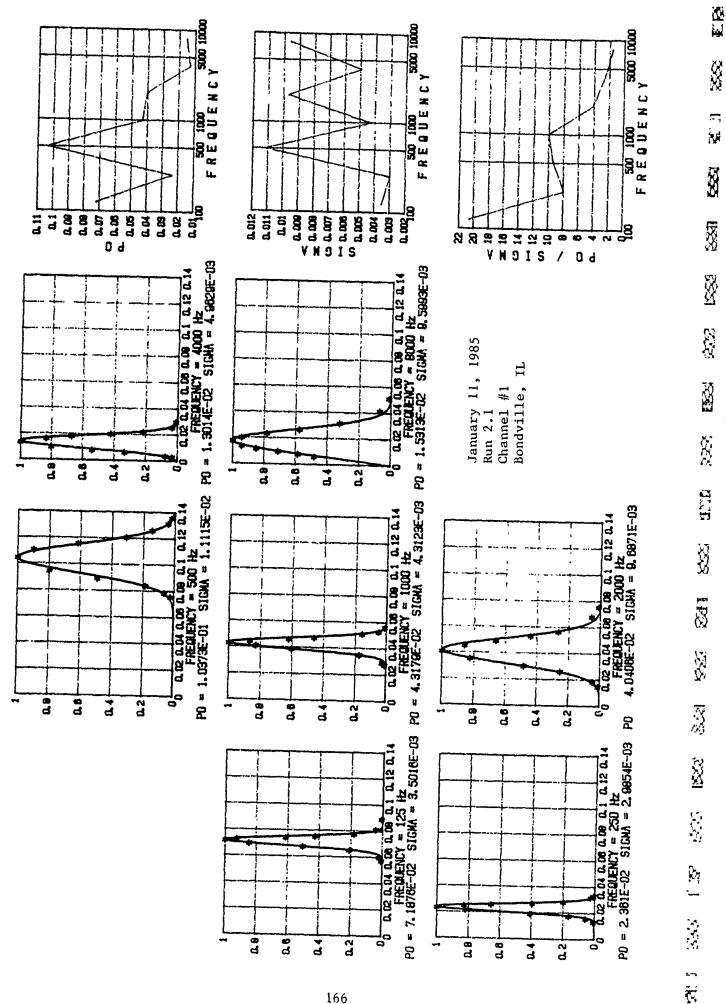
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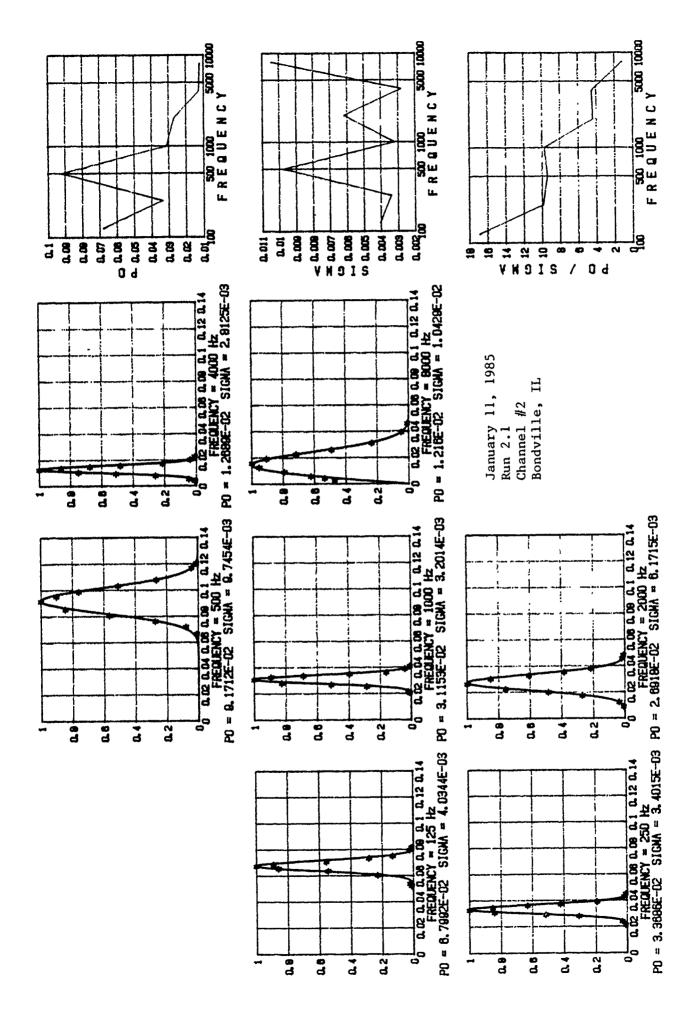
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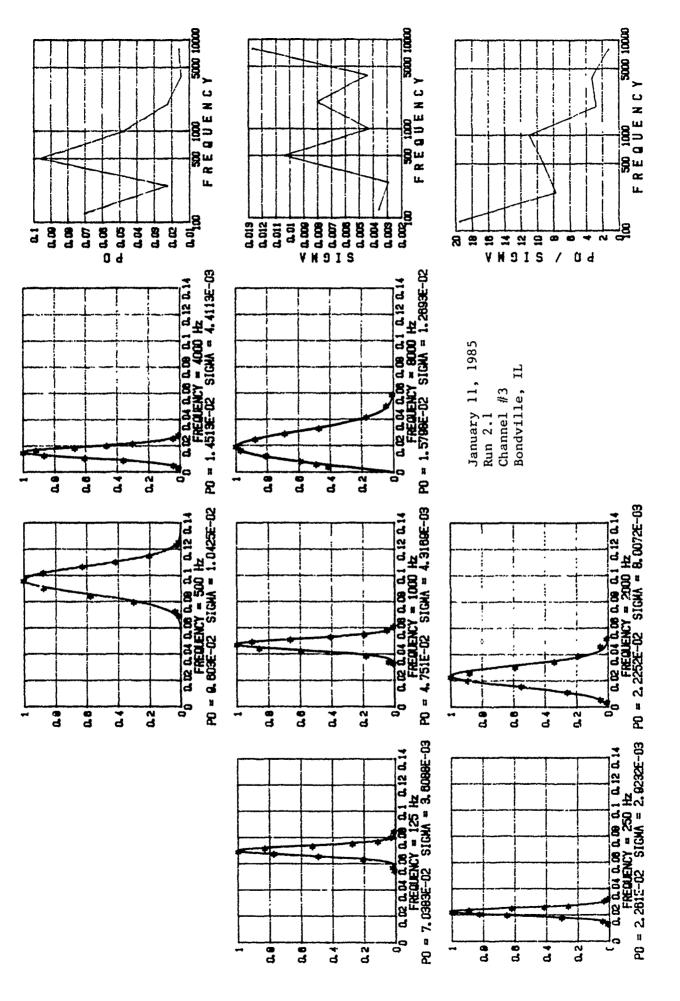
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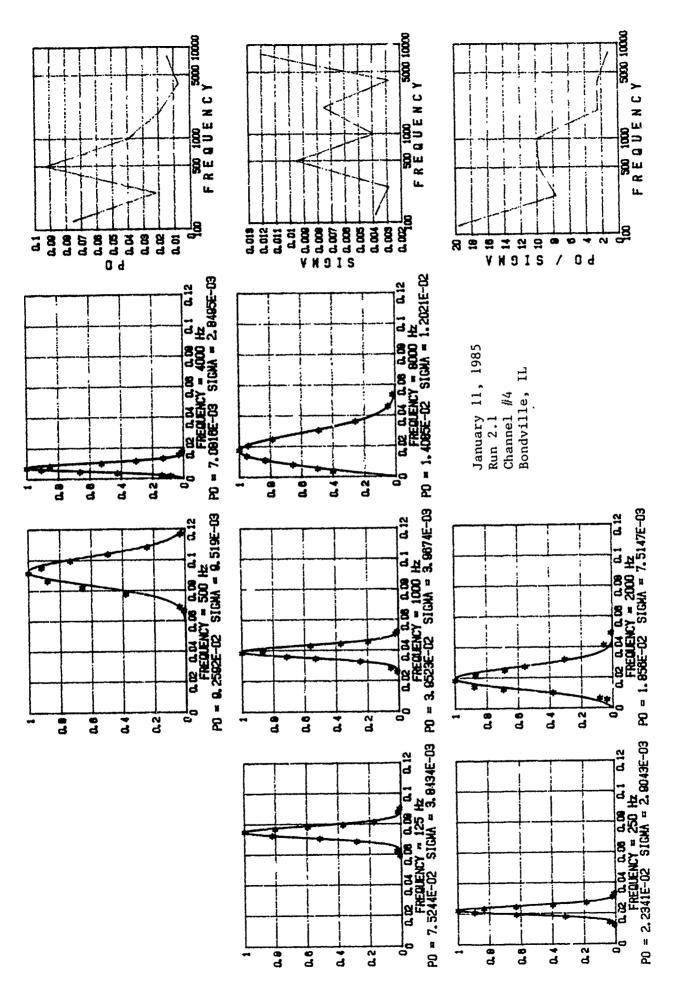
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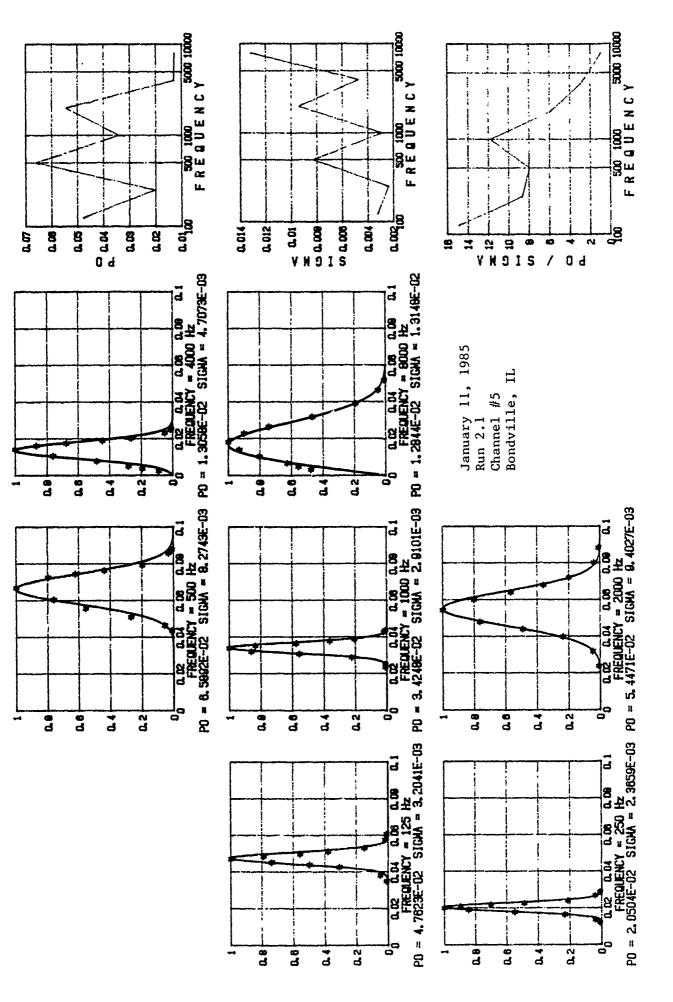
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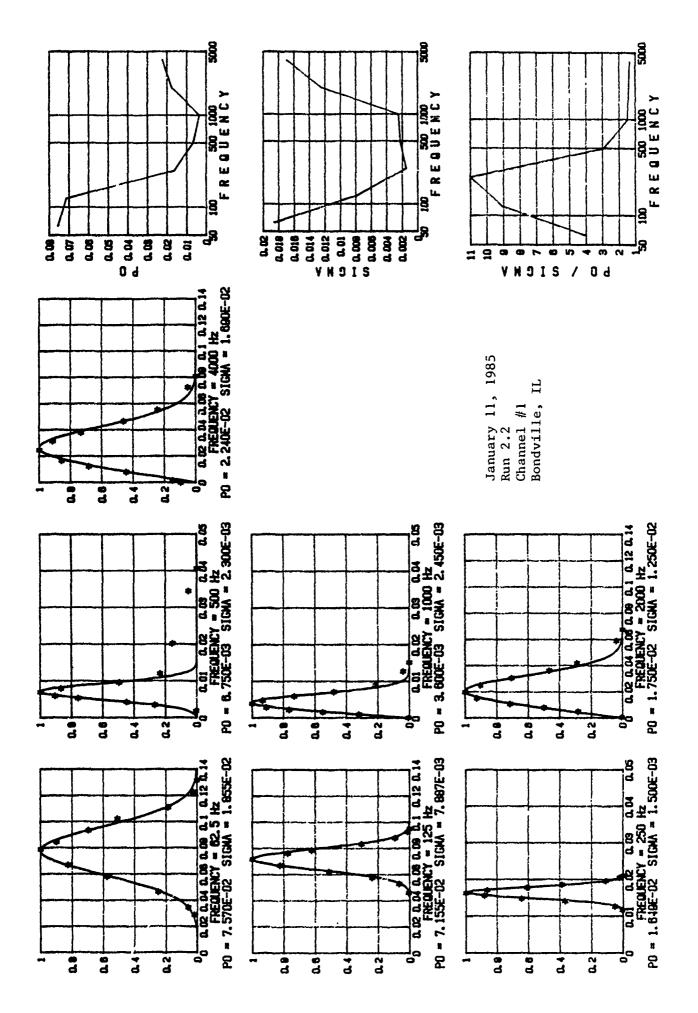
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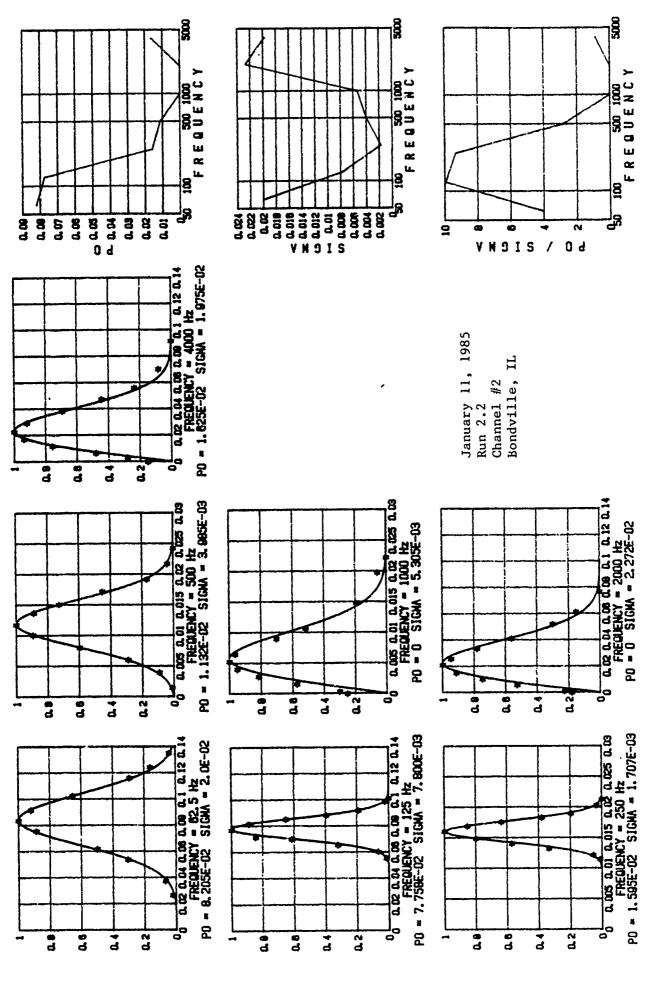
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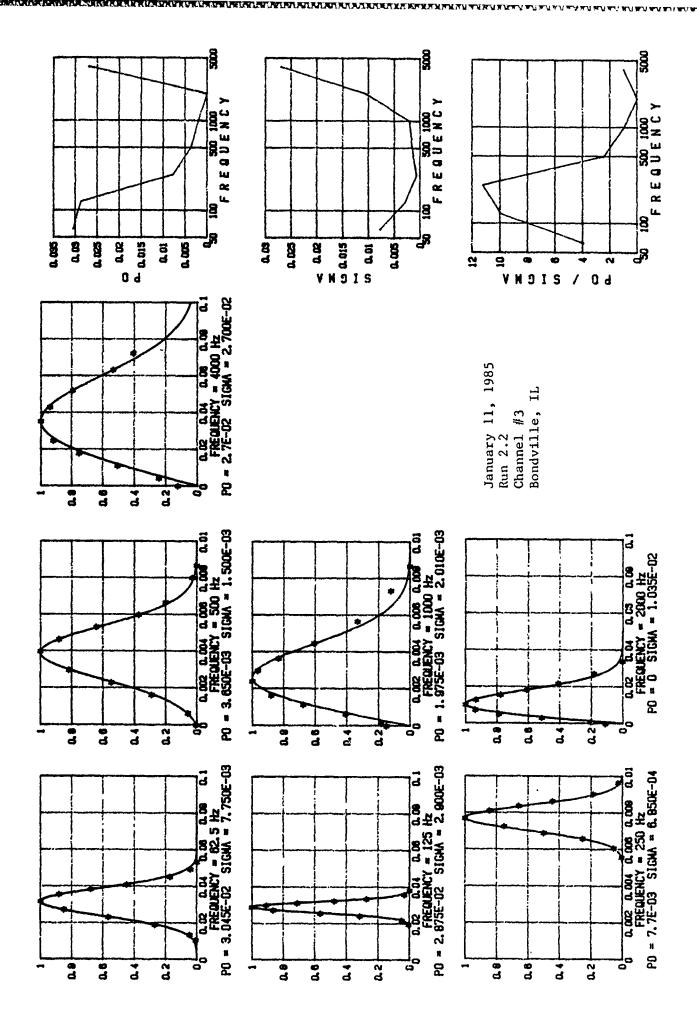
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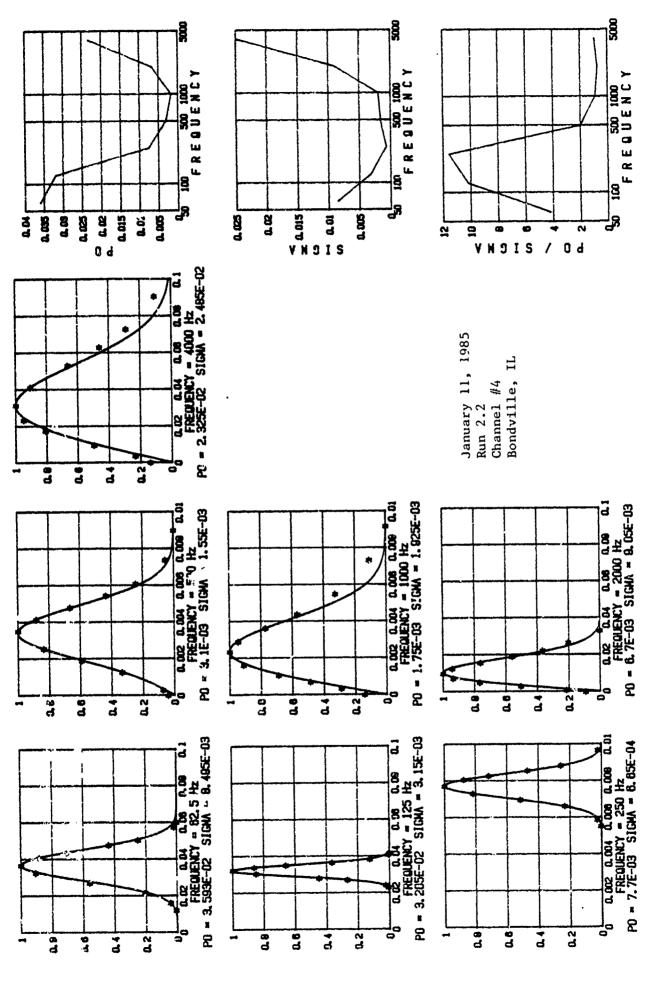
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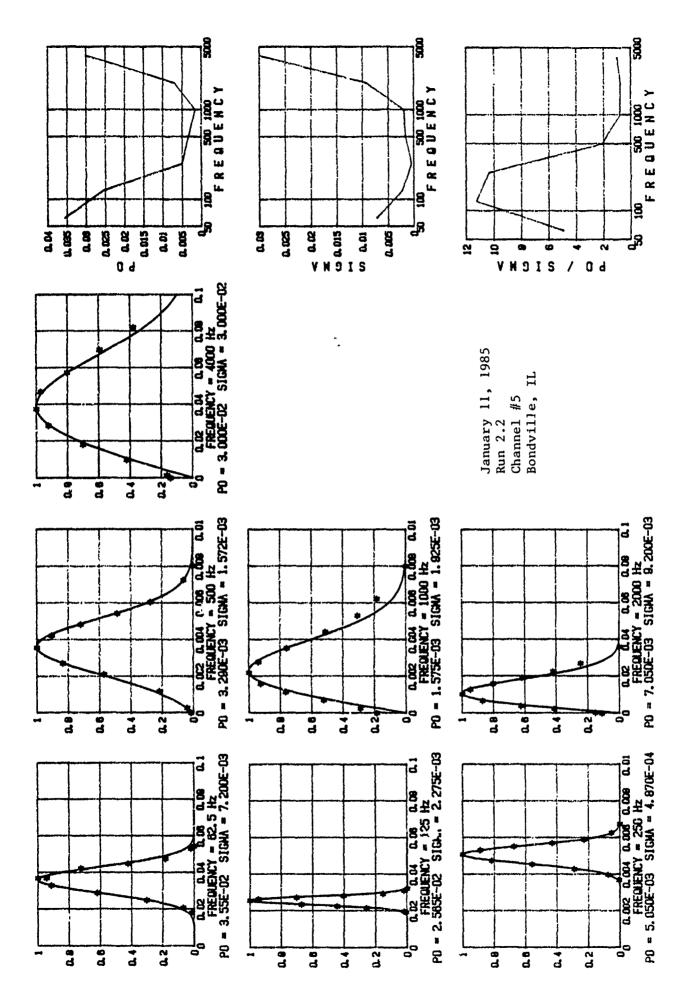
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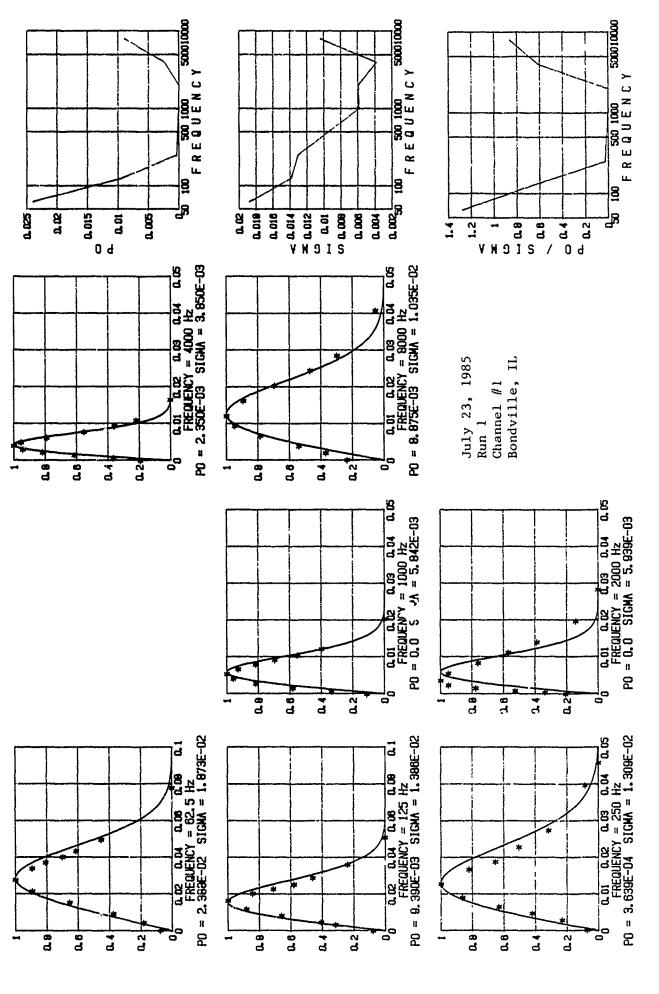
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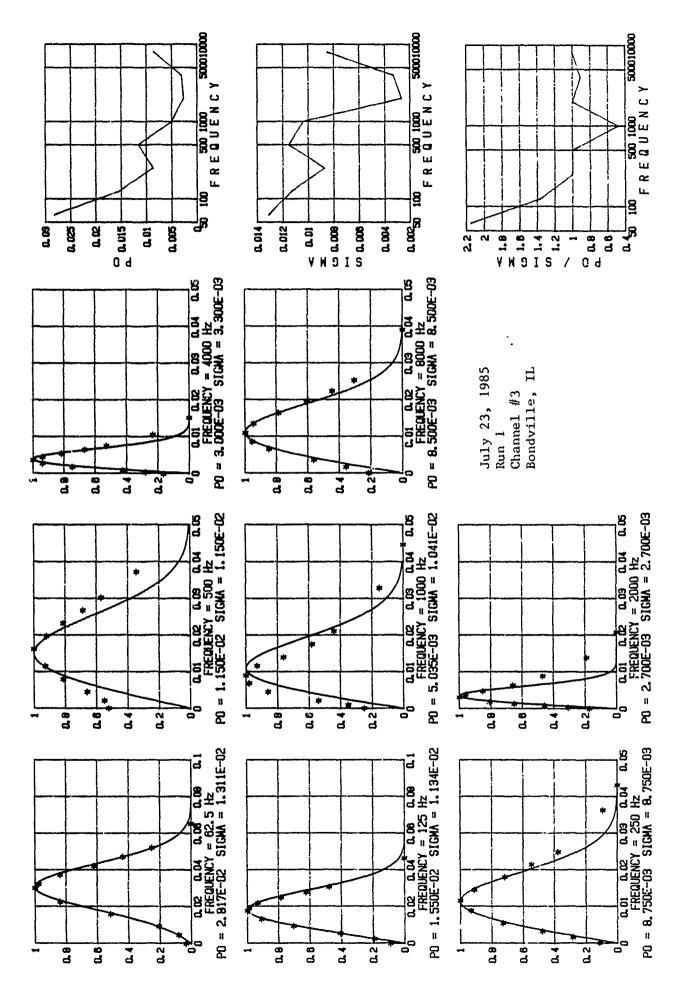
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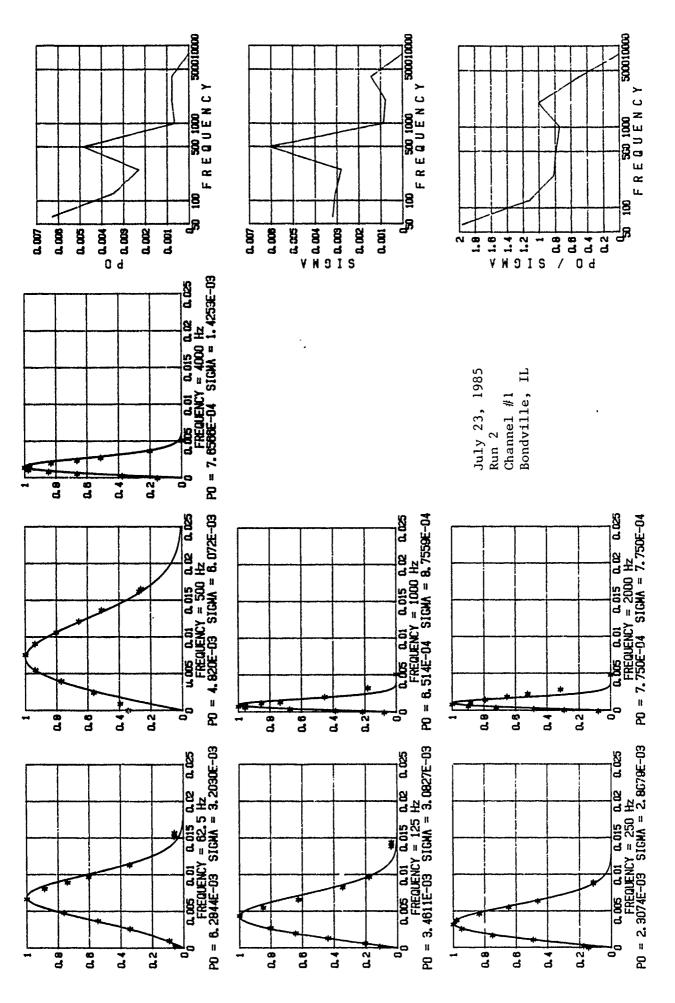
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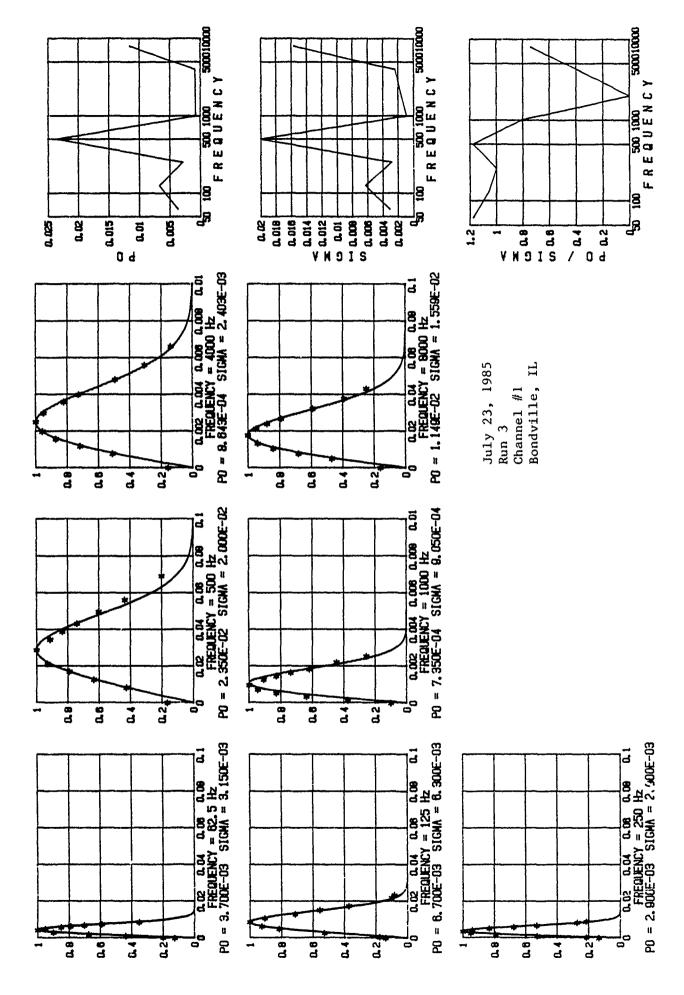
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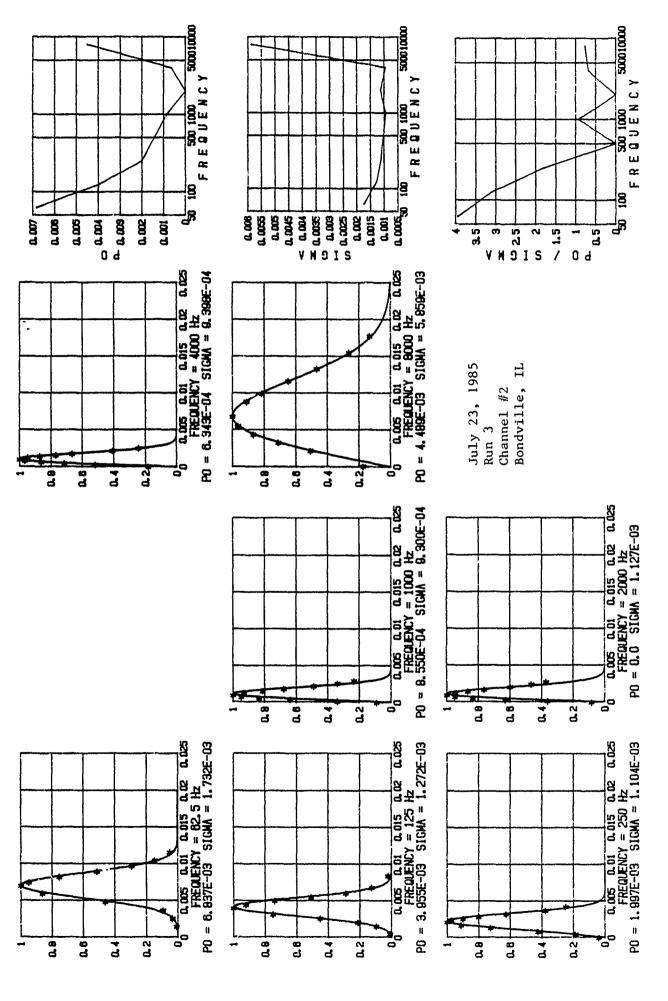
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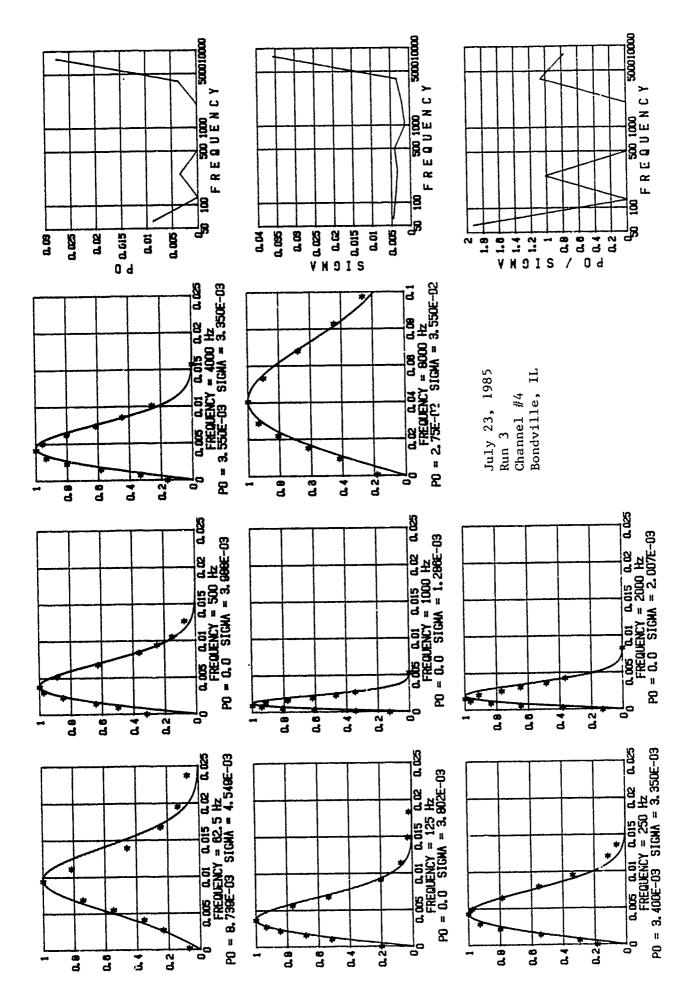
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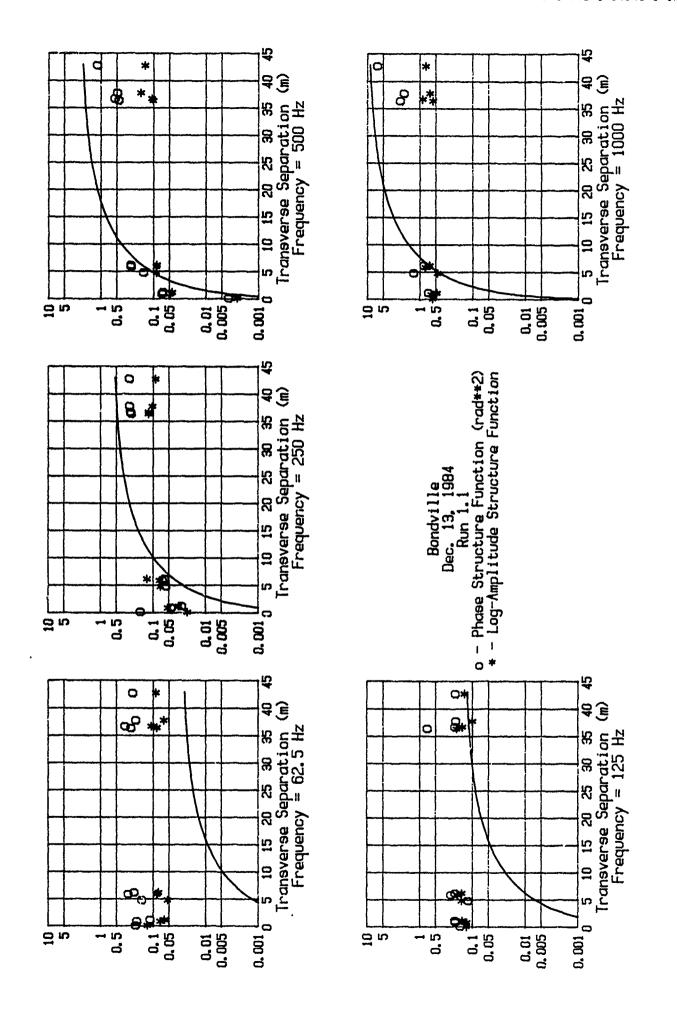
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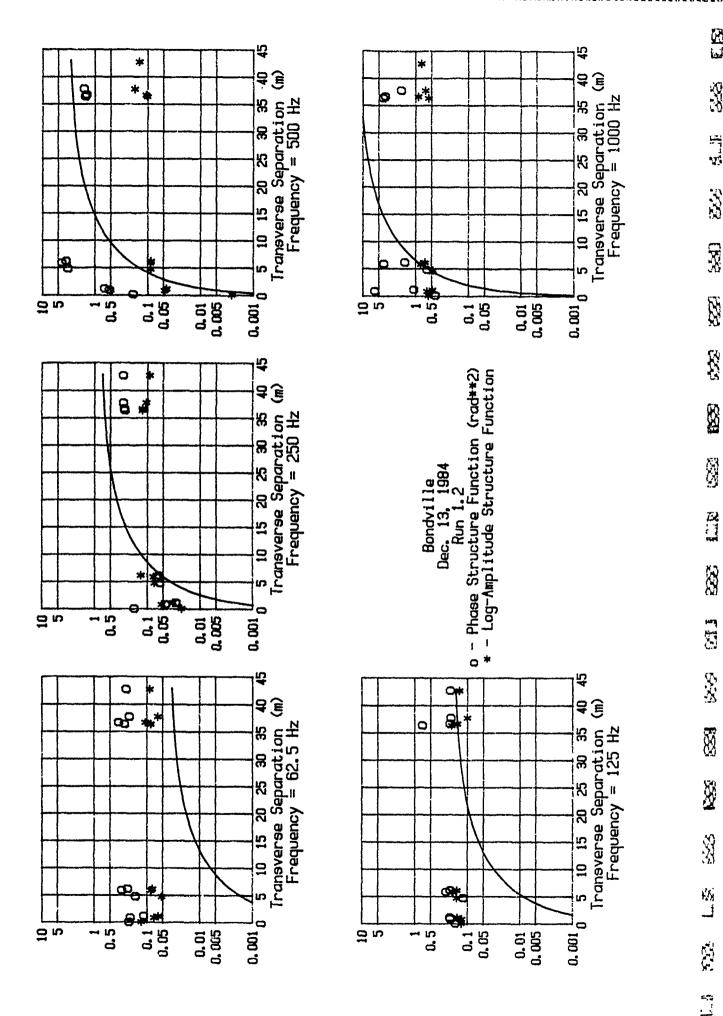


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APPENDIX F

Comparisons between the structure functions calculated from the data and Daigle's theoretical structure function.





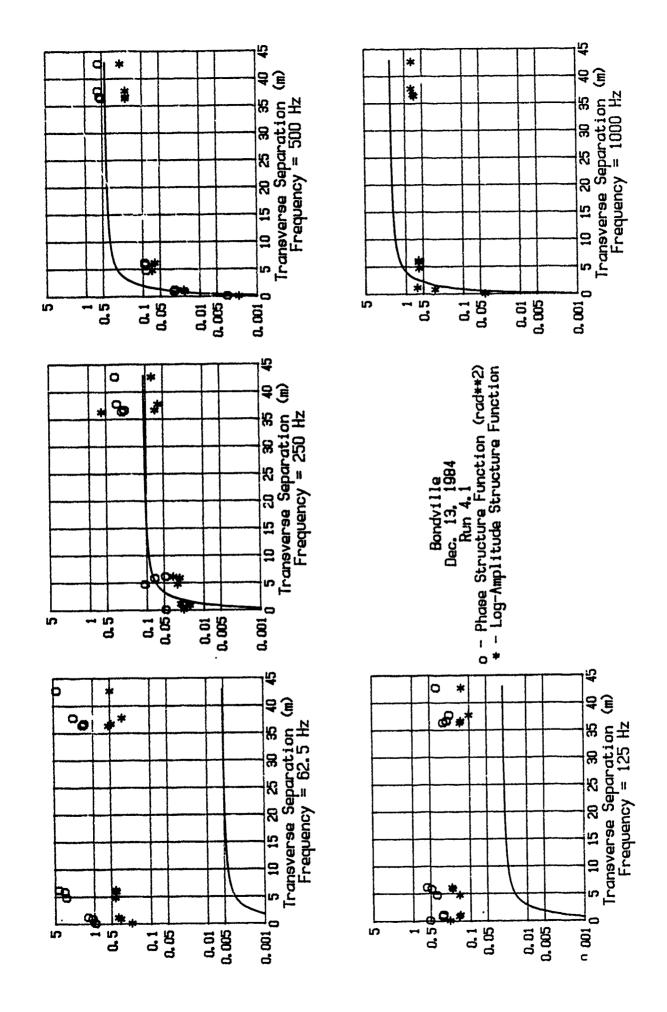
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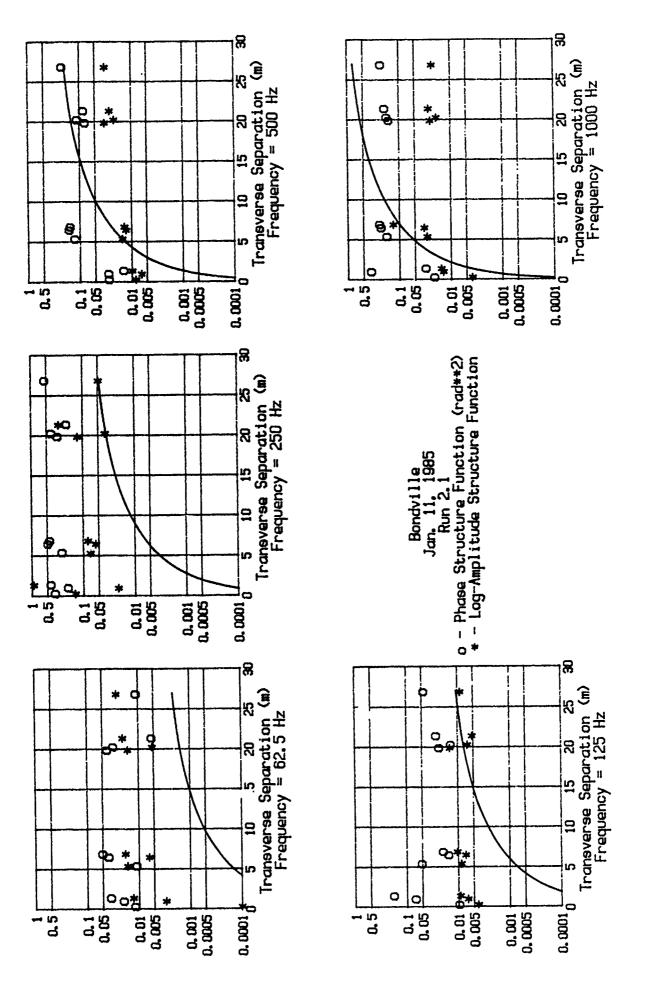
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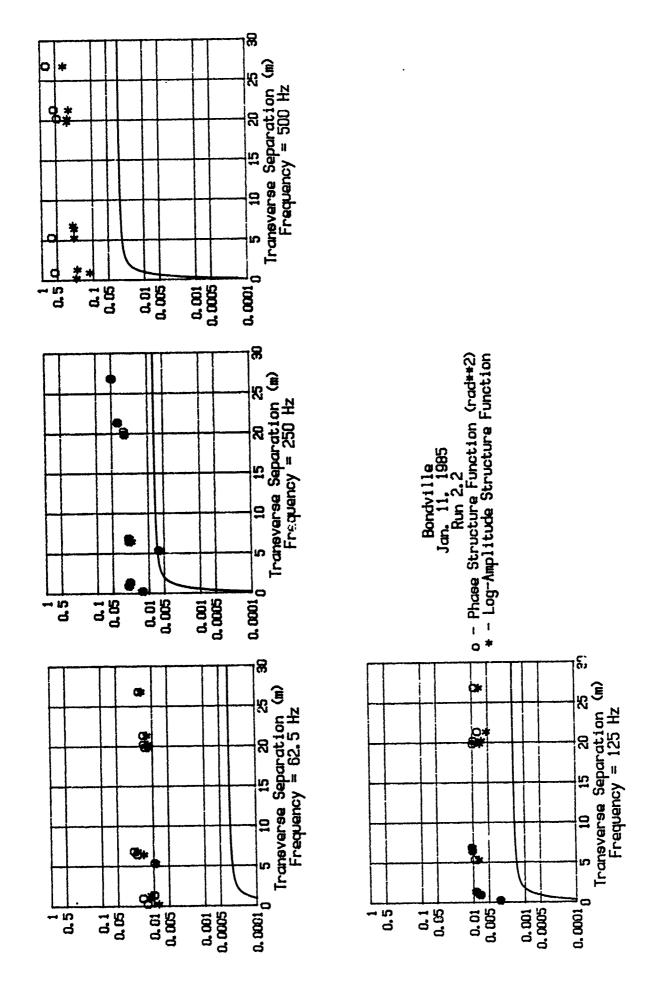
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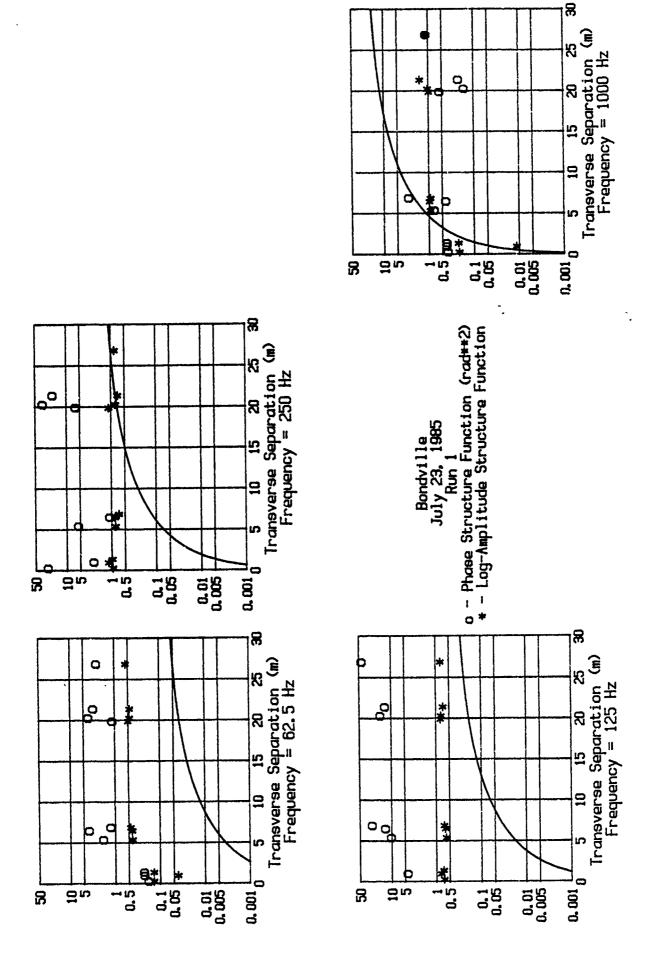
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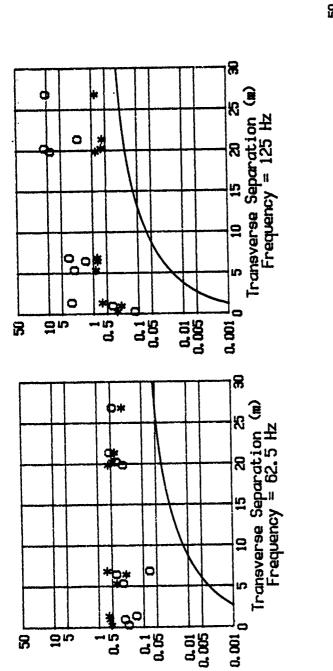
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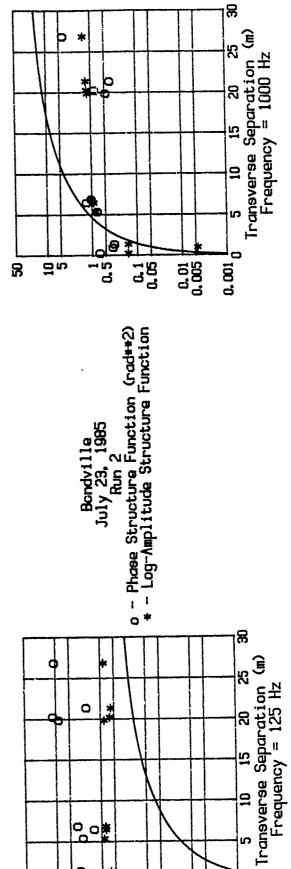
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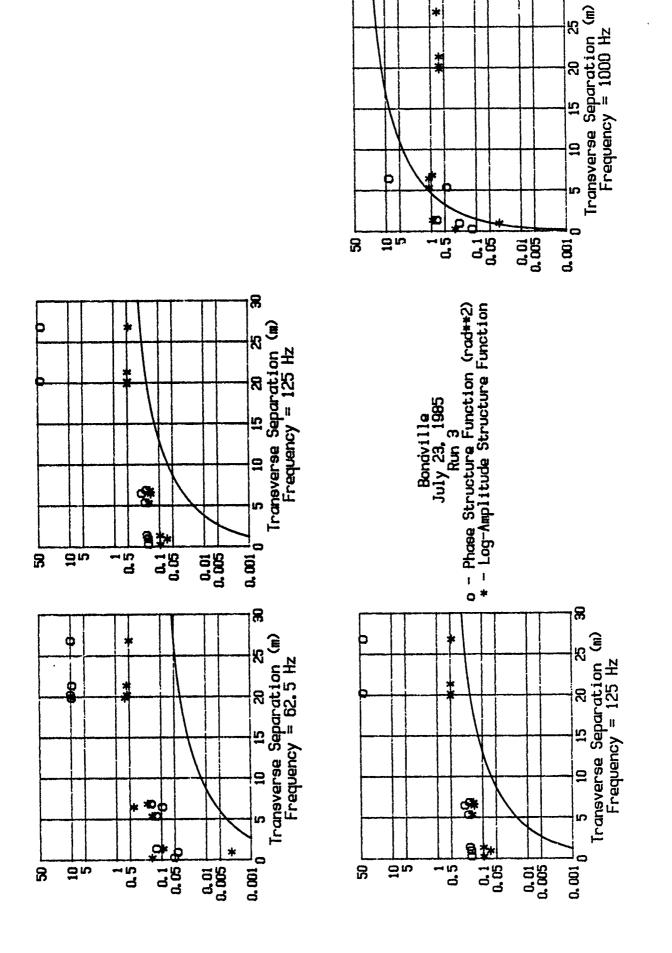
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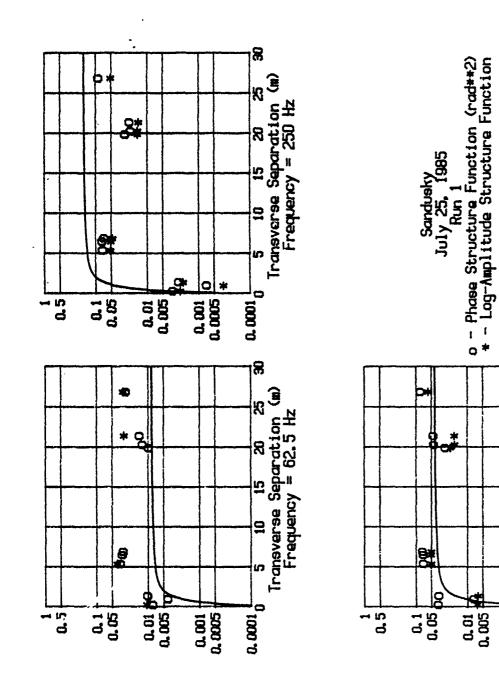
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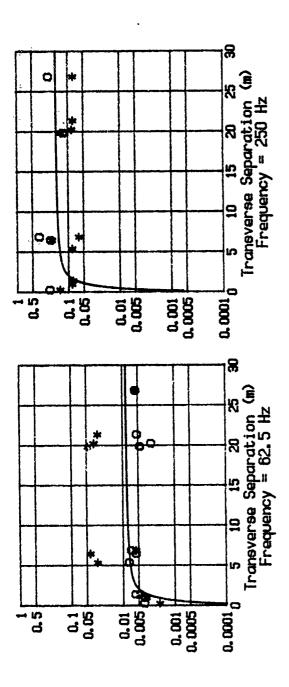
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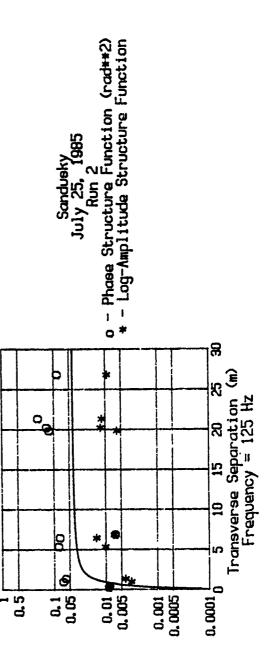


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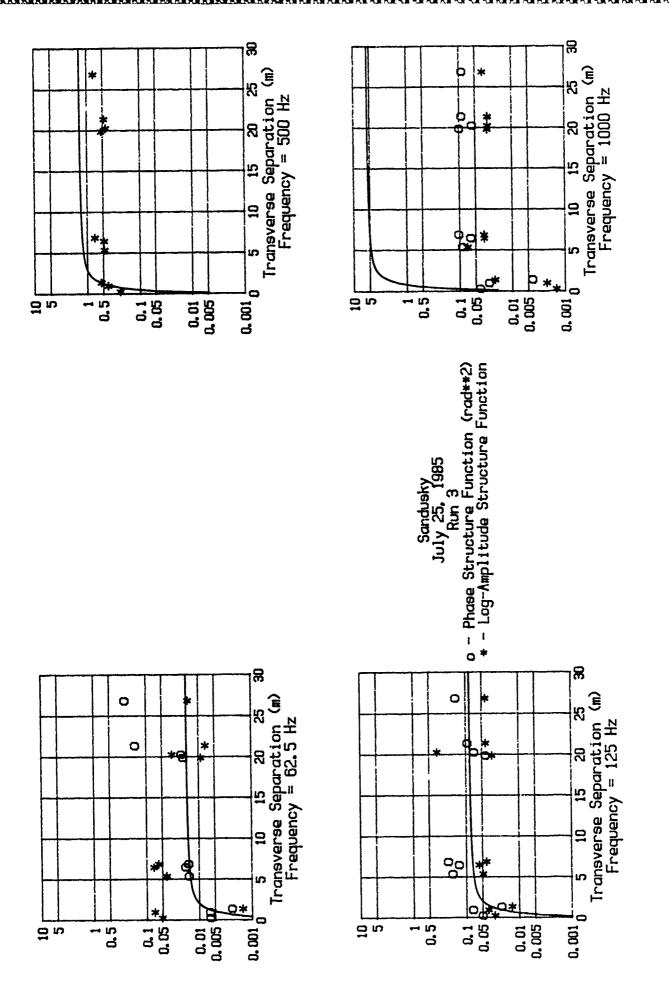
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